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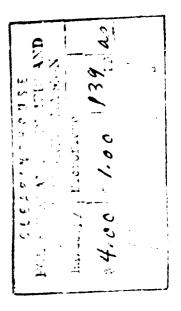
WM. B. McLEAN, Ph.D. Technical Director

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BALLISTIC HANDBOOK

by

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and
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Aviation Ordnance Department



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FOREWORD

This report is a compilation of ballistic information on freefall ordnance in a form easily used by those engaged in fire control system design, weapon design, or weapon system analysis.

The data is presented in the form of approximate solutions to the equations of motion of particle ballistics; numerical data, including ballistic tables, conversion factors, etc.; and nomographs from which many variables of interest can be quickly obtained.

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ABSTRACT

This handbook contains, in a variety of forms, ballistic information on free-fall, unguided weapons of all types, and is intended for use by those engaged in weapon design, fire control system design, and weapon system analysis. The ballistic information is presented in the form of ballistic trajectory equations, tables, graphs, and nomographs, from which many trajec ory parameters of interest can be quickly obtained with accuracy sufficient for design and analysis purposes.

ACKNOWLEDGMENT

Acknowledgment is made to Frank Breitenstein, Analysis Branch, Development Division I, for his efforts in supplying the trajectory programs and much of the numerical data presented in this report; and to Hildegard Weinhardt, Analysis Branch, Aircraft Project Division, for her efforts in providing the scale moduli and scale values for individual curves representing the variables from the given original equations, and also for her guidance and assistance in supervising contractor personnel in constructing and plotting the scales presented in this report.

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I. INTRODUCTION

The ballistic equations and numerical data presented in this hand-book are intended for use by those engaged in weapon design, fire control system design, and weapon system analysis. The first section, containing ballistic equations, defines the coordinate system, gives the nomenclature, and states the assumptions leading to the simplified equations of motion of particle ballistics. Approximate solutions to these equations of motion are then given in a variety of forms. The second section concerning numerical data contains some useful conversion factors, ballistic characteristics and drag functions of some current weapons, trajectory tables, and graphs and nomographs from which the desired information may be easily extracted.

II. BALLISTIC EQUATIONS

A. PURPOSE AND USE OF BALLISTIC SECTIONS

This section contains ballistic trajectory equations in a sufficient variety of forms that, given a particular set of independent variables, an unknown dependent variable can be computed. All of the equations, with the exception of the vacuum ballistic equations, are fairly simple approximations, and as such do not yield exact solutions. They could be further refined and expanded to yield greater accuracy over a larger range of independent variables, but only at the expense of rapidly increasing equation complexity. It is hoped a suitable balance between accuracy and complexity has been attained to accomplish the purpose for which this handbook is published.

To use the equations, the ballistic characteristics of the weapon or shape in question must be known or assumed, i.e., its reciprocal ballistic coefficient and its ballistic (or aerodynamic) drag coefficient. In some instances, it is possible to reverse the procedure to determine the approximate ballistic characteristics required of a weapon to cause it to describe a desired trajectory for a given set of release conditions.

The user is again cautioned that the solutions herein are approximate. If accurate solutions are required, numerical integration of the equations of motion on a high-speed digital computer is recommended.

B. COORDINATE SYSTEM AND NOMENCLATURE

1. Coordinate System

The coordinate system used in the ballistic section of this report is shown in Fig. 1. In this system, whose origin (0, 0, 0) is the weapon release point, Z lies along the direction of gravity, X is horizontal and lies along the direction of the initial horizontal velocity component of the weapon in the $air\ mass$, and Y is normal to the XZ plane, i.e., $Y = Z \times X$, giving a right-handed system. This XYZ system is stationary in the air mass so that if wind exists, the coordinate system is moving with respect to the ground.

It is convenient to define a coordinate system X'Y'Z' which is fixed with respect to the ground, but which initially (at weapon release) coincides with the XYZ system. This fixed system will be useful in accounting for the effects of wind on the weapon trajectory.

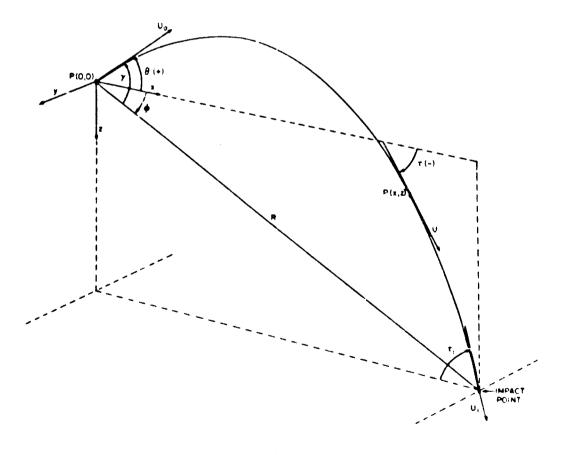


FIG. 1. Coordinate System.

2. Nomenclature

A_1, A_2, A_3	Coefficients of terms in the series solutions of the equations of motion
c _{DO}	Zero lift aerodynamic drag coefficient, a function of Mach number
c	Reciprocal ballistic coefficient equal to id^2/w
cs	Speed of sound
D	Deceleration of weapon due to aerodynamic drag
d	Haximum body diameter of weapon
\$	Acceleration of gravity; 32.174 ft/sec ²
h	Altitude above mean sea level (MSL)
i	Subscript denoting the value of a quantity at weapon impact
í	Form factor of weapon
$\kappa_{_{D}}$	Ballistic drag coefficient, a function of Mach number
K*	A modified ballistic drag coefficient
o	Subscript denoting an initial condition
p	Subscript denoting a pullup point
R	Slant range to target
t	Time
tf	Time of flight of weapon
u	Magnitude of weapon speed with respect to the air mass
v	Magnitude of weapon speed with respect to the ground
ri.	Weapon weight
w	Wind speed with respect to the ground
x , y , z	Air mass coordinate system; origin at release point. \vec{Z} is positive down, \vec{X} is horizontal, $\vec{Y} = \vec{Z} \times \vec{X}$
x' , ȳ' , <i>z̄'</i>	Coordinate system coinciding with \vec{X} , \vec{Y} , \vec{Z} system of weapon release, but fixed with respect to the ground
a _T	Angle of attack
$e_{\mathbf{T}}$	Angle of skid
Γ	Function to account for the effects of aerodynamic drag in closed trajectory equations
Y	Ballistic lead angle: angle in a vertical plane between the line of sight to the target at release and the direc- tion of the initial velocity vector

Δ	Operator indicating an incremental change in a variable, i.e., $\Delta X = dX$
θ	Release angle: angle between the velocity vector of the weapon at release and the horizontal, positive when the velocity vector is above the horizontal
o	Air density
τ	Angle between the tai, int to the trajectory at any point and the horizontal: $\tau_0 = \theta$; $\tau_1 = impact$ angle
•	Line of sight or harp angle: angle between the horizontal and the line of sight to the target at release
ψ , Φ , ψ _{τ}	Functions to account for the effects of aerodynamic drag in closed trajectory equations

C. ASSUMPTIONS

The ballistic equations of the next sections were derived using the following assumptions:

- a. The acceleration of gravity is equal to 32.174 ft/sec^2 and is constant, independent of altitude.
 - b. The earth is flat and nonrotating.
 - c. Wind is constant from release point to impact point.
 - d. The air density is that given by the ICAO Tables of 1954.
- e. The forces acting on the weapon are due only to gravity and to the motion of the weapon through the atmosphere.

The aerodynamic forces are further assumed to act only along the longitudinal axis of the weapon with a magnitude given by:

$$F = \frac{1}{2} \rho u^2 S C_{Do}$$
 (1)

In eq. 1, C_{Do} is the aerodynamic drag coefficient at zero lift or zero angle of attack, and S is a reference area, usually the maximum body cross-section area. The deceleration of the weapon is

$$D = \frac{1}{2} \rho \frac{u^2 S}{W} C_D$$
 (2)

where W is the weight of the weapon, and the units of p have changed from mass per volume in eq. 1 to weight per volume in eq. 2 to account for the "missing" gravity term.

If
$$S = \frac{\pi d^2}{4}$$
;
then $D = \frac{\pi}{8} \rho u^2 \frac{d^2}{W} C_D$. (3)

In ballistic work, the weapon deceleration due to drag is normally written

$$D = \rho c u^2 K_D \tag{4}$$

where c, the reciprocal ballistic coefficient, is defined by:

$$c = i \frac{d^2}{w} \tag{5}$$

and K_D is the ballistic drag coefficient. From eq. 3, 4, and 5, it is evident that, for i=1,

$$K_{D} = \frac{\pi}{8} C_{D} = 0.3927 C_{D}$$

$$C_{D} = 2.546 K_{D} . \qquad (6)$$

or

In eq. 5, i is called the form factor, and is introduced as a correction term relating the ballistic drag coefficient of some standard projectile to that of a projectile of usually similar shape. Thus, if $K_{\rm D}$ is the drag function of a standard projectile, the form factor i is given by

$$i = \frac{K_D}{K_{Ds}}$$

and is a sort of average correction term applied to the drag coefficient of the standard projectile to obtain a drag function suitable for the weapon at hand.

D. EQUATIONS OF MOTION, DIFFERENTIAL RELATIONSHIPS, AND WIND EFFECTS

1. Normal Equations of Motion

In terms of the air mass coordinate system defined, the assumptions stated in the previous section lead to the following differential equations of motion for particle ballistics:

$$\frac{d^2X}{dt^2} = -D \cos r , \qquad \frac{d^2Z}{dt^2} = D \sin r + g ,$$

$$\frac{dX}{dt} = u \cos \tau, \qquad \frac{dZ}{dt} = -u \sin \tau, \qquad (7)$$

where

$$D = \rho c K_D u^2 .$$

The ballistic equations of the next sections were obtained from Taylor series solutions of eq. 7 of the general form

$$\frac{1}{n!} \int_{0}^{\eta} (\eta - \varepsilon)^{n} \frac{ds^{(n+1)}}{ds^{(n+1)}} d\varepsilon . \qquad (8)$$

where the subscript o indicates that the derivatives are evaluated at the release point of the weapon, i.e., at X = Y = Z = t = 0.

2. Differential Relationships

Table 1 is a compilation of some useful first derivatives from which the higher order derivatives can be obtained.

X Z 7 t d+ X 1 - tan r u cos T $D + g \sin \tau$ g cot T <u>-1</u> Z 1 - cot 7 u sin T u sin r - u cos r u sin 7 $\frac{1}{u} \left(\frac{g \cos \tau}{D + g \sin \tau} \right)$ + g sin r 1 D + g sin τ $D + g \sin r$ u² tan r 1 g cos r g cos T u cos 7 -u sin T $-(D + g \sin r)$ 1

TABLE 1. Differential Relationships

$$D = \rho cK_{D}(M) u^{2}, \qquad \frac{d^{2}X}{dt^{2}} = -D \cos r, \qquad \frac{dX}{dt} = u \cos r,$$

$$\frac{d^{2}Z}{dt^{2}} = D \sin r + g, \frac{dZ}{dt} = -u \sin r.$$

3. Wind Correction

With the normal equations of particle ballistics solved in an airmass coordinate system, the motion of the air mass must be accounted for if the variables of the trajectory need to be described in terms of a fixed coordinate system, e.g., the X'Y'Z' system defined in Section B.1.

If wind is restricted to be horizontal and constant, the relations between the trajectory parameters in the X'Y'Z' and the XYZ systems are:

$$t_f' = t_f$$
 (no vertical wind) , (9)

$$x^* = x + w_x t_f, \qquad (10)$$

$$Y' = W_y t_f , \qquad (11)$$

$$v_i = (u_i^2 + w^2 + 2Wu_i \cos \tau_i)^{\frac{1}{2}},$$
 (12)

$$\sin \tau_i^{\ i} = \frac{u_i}{v_i} \sin \tau_i \ . \tag{13}$$

In the above equations, W_X and W_V are the X and Y components of wind, respectively, and thus

$$V_{x} = U_{x} + W_{x}$$
,
 $V_{y} = W_{y}$,
and $V_{z} = U_{z}$. (14)
Also, $V_{i} = (V_{x}^{2} + V_{y}^{2} + V_{z}^{2})^{\frac{1}{2}}$,
 $U_{i} = (U_{x}^{2} + U_{z}^{2})^{\frac{1}{2}}$,
 $W_{z} = (W_{x}^{2} + W_{y}^{2})^{\frac{1}{2}}$. (15)

SOLUTIONS TO EQUATIONS OF MOTION

Vacuum Case, D = 0

$$X = \frac{U_0^2 \cos \theta}{E} \left[\sin \theta + \sqrt{\sin^2 \theta} + \frac{2Z_E}{U_0^2} \right]. \qquad (16)$$

$$t = \frac{U_0}{E} \left[\sin \theta + \sqrt{\sin^2 \theta} + \frac{2Z_E}{U_0^2} \right]. \qquad (17)$$

$$tan \tau = -\sec \theta \sqrt{\sin^2 \theta} + \frac{2Z_E}{U_0^2}. \qquad (18)$$

$$t = \frac{U_0}{g} \left[\sin \theta + \sqrt{\sin^2 \theta + \frac{2Zg}{U_0^2}} \right]. \tag{17}$$

$$\tan \tau = -\sec \theta \sqrt{\sin^2 \theta + \frac{27g}{U_0^2}} . \tag{18}$$

$$u = \sqrt{u_0^2 + 2zg} = u_0 \sqrt{1 + \frac{2zg}{u_0^2}}.$$
 (19)

b. Variable t

$$X = U_0 t \cos \theta . (20)$$

$$Z = -U_0 t \sin \theta + \frac{ct^2}{2} . \qquad (21)$$

$$\tan \tau = -\tan \theta + \frac{gt}{U_0 \cos \theta} . \tag{22}$$

$$U = \sqrt{U_0^2 + gt \left(gt - 2U_0 \sin \theta\right)} . \tag{23}$$

c. Variable X

$$Z = -\tan\theta + \frac{gX^2}{2U_0^2\cos^2\theta} . \qquad (24)$$

$$t = \frac{X}{U_0 \cos \theta} . \tag{25}$$

$$\tan \tau = -\tan \theta + \frac{gX}{U_0^2 \cos^2 \theta} . \qquad (26)$$

$$U = \sqrt{U_0^2 + \frac{gX}{U_0 \cos \theta} \left(\frac{gX}{U_0 \cos \theta} - 2U_0 \sin \theta \right)} . \quad (27)$$

2. Series Solutions

a. Coefficients of Series Solutions

The series solutions in the next sections are written in terms of coefficients A_1 , A_2 , and A_3 . These coefficients, given below, were evaluated assuming that (1) the drag coefficient KD remains at its value at release, and (2) air density at altitude h above MSL is given by 1

$$\rho = \rho_0 e^{-\alpha h} \tag{28}$$

where, for h in feet, $\alpha = 3.015 \times 10^{-5} \text{ ft}^{-1}$, and ρ_0 is air density at sea level.

With $D_0 = \rho c K_D U_0^2$, the coefficients are as follows:

$$A_1 = \frac{4 D_O}{U_O^2 \cos \theta} , \qquad (29)$$

This is not in accordance with ICAO standards, but it allows an analytical expression for the density in the series coefficients. This expression gives values very close to the ICAO that was used in computation of the tables.

$$A_2 = \frac{4 D_0}{U_0^4 \cos^2 \theta} \left[2 D_0 - (g + \alpha U_0^2) \sin \theta \right] , \quad (30)$$

and

$$A_3 = \frac{4 D_0}{U_0^6 \cos^2 \theta} \left[4 D_0^2 + g (g + \alpha U_0^2) \cos^2 \theta - 2 D (4g + 3 \alpha U_0^2) \sin \theta + 2\alpha_0^2 (3g + 2\alpha_0^2) \sin^2 \theta \right]. (31)$$

Alternate expressions for these coefficients are:

$$A_{3} = 4 \rho c K_{D} \sec \theta , \qquad (32)$$

$$A_2 = \frac{A_1^2}{2} - A_1 (g/U_0^2 + a) \tan \theta$$
, (33)

$$A_{3} = \frac{A_{1}^{3}}{4} - \frac{A_{1}^{2}}{2} \left(\frac{4g}{U_{0}^{2}} + 3a \right) \tan \theta + A_{1} \left[\frac{g}{U_{0}^{2}} \left(\frac{g}{U_{0}^{2}} + a \right) + a \left(\frac{3g}{U_{0}^{2}} + a \right) \tan^{2} \theta \right]. (34)$$

b. Independent Variable X, Horizontal Range

$$Z = -X \tan \theta + \frac{gX^2}{2U_0^2 \cos^2 \theta} \left(1 + \frac{A_1X}{3!} + \frac{A_2X^2}{4!} + \frac{A_3X^3}{5!} + \ldots \right). \quad (35)$$

$$t = \frac{X}{U_0 \cos \theta} \left[1 + \frac{2 A_1 X}{(2)(8)} + \frac{1}{(3)(8)} \left(A_2 - \frac{A_1^2}{4} \right) X^2 + \right]$$

$$\frac{1}{(4)(8)} \left(\frac{A_3}{3} - \frac{A_1 A_2}{4} + \frac{A_1^3}{16} \right) \quad \chi^3 + \ldots \right] . \tag{36}$$

$$\tan \tau = \tan \theta - \frac{gX}{U_0^2 \cos^2 \theta} \left(1 + \frac{A_1}{2} \frac{X}{2!} + \frac{A_2}{2} \frac{X^2}{3!} + \frac{A_3}{2} \frac{X^3}{4!} + \ldots \right) (37)$$

$$U \cos \tau = U_0 \cos \theta \left[1 - \frac{2A_1 X}{8} - \frac{1}{8} \left(A_2 - \frac{3A_1^2}{4} \right) X^2 - \right]$$

$$\frac{1}{8} \left(\frac{A_3}{4} - \frac{3A_1 A_2}{4} + \frac{5A_1^3}{16} \right) \quad X^3 + \dots \right] . \tag{38}$$

c. Independent Variable t, Time of Flight

$$X = U_0 t \cos \theta \left(1 - \frac{\Lambda_1 U_0 t \cos \theta}{8} - \frac{\Lambda_2 - \Lambda_1^2}{3 \cdot 8} U_0^2 t^2 \cos^2 \theta + ...\right)$$
 (39)

$$\frac{z}{x} = -\tan \theta + \frac{gt}{2U_0 \cos \theta} \left(1 + \frac{A_1 U_0 t \cos \theta}{4!} + 0 + \ldots \right) . \tag{40}$$

$$\tan \tau = \tan \theta - \frac{gt}{U_0 \cos \theta} \left[1 + \frac{A_1 U_0 t \cos \theta}{8} + \frac{A_2 U_0 t \cos \theta}{8} \right]$$

$$\frac{1}{3\cdot8}\left(\Lambda_2-\frac{\Lambda_1^2}{2}\right) v_0^2 t^2 \cos^2\theta + \ldots \right] \cdot (41)$$

$$U \cos \tau = U_0 \cos \theta \left(1 - \frac{A_1}{4} \frac{U_0 t \cos \theta}{4} - \frac{A_2 - A_1^2}{8} U_0^2 t^2 \cos^2 \theta + \ldots\right). (42)$$

d. Independent Variable (tan $\theta + Z/X$)

$$X = \frac{2U_0^2 \cos^2 \theta}{g} (\tan \theta + \frac{Z}{X}) \left[1 - \frac{2\Lambda_1}{3!} \frac{U_0^2 \cos^2 \theta}{g} (\tan \theta + \frac{Z}{X}) - \left(A_3 - \frac{2\Lambda_1^2}{3} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right)^2 \left(\tan \theta + \frac{Z}{X} \right)^2 + \dots \right]. \tag{43}$$

$$t = \frac{2U_0 \cos \theta}{g} \quad (\tan \theta + \frac{Z}{X}) \left[1 - \frac{2A_1}{4!} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) (\tan \theta + \frac{Z}{X}) + \frac{2A_1}{g} \right]$$

$$\frac{8}{4!} \Lambda_1^2 \left(\frac{U_0^2 \cos^2 \theta}{g} \right)^2 \left(\tan \theta + \frac{Z}{X} \right) + \dots \right] . \tag{44}$$

$$\tan \tau = \tan \theta = 2 \left(\tan \theta + \frac{Z}{X} \right) \left[1 + \frac{4A_1}{4!} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta + \frac{Z}{X} \right) + \frac{2A_1}{4!} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta + \frac{Z}{X} \right) \right]$$

$$\frac{4}{4!} \left(\Lambda_2 - \frac{2\Lambda_1^2}{3}\right) \left(\frac{U_0^2 \cos^2 \theta}{g}\right)^2 \left(\tan \theta + \frac{Z}{X}\right) + \ldots \right] . \tag{45}$$

$$U \cos \tau = U_0 \cos \theta \left[1 - \frac{2\Lambda_1}{4} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta + \frac{Z}{X} \right) - \frac{2\Lambda_1}{4} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta + \frac{Z}{X} \right) \right]$$

$$\left(\frac{A_2}{2} - \frac{A_1^2}{4!}\right) \left(\frac{U_0^2 \cos^2 \theta}{g}\right)^2 \left(\tan \theta + \frac{Z}{X}\right)^2 + \dots \right]. \tag{46}$$

e. Independent Variable (tan θ - tan τ)

$$X = \frac{U_0^2 \cos^2 \theta}{g} \quad (\tan \theta - \tan \tau) \left[1 - \frac{A_1}{4} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \right] (\tan \theta - \tan \tau) - \frac{1}{4} \left(\frac{A_2}{3} - \frac{A_1^2}{2} \right) \frac{U_0^4 \cos^4 \theta}{g^2} \quad (\tan \theta - \tan \tau)^2 + \dots \right]. \tag{47}$$

$$\tan \theta - \frac{Z}{X} = \frac{(\tan \theta - \tan \tau)}{2} \left[1 - \frac{2 A_1}{4!} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) (\tan \theta - \tan \tau) - \left(\frac{(A_2 - A_1^2)}{4!} \right) \left(\frac{U_0^4 \cos^4 \theta}{g^2} \right) \left(\tan \theta - \tan \tau \right)^2 + \dots \right]. \tag{48}$$

$$t = \frac{U_0 \cos \theta}{g} \left(\tan \theta - \tan \tau \right) \left[1 - \frac{A_1}{8} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{4} \left(A_2 - \frac{5 A_1^2}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right)^2 + \dots \right]. \tag{49}$$

$$U \cos \tau = U_0 \cos \theta \left[1 - \frac{A_1}{4} \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(A_2 - \frac{5 A_1^2}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(A_2 - \frac{5 A_1^2}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(A_2 - \frac{5 A_1^2}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\tan \theta - \tan \tau \right) - \frac{1}{8} \left(\frac{A_2^2 - \frac{5 A_1^2}{4}}{4} \right) \left(\frac{U_0^2 \cos^2 \theta}{g} \right) \left(\frac{A_1^2 - \frac{A_1^2}{4}}{4} \right) \left(\frac{A_1^2 - \frac{A_1^2}{4}}{4}$$

f. Accuracy of Series Solutions

In general, these series solutions will provide solutions accurate to within one or two percent of value for low or medium drag weapons (e.g. the Mk 76 bomb) released at less than 1,000 ft/sec velocity below +10 degrees release angles, and for ground ranges less than 15,000 to 20,000 feet.

For higher drag weapons, the series convergence is slow, and the remainder term implicit in each of the equations becomes large, causing considerable error. A sample calculation using set E.2.b. will illustrate.

From Table 8, we find for the Mk 76 bomb that the release conditions:

$$Z = 5,000 \text{ ft}$$
, $U_0 = 800 \text{ ft/sec}$, $\theta = -20 \text{ deg}$

yield the resulting trajectory parameters at Z = 0:

X = 7,986 ft, $U_1 = 818.0 \text{ ft/sec}$, $t_f = 11.841 \text{ sec}$, $\tau = 42.96 \text{ deg}$.

With the given ground range X and using eq. 24 to get an approximate value of Z from which to find air density, Mach number, and the appropriate value of KD, the series solutions, set E.2.b., give from eq. 35, 36, 37, and 38:

Z = 4,992 ft; error = 0.16%, $\tau = 42.92$ deg; error = 0.09%, $t_f = 11.803$ sec; error = 0.32%, $U_i = 824.9$ ft/sec; error = 0.84%

By contrast, the vacuum equations yield:

Z = 4,722 ft; error = 5.56%, $\tau = -39.30$; error = 8.69%, $t_f = 10.623$ sec; error = 10.30%, $U_f = 971.5$ ft/sec; error = 18.77%

As an example for a high drag weapon, Table 9 gives for the fictitious HD 200 bomb, with the release conditions:

Z = 500 ft,

 $\theta = 0 \deg$,

 $v_o = 800 \text{ ft/sec}$,

the following trajectory parameters at Z = 0 ft:

X = 2,100 ft, $\tau = 43.75 \text{ deg}$, $t_f = 7,053 \text{ sec}$, $U_f = 184.0 \text{ ft/sec}$.

Equations set E.2.b. with sea level air density assumed, gives

Z = 401.6 ft; error = 19.7%, $\tau_1 = 33.82$ deg; error = 22.7%, $t_f = 6.496$ sec; error = 8.2%, $U_1 = (unknown, series alternating)$

In this example, it is obvious that the convergence of these series solutions is slow, and too few terms are included.

For high drag weapons such as the HD 200, it is suggested that the closed solution equations of the following sections be used rather than the series solutions.

3. Closed Solutions

A closed solution is easier to work with, particularly when the equations are used in a bombing system. Two forms are considered here: (1) an exponential approximation to the series solutions; and (2) an empirical function representation of the solution.

The basic equations are written as:

$$Z = -X \tan \theta + \frac{gX^2}{2U_0^2 \cos^2 \theta} \psi , \qquad (51a)$$

$$t_{f} = \frac{X}{U_{o} \cos \theta} \quad \Phi , \qquad (51b)$$

$$\tan \tau = \tan \theta - \frac{gX}{U_0^2 \cos^2 \theta} \psi_{\tau}, \qquad (51c)$$

and

$$U \cos \tau = U_0 \cos \theta \psi_0. \tag{51d}$$

The problem is to find convenient functions for ψ , ϕ , ψ_{τ} , and ψ_{u} . These are given in series form by eq. 35 through 37. These series suggest that the variable:

$$\rho\,cK_{\stackrel{}{D}}\,\,X\,\,\,\text{sec}\,\,\,\theta$$

be used in finding suitable functions. For condensing the notation use:

$$k = (2/3) \rho c K_D$$
, (52)

$$k_0 = (2/3) \rho_0 cK_D,$$
 (53a)

and

$$k_{T} = (2/3) \rho_{T} c K_{D},$$
 (53b)

when the T subscript indicates value at the impact (target) point. Figure 2 indicates the bomb terminal velocity as a function of k for p equal to sea level value.

One set of approximations is:

$$\ln \psi = kX \sec \theta (1 + 0.285 kX \sec \theta)$$
, (54a)

$$\ln \Phi = (3/4)kX \sec \theta (1.0364 + 0.134 kX \sec \theta)$$
, (54b)

$$\ln \psi_{\perp} = (3/2)kX \sec \theta (1.0173 + 0.296 kX \sec \theta)$$
 (54c)

For many uses these can be approximated by 2:

$$ln \psi = kX \sec \theta$$
, (55a)

$$\ln \Phi = (3/4) \ln \psi$$
, (55b)

$$\ln \psi_{\tau} = (3/2) \ln \psi$$
, and (55c)

$$\ln \psi_{ii} = (3/2) \ln \psi$$
 (55d)

For other uses, such as in bombing systems and some nomographs, a mathematical expression is not needed. This leads to the empirical functions³:

$$\psi = \psi(kX \sec \theta) \tag{56}$$

$$\Phi = \Phi(kX \sec \theta) \tag{57}$$

$$\psi_{\tau} = \psi_{\tau}(kX \sec \theta)$$
 (58)

Figures 3 to 8 show empirical functions which were determined by using bombing tables (for several bombs) that had been computed by numerical integration, and then computing the functions, such as ψ , in reverse. Figures 9 to 17 show the data used in obtaining the functions. The accuracy of the fit can be seen. Tables 2, 3, and 4 give the functions in number form. Using k_T in the above equations gives a better fit for retarded bombs.

Most retarded bombs are <u>not</u> retarded from release (as is assumed in this report) but are low drag for a short time or distance from the aircraft. This discontinuous drag presents a problem. Empirical functions similar to those shown in Fig. 3-8 can be obtained; however, each bomb will probably have its own set of functions.

Often the lead angle, y, is desired. This can be obtained by:

$$\sin \gamma = \frac{gX \cos (\gamma - \theta)}{2U_0^2 \cos \theta} \psi . \qquad (59)$$

These give good results for low drag bombs. For higher drag bombs and retarded weapons an empirical value of k should be used. The expression for u must be used with skepticism on high drag bombs.

The basic equations 51 and 59 can be used to express the empirical functions independent variable in various forms.

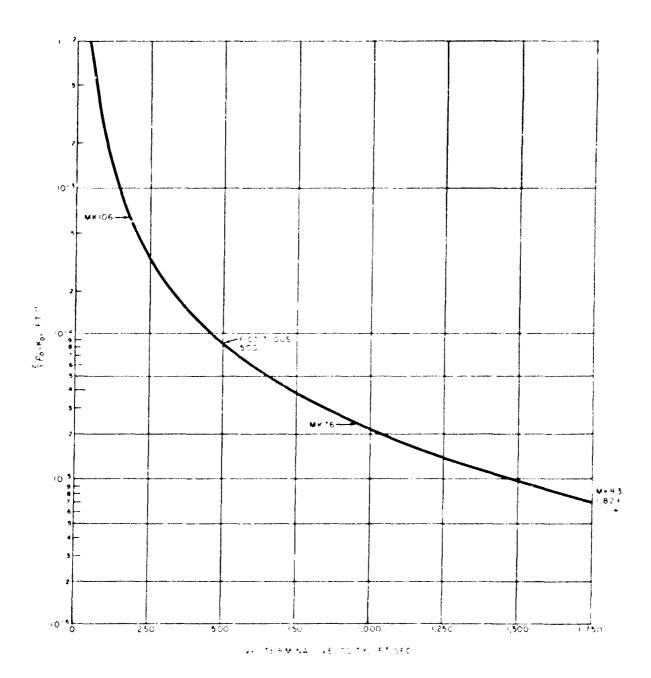


Fig. 2. Ballistic Drag Function.

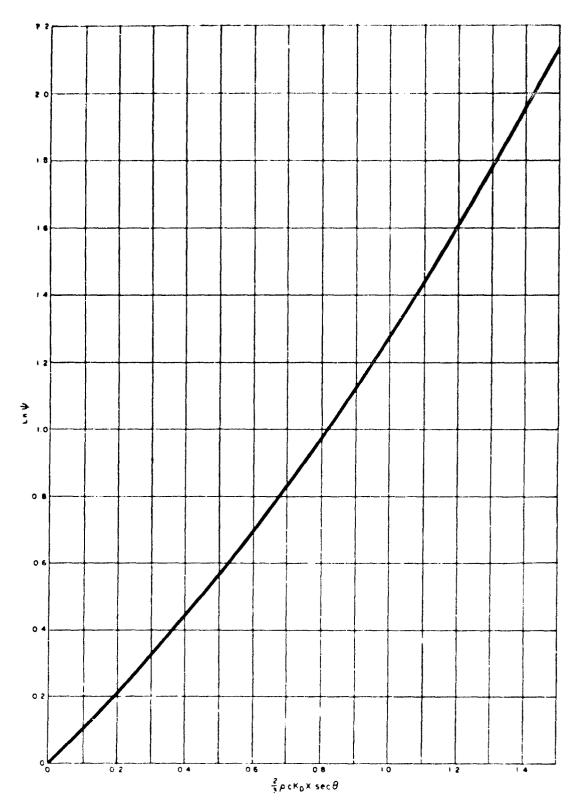


FIG. 3. Ballistic Drag Function.

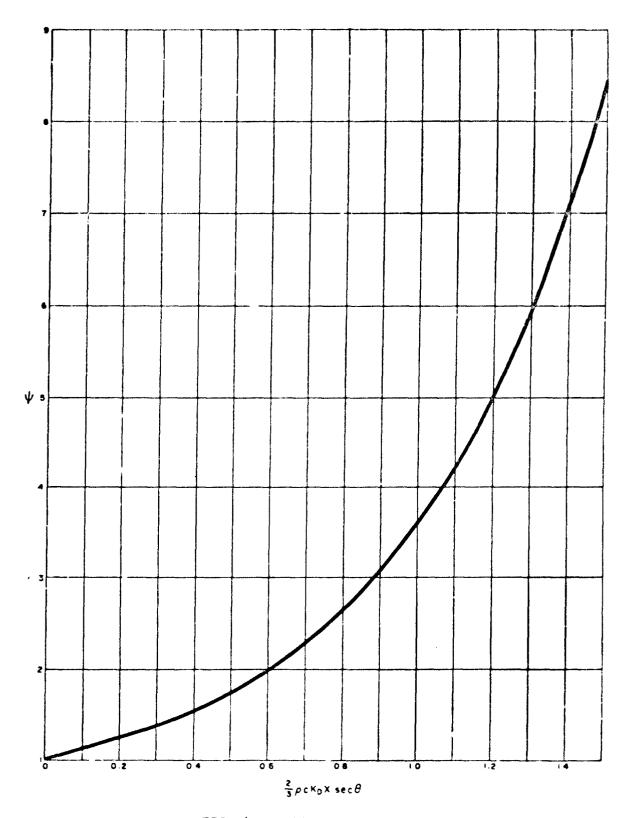


FIG. 4. Ballistic Drag Function.

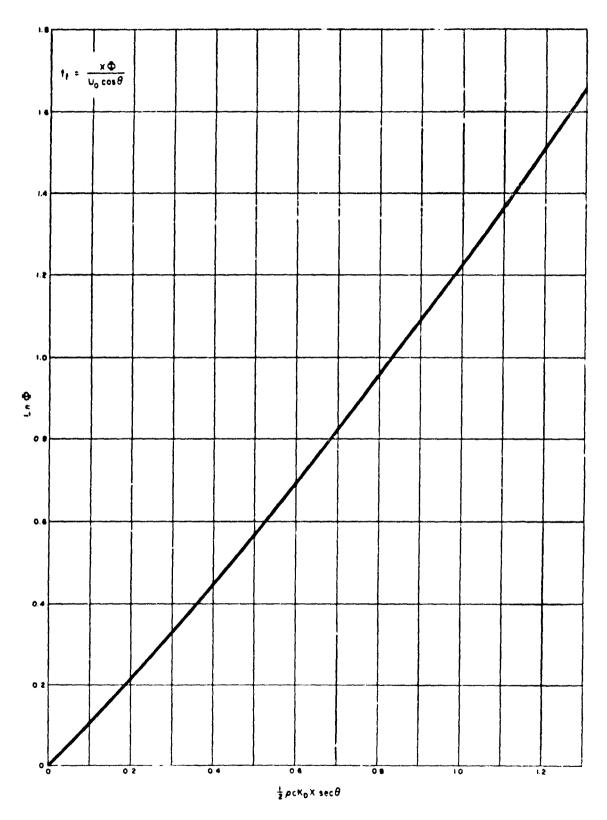


FIG. 5. Ballistic Drag Function.

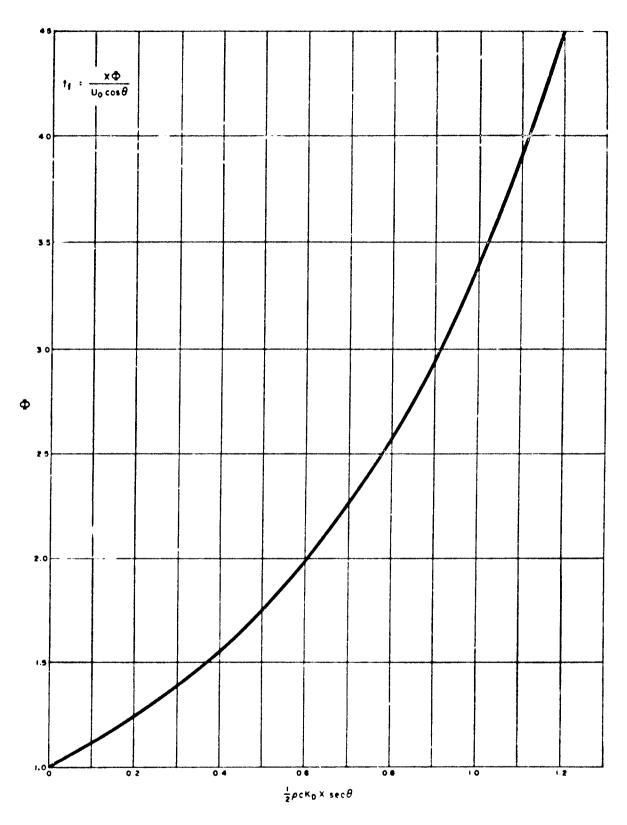


FIG. 6. Ballistic Drag Function.

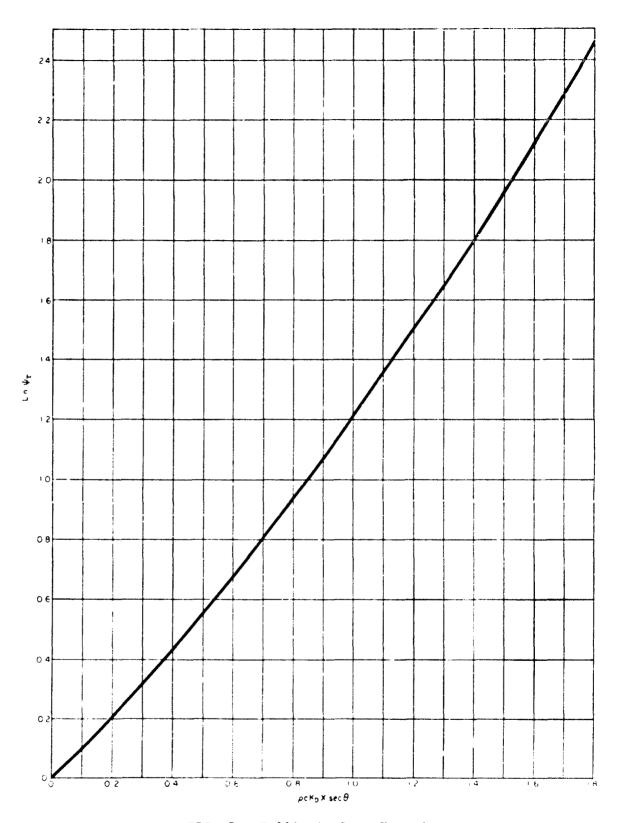


FIG. 7. Ballistic Drag Function.

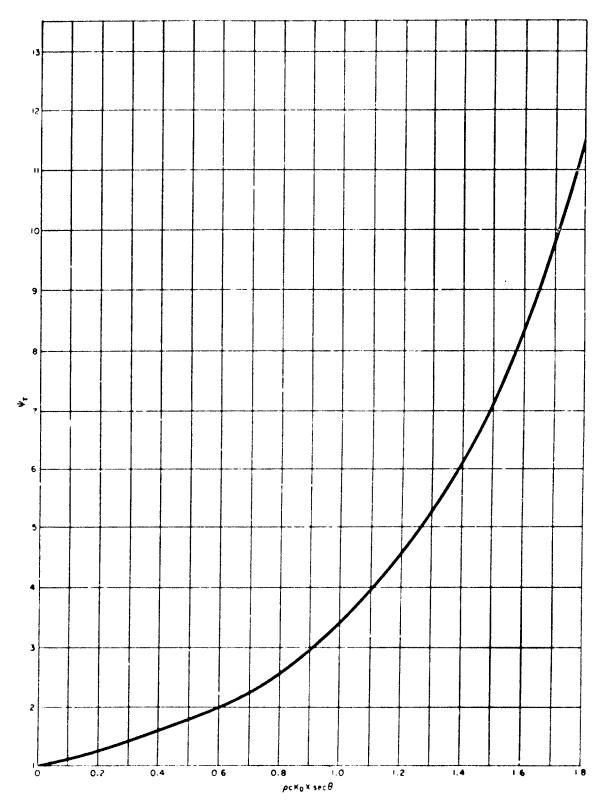


FIG. 8. Ballistic Drag Function.

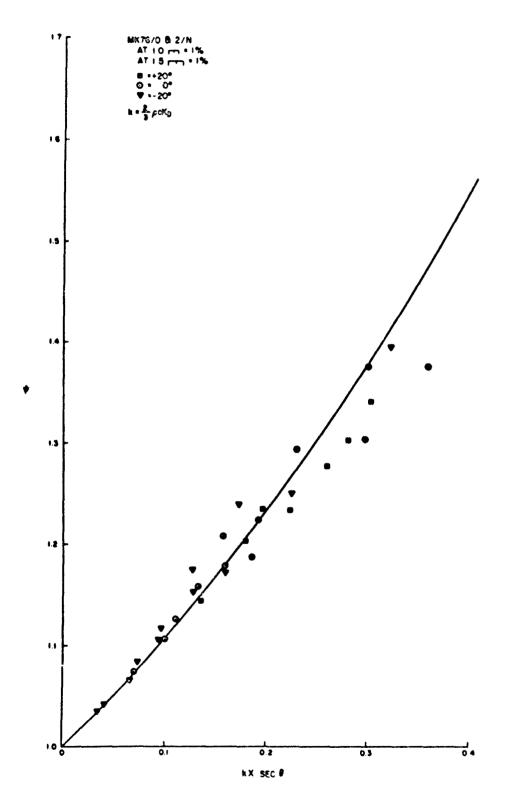


FIG. 9. Ballistic Drag Function.

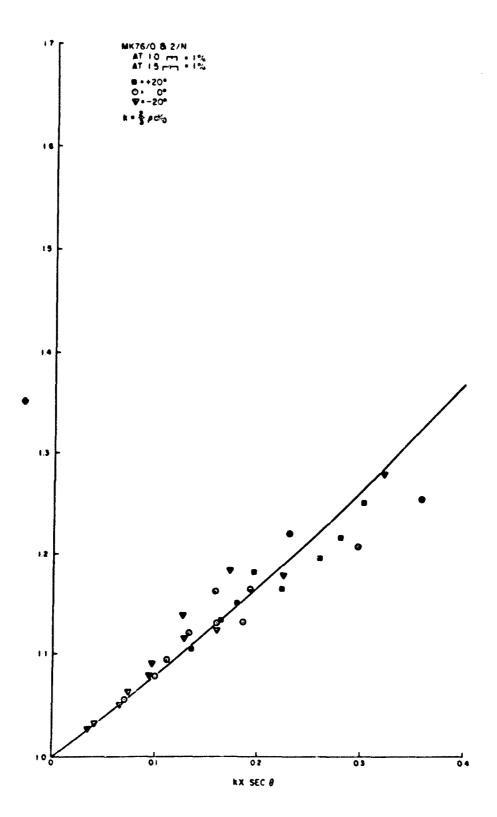


FIG. 10. Ballistic Drag Function.

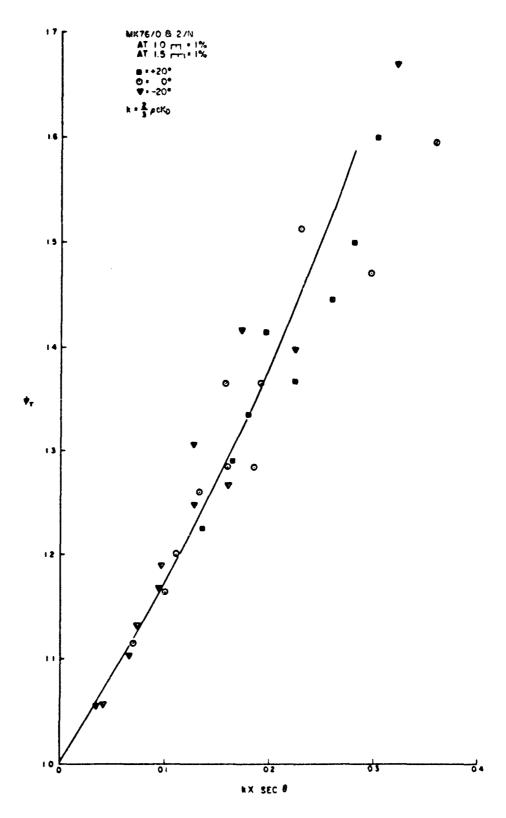


FIG. 11. Ballistic Drag Function.

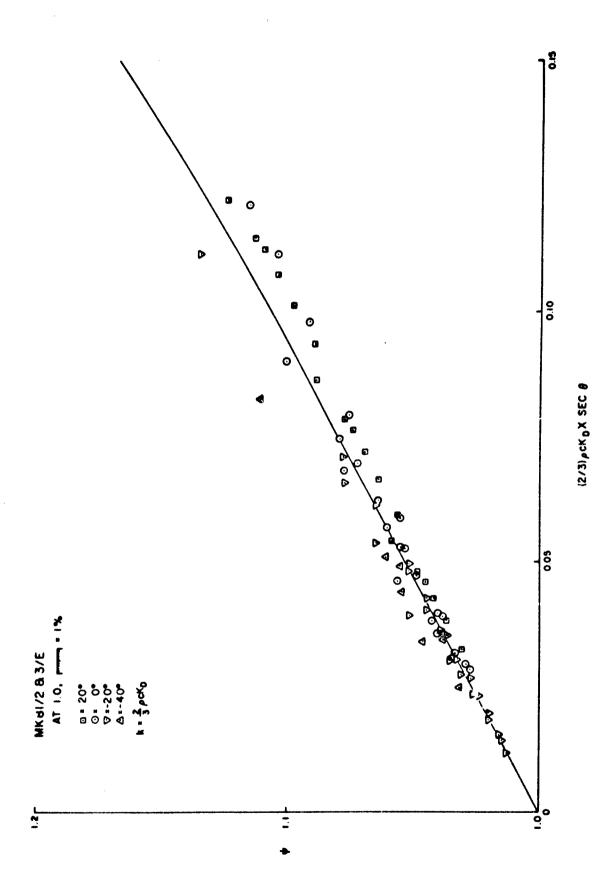


FIG. 12. Ballistic Drag Function.

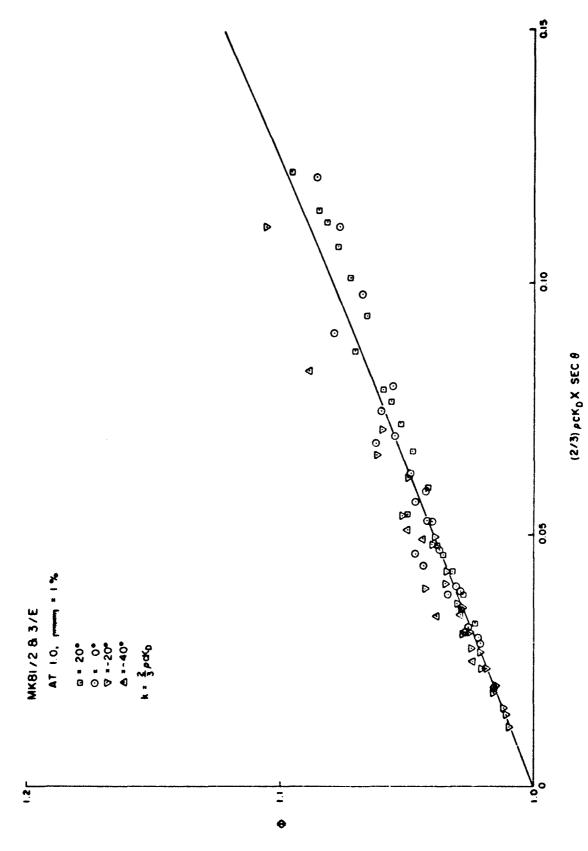
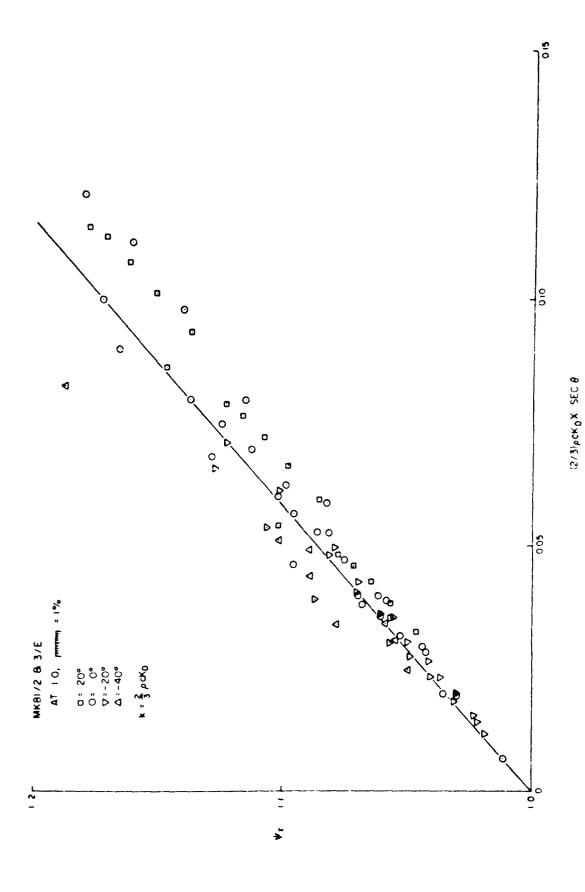
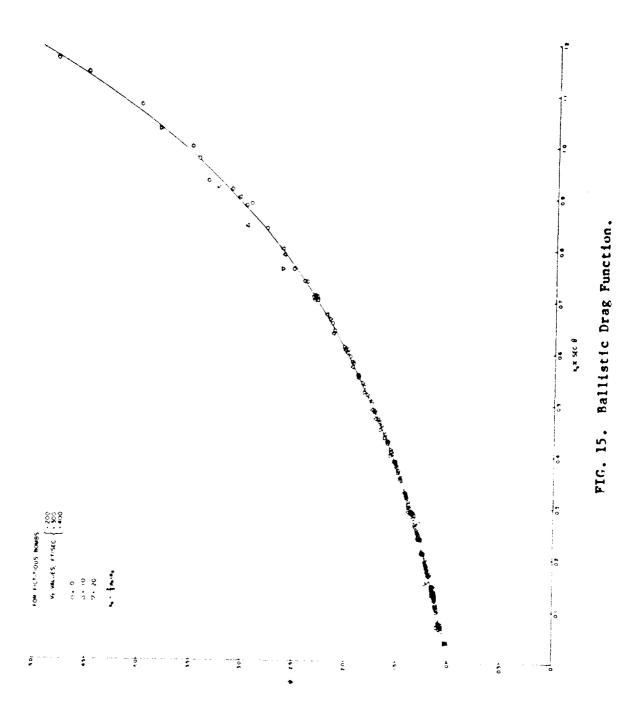


FIG. 13. Ballistic Drag Function.

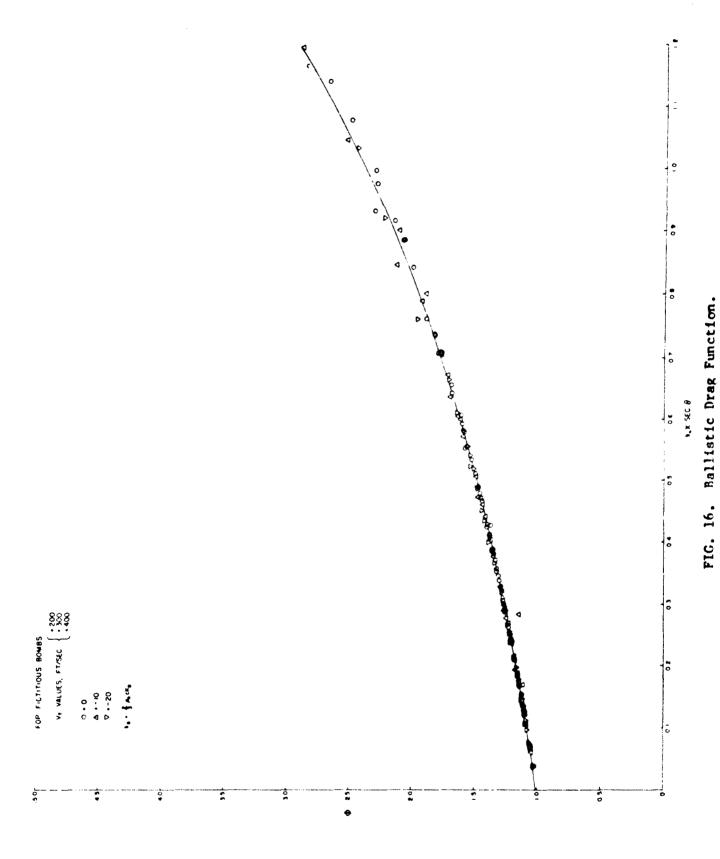


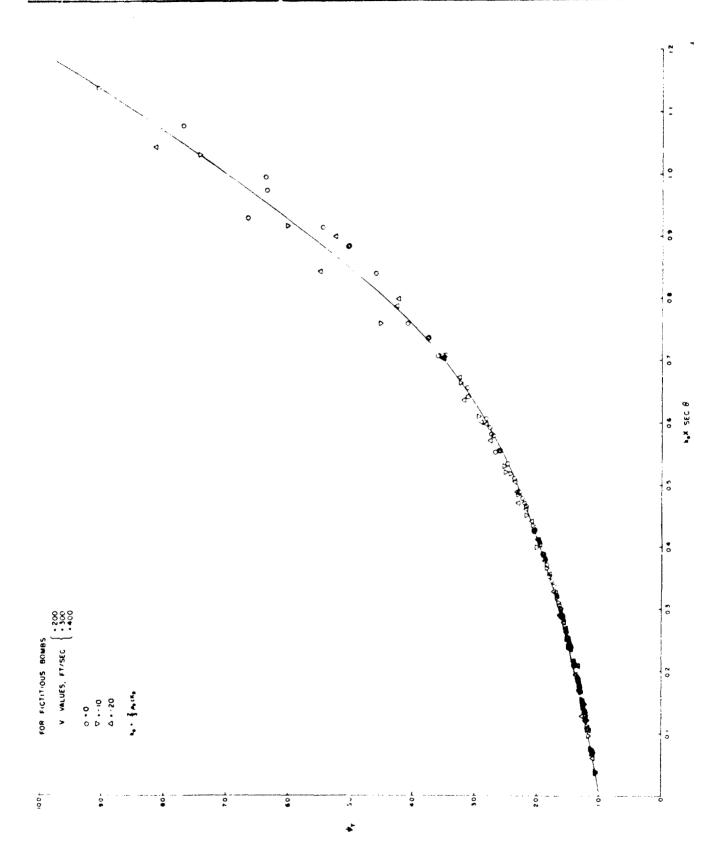
27

FIG. 14. Ballistic Drag Function.



28





Ballistic Function Y and En \div Versus 2/3 pc K_D x sec υ (kX sec υ) TABLE 2.

kX cos c	>	£n ÿ	kX cos u	€	gn &	kX cos θ	> -	£n ÷	kX cos E	>-	fu v	kX cos c]	fn ¥
00.	1.000	.000	.30	1.380	.322	09.	2.003	695	. 90	3.070	1.121	7.	10.	19:
.02		.020	.32) 4	.62	.05	721	2	77.	3.5	1.21	5.10	1.629
.03	1.030	.030	.33	•	35	.63	.08	~	.93	. 20	.16	. 2	. ~	5 6
÷.	1.041	.040	.34	•	36	.64	.11	.747	76.	.25	.18	. 2	. m	. 68
.05	1.051	.050	.35	•	.381	.65		.761		.30	19	7	7	7.0
90.	1.062	090.	.36	•	.393	99.		.775		.35	. 21			
.07	1.073	.070	.37	•	707	.67	. 2	.789	6	41	. 22	. 2	, .0	73
.08	1.084	.081	.38	1.516	914.	.68	2.233	708.	.98	3.467	1.243	1.28		. ~
60.	1.096	.092	.39	•	.428	69.	. 2	.818	6	. 52	. 26	. 2	5.88	1.771
.10	1.107	.102	07.	٠.	077	. 70		832		ď	77	~	c	,
.11	1.119	.112	14.	1.570	.451	~	2.332	.847	1.01	3.638	1 291		6.70	· «
.12	1.131	.123	.42	₹.	.463	1	•	.861		69	30		•	3 6
.13	1.143	.134	.43	9.	.475	.73	•	.875	•	.75	32	. ~	. ~	8
. 14	1.156	.145	777	9	.487	~	•	.889	•	.81	.33	Ψ,	7.	1.856
.15	1.158	.155	.45	•	•	.75	47	706	C	ď	2	r	U	
.16	1.181	.166	94.	•	, ,- -	.76	.50	919	0	6			م	•
.17	1.194	.177	.47	1.688	. 524	.77	2.542	.933	1.07	3,995	1,385	, ~	6 73	•
. 18	1.207	.188	84.	•	53	.78	.57	.947	0	90.	9	, (1)	٠ م	•
.19	1.220	. 199	65.	•	4	.79	.61	.961	0.	. 12	.41	1.39	· •	1.941
. 20	1.234	.210	.50	•	•	.80	9.	.975	,q	19	7		C	C.
.21	1.248	.222	.51	1.777	.575	.81	2.690	066.	1.11	4.270	1.452	1.41	?	•
.22	1.262	.233	.52	•	œ	.82	۲.	•	٦.	.34	7		. ~	00
.23	•	. 244	.53	•	0	.83	<u>.</u>	1.018	~	.42	4.	•	7	` [
. 24	1.290	.255	. 54	•	-	. 84	œ	•		. 50	٠.		7.61	2.030
.25	1,305	.266	.55	•	.628	.85	. 84	.04		.58	. 52	7		2
.26	1.320	.278	. 56	•	.642	98.	.89	.06	۲.	.66	.53	•	•	Š
.27	1.335	. 289	.57	1.926	.655	.87	2.337	1.077	1.17	4.745	1.557	1.47	8.07	2.088
. 28	1.350	.300	85.	•	699.	88.	.98	.09	•	.83	.57	7.	•	. 12
29	1.365	.311	65.	•	.682	68.	.02	. 10		.92	. 59	. 5	•	. 14

Ballistic Function Φ and in Φ Versus 1/2 pc K_D x sec θ (3/4 kX sec θ) TABLE 3.

	£n �	1,223	•	•	1,265	•	-2	۳,	1,322	٣,	٠,		, ,	1,394		•	1,438	1,452	1,466							
	•	۳.	7.	7.	3,543	5	3.644	.67	3,751	.80	.85		, ,	4.031		•	.21	2	.33							
	3/4 kX	1.00	1.01	1.02	1,03	1.04	1,05	1.06	1.07	1.08	1.09	1.10		1,12	1,13	1.14		1,16	~							
	tn ф	.881	.893	806	.920	.934	876.	,962	.975	886	1.002	•	1,029	1,043	•	•	80.	60.	1.111	.12	13	-	-	-	1.194	-
	•		•	•	2,509	•	2.580	9	2.651	9			•	2.838	•	•	•	•	3,037	•	•	3,168	3 216	3,758	3.300	3,347
9	3/4 kX cos 9	.75	• 76	.77	.78	•79	80	.81	.82	.83	*84	.85	86	.87	.88	.89	90	.91	.92	.93	76	.95	96	47	98	66.
	tn 🗣	.563	.575	.588	.599	.612	.624	.637	679.	.662	.674	688	700	.713	.726	.738	.750	.763	177.	.789	.801	.815	828	842	.855	.868
	•		1.777		1,820	1.844	1.866	.89	1.914	.93	•		, ,	2.040	•		•	•	2,175			•	•	•	2,351	•
	3/4 kX cos 0	.50	.51	.52	.53	.54	.55	• 56	.57	.58	•59	09	.61	.62	.63	*9	.65	99.	.67	.68	69*	.70	. 71	.72	.73	.74
	tn 🗣	.269	.279	.291	.302	.313	.325	.336	.348	.359	.371	183	191	404	.418	.429	.442	.452	795.	.478	067.	502	513	526	538	.550
	•	1,309	1,322	1,333	1,353	1,367	1,384	1,399	1,416	1,432	1,449	1.467	1.481	1,498	1.519	1,536	1,556	1,571	1,590	1,613	1.632	1.652	1 670	1.692	1,713	1,733
	3/4 kX cos θ	.25	• 26	.27	•28	•29	• 30	.31	.32	.33	.34	35	36	.37	38	•39	07.	.41	.42	.43	77.	57	97	7.7	87	67.
	ln ф	000	.012	.024	.034	.043	.054	*90	•074	.085	.095	106	116	.127	.138	.148	.158	.170	.181	.192	.202	.213	225	l C	.248	7
	•	1,000	1.012	1.024	1,035	1.044	1,055	1.066	1.077	•	1.100	1,112	1.123	1,135	1,148	1,159	1,171	۳.	1,198	.2	• 2	7	C	•	7	• 29
	3/4 kX cos 8	00.	.01	.02	.03	•00	.05	90.	.07	•08	60*	.10	.11	.12	.13	.14	.15	•16	.17	.18	•19	•20	.21	.22	.23	.24

TABLE 4. Ballistic Function : $_{ au}$ and in $_{ au}$ Versus pc K $_{
m D}$ x sec θ (3/2 kX sec θ)

3/2 kX sec b	ş.	£nŸŢ	3/2 kX sec v) -	£n≚⊤	3/2 kX	}	£n:T	3/2 kX sec 6	jer jer	£n∀⊤	3/2 kX	} -	£n.Y.
00.	1.000	000.	.25	1.306	9	.50	74	55		.39	1 ~	1 %	38	21
10.	•	.011		.32	~	.51	.76	56		.42	88	0	43	23
.02	1.022	.022	.2	.33	.289	.52	1.788	.581		9	006		7	24
.03	•	.034		.35	0	.53	.81	59		67.	91	0	53	26
. 04	•	970.	7.	.36	-	. 54	.82	0	1	.5	.928	1.04	3.586	1.277
0.5	5	057	Ş	2		U	Ċ		(1				
50.	5 5		2.5	2.0	v		3		. 80	. 56	せ	0	۰.	7
90.	70.	.008	.31	. 3 9	~	. 56	.88	63	.81	. 59	S	0	9	٣,
70.	80.	.078	.32	.41	サ	.57	. 90	t.	.82	.63	9	0	7	ູ
80.	1.092	.088	.33	1.428	.356	. 58	1.925	.655	.83	.67	∞	0	_	. "
60.	≘.	.097	.34	77.	9	.59	.94	9	8	2.713	766.	1.09	3.850	1,348
•														•
.10		. 105	.35	1.462	.380	9.	.97	∞		.74	00.	7	6	.36
Ι.	. 12	.117	<u>.</u>	.47	9	.61	.99	6		. 78	.02		6	37
.12	. 13	. 129	٣.	67.	0	.62	.02	70		.82	03	, ,,,		9
.13	•	.140	٣.	.51	-	.63	.04	7.1	00	86	50		•	
.14	. 16	.150	<u>۳</u>	. 53	2	79.	2.075	.730	. 89	2.895	1.063	1.14	4.145	1 422
										·	•	•	•	•
.15		.160	07.	1.550	\sim	.65	01:	74	.90	.939	.07	7	20	٤7
. 16	. 18	.170	•	'n.	4	99.	.13	75	.91	.980	60	, ,	26	57
.17	. 19	. 180		₹.	9	.67	.16	77	6	050			٠ د	7.4
.18	.20	.190	•	9.	.472	.68	_	7	9	.065	12	•	, 6	
.19	. 22	. 200	•	9.	∞	69.	21	767.	76.	105	1.133	1.19	4.459	1.495
	23	_	٧.	,	ē	<u> </u>	2	(,				· ·
) (4 (÷.	•	7	٥.	77.	\supset	3	.152	~	7	. 52	5
	77.	~	97.	9.	Ò	.71	.27	7	9	.196	~	7	59	S
. 22	1.262	. 233	.47	1.684	. 521	.72	0	.833	.97	.238	-	. 2	9	75
	.27	4	.48		3	.73	.33	4	6	.287	,	. 2		
	. 29	S	67.	۲.	4	.74	ų.	.860	66.	333	1.204	1.24	4.807	1.570
			•			-			_			•		•

Ballistic Function \mathbb{Y}_{τ} and In \mathbb{Y}_{τ} Versus Dc K_D x sec υ (3/2 kX sec υ) TABLE 4.

	£nv⊤						
	L'A						
	3/2 kX sec t						
	£n Ÿ⊤	2.772					
	ΨŢ	15.991					
	3/2 kX sec t	2.00					
	£n Ψτ	2.369 2.385 2.402	2.418 2.434 2.451	4440	2.532 2.547 2.563 2.563	. 59 . 61 . 64 . 66	2.694 2.710 2.725 2.742 2.742
(Cont'd.)	ΫŦ	10.687 10.859 11.045					14.791 15.029 15.256 15.518 15.753
၁)	3/2 kX sec b	1.75 1.76 1.77		` 		1.89 1.90 1.91 1.92 1.93	1.95 1.96 1.97 1.98 1.99
	ξn:τ	1.970 1.988 2.002	2.019 2.034 2.050	2.067 2.082 2.098 2.112		2.192 2.207 2.223 2.240 2.256 2.256	2.289 2.303 2.321 2.337 2.353
	.	7.301		7.901 8.020 8.150 8.265	8.398 8.542 8.671 8.811	8.953 9.088 9.235 9.393 9.545	9.865 10.004 10.186 10.350 10.517
	3/2 kK sec v	1.50 1.51 1.52	N, N,	1.56 1.57 1.58 1.59		o.	1.70 1.71 1.72 1.73
	βn∵⊤	1.586 1.600 1.617	9. 9.	1.677 1.692 1.705 1.722	.73 .75 .76 .78	.80 .83 .84 .84 .86	1.893 1.908 1.923 1.939 1.939
	} +	4.884 4.953 5.038	.114	5.349 5.430 5.501 5.596	.686 .766 .859	. 050 . 135 . 234 . 341 . 430 . 540	6.639 6.740 6.841 6.952 7.057
	3/2 kX sec c	1.25 1.26 1.27	2.2. 8.	1.31 1.32 1.33 1.34		w 44444	1.45 1.46 1.47 1.48

One of the nomographs uses the strictly empirical equation:

$$t_f = \sqrt{\frac{2Z}{g}} e^{(k_{Zt})Z^{(1/3.5)}}$$
 (60)

Figure 18 gives a graph of k_{Zt} versus terminal velocity.

4. Partial Derivative Equations

The partial derivative equations of this section were obtained from the closed trajectory equations of Section 3. For an initial set of release conditions and the resulting trajectory parameters, the equations will give the change in the dependent variable due to an incremental change in the independent variable from its value in the initial set, all other release variables remaining constant. Where possible, several equivalent forms of the equations are given.

For simplicity the assumption is made that $\ln \psi = (2/3) \operatorname{pcK}_D X$ sec θ , and $\psi = \exp(2/3) \operatorname{pcK}_D X$ sec θ . For very high drag weapons this approximation for the more exact expressions given by eq. 52, 54, and 56, will result in some error, but this is usually negligible for the purpose for which these equations are normally used.

(1) Dependent variable X, horizontal range

$$\frac{\partial X}{\partial Z} = \frac{2U_o^2 \cos^2 \theta}{gX\psi (2 + \ln \psi) - 2U_o^2 \sin \theta \cos \theta}$$
 (61a)

$$= \frac{X}{Z + (Z + X \tan \theta)(1 + tn\psi)}$$
 (61b)

$$= \frac{1}{\tan \phi + (\tan \phi + \tan \theta)(1 + \ln \psi)}$$
 (61c)

$$= -\cot \tau \tag{6!d}$$

$$\frac{\partial X}{\partial U_0} = \frac{2}{U_0} \frac{gX^2 \psi}{gX \psi (2 + 2n\psi) - 2U_0^2 \sin \theta \cos \theta}$$
 (62a)

$$= \frac{2X}{U_0} \frac{Z/X + \tan \theta}{(Z/X + \tan \theta)(2 + \ln \psi) - \tan \theta}$$
 (62b)

$$= \frac{2X}{U_0} \frac{\tan \phi + \tan \theta}{(\tan \phi + \tan \theta)(2 + \ln \psi) - \tan \theta}$$
 (62c)

$$\frac{\partial X}{\partial \theta} = \frac{2U_0^2 - gX\psi \tan \theta (2 + in\psi)}{gX (2 + in \psi) - 2U_0^2 \sin \theta \cos \theta}$$
 (63a)

$$= x \frac{\sec^2 \theta - \tan \theta (7/X + \tan \theta)(2 + \ln \psi)}{(2/X + \tan \theta) (2 + \ln \psi) - \tan}$$
 (63b)

$$= X \frac{\sec^2 \theta - \tan \theta (\tan \phi + \tan \theta)(2 + \ln \psi)}{(\tan \phi + \tan \theta)(2 + \ln \psi) - \tan \theta}$$
 (63c)

$$= - X (\cot \tau + \tan \theta)$$
 (63d)

$$\frac{\partial X}{\partial (cK_D)} = -\frac{1}{cK_D} \frac{gX^2 \psi \ln \psi}{gX\psi (2 + \ln \psi) - 2U_0^2 \sin \theta \cos \theta}$$
(64a)

$$= -\frac{X}{cK_D} \frac{(\tan \phi + \tan \theta) \ln \psi}{\tan \phi + (\tan \theta + \tan \theta)(1 + \ln \psi)}$$
 (64b)

=
$$\frac{X}{cK_D}$$
 cot τ_i (tan ϕ + tan θ) $\ln \psi$ (64c)

(2) Dependent variable t, time of fall

$$\frac{\partial t}{\partial z} = -\frac{\psi^{3/4}}{U_0 \cos \theta} \left\{ 1 + (3/4) \ln \theta \right\} \cot \tau \qquad (65a)$$

$$= -\frac{t}{x} \{1 + (3/4) \ln \psi\} \quad \cot \tau$$
 (65b)

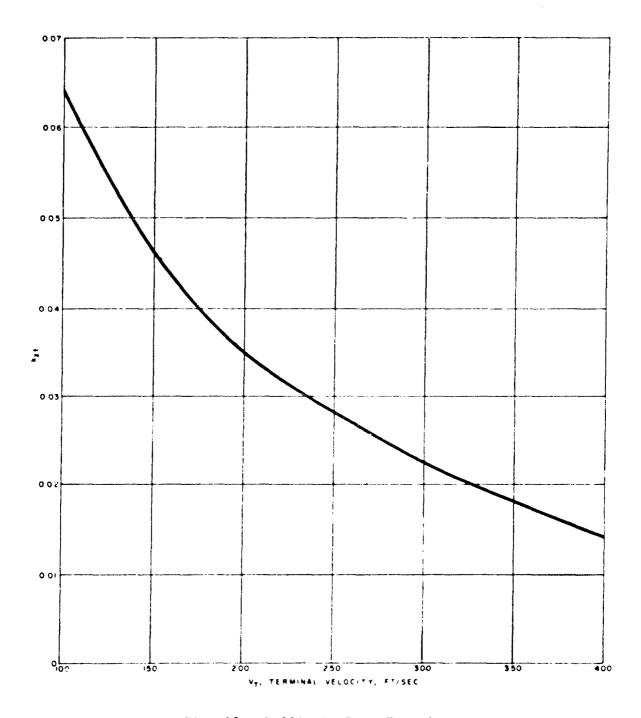


Fig. 18. Ballistic Prag Function.

$$\frac{\partial t}{\partial U_0} = -\frac{\chi \psi}{U_0^2 \cos \theta} \left[1 + 2 \left\{ 1 + (3/4) \ln \psi \right\} \left(\tan \phi + \tan \theta \right) \cot \tau \right]$$
 (66a)

$$= -\frac{t}{U_0} \left[1 + 2 \left\{ 1 + (3/4) \ln \psi \right\} (\tan \phi + \tan \theta) \cot \tau \right]$$
 (66b)

$$\frac{\partial t}{\partial \theta} = -t \cot \tau \left\{ 1 + (3/4) \ln \theta \right\} \tag{67}$$

$$\frac{\partial t}{\partial (cK_{D})} = 3/4 \frac{t}{cK_{D}} tn\psi$$
 (68)

(3) Dependent variable 1. impact angle.

$$\frac{\partial \tau}{\partial U_0} = \frac{2 \cos^2 \tau}{U_0} \left(\tan \theta - \tan \tau \right) \left[1 - \cot \tau \left(\tan \theta + \tan \theta \right) \left\{ 1 + (3/2) \ln \psi \right\} \right]$$
(69)

$$\frac{\partial \tau}{\partial \theta} = \cot \tau \tan \theta \left\{ 1 + (3/4) \ln \psi \right\}$$
 (70a)

$$= \frac{\tan \theta \left\{1 + (3/2) \ln \psi\right\}}{\tan \phi + (\tan \phi + \tan \theta) (1 + \ln \psi)}$$
 (70b)

$$\frac{\partial \tau}{\partial z} = -\frac{\cos^2 \tau \cot \tau^2 g \psi^{3/4} \{1 + (3/4) \ln \psi\}}{U_0^2 \cos^2 \theta}$$
(71a)

=
$$\cos^2 \tau \cot \tau (\tan \theta - \tan \tau) \{1 + (3/4) \ln n \} / X$$
 (71b)

$$\frac{\partial \tau}{\partial (cK_D)} = -\frac{\cos^2 \tau}{ck_D} \left(\frac{gX\psi}{2U_O^2 \cos^2} \right) \ln \psi \quad (3 + \ln \epsilon)$$
 (72a)

$$= \frac{\cos^2 \tau}{cK_D} (\tan \tau + \tan \theta + 2 \tan \phi) (3 + \ln \phi)$$
 (72b)

$$= \frac{3 \cot \tau_1}{2 \operatorname{ck}_{D}} \operatorname{ln} \psi \tag{72c}$$

(4) Dependent variable V, true airspeed

$$\frac{\partial U}{\partial \theta} = -U_0 \sec \tau \sin \theta \psi^{-3/2} \left[\left\{ 1 + (3/2) \ln \psi \right\} \right]$$
 (73a)

$$= - U \tan \theta \sec \tau \left[\left\{ 1 + (3/2) \ln \psi \right\} \right]$$
 (73b)

$$\frac{\partial U}{\partial U} = \frac{\cos \alpha}{\cos \tau} \psi^{-3/2} \tag{74a}$$

$$= \frac{l!}{l!}$$
 (74b)

$$\frac{\partial U}{\partial Z} = -3/2 \left(\frac{U}{X} \cot \tau_i \ell n \psi \right)$$
 (75)

$$\frac{\partial U}{\partial (cK_{D})} = -\frac{3 U_{o} \cos \theta \psi^{-3/2}}{2 cK_{D} \cos \tau} \ell n \psi$$
 (76a)

$$= \frac{3 \text{ U } \ln \psi}{2 \text{ cK}_{D}} \tag{76b}$$

III. NUMERICAL DATA

A. CONVERSION FACTORS AND CONSTANTS

Various constants: $\pi = 3.14159265$ e = 2.71828183

Measures of length:

1 meter = 1.0936 yards = 3.2808 feet = 39.3700 inches

1 foot = 0.30480 meter

1 inch = 2.5400 centimeter

1 mile = 1.60935 kilometer

1 kilometer = 0.62137 mile

1 nautical mile = 6,076.1 feet

1 mile = 0.86898 nautical mile

Measures of velocity:

1 foot per second = 0.5925 knots

1 knot = 1.6878 feet per second

Measures of pressure:

1 pound per square foot = 0.01414 inches Hg at 32°F

= 4.725×10^{-4} atmosphere

= 0.006944 pounds per square inch

1 millibar = 2.089 pounds per square foot

1 atmosphere = 29.92 inches of Hg at 32°F

Angular measure:

1 degree = 0.01745 radians = 0.002778 revolutions

1 radian = 57.296 degrees

B. AIR DATA TABLE

Several parameters of interest are tabulated in Table 5 with respect to altitude. The values given here are in agreement with the values defined by ICAO. The following quantities are listed herein:

h = altitude in feet

 $P = density in lb/ft^3$

 ρ/ρ_0 = ratio of density at given altitude to density at zero altitude

 P_s = the "standard" pressure for that altitude given in $1b/ft^2$

 P_s/P_{so} = the ratio of pressure at given altitude to pressure at zero altitude

Cs = speed of sound at given altitude

Conversion factor = Mach no./1000 fps

 U_t/U_t = ratio of true velocity to indicated velocity

T = standard temperature in F

TABLE 5. Air Data

h ft	ρx10-2 lb/ft ³	$\frac{\rho}{\rho_{ullet}}$	P ₈ lb/ft ²	$\frac{\frac{P_{s}}{P_{so}}}{\frac{P_{so}}{P_{so}}}$	C _s fps	Mach no. 1000 fps	u _t /u _i	T °F
0	7.648	1.0000	2116	1.000	1117	.8953	1.0000	59.00
200	7.603	0.9942	2101	0.9928	1116	.8961	1.0029	58.29
400	7.558	0.9884	2086	0.9856	1115	.8969	1.0059	57.57
600	7.514	0.9826	2071	0.9785	1115	.8969	1.0089	56.86
800	7.470	0.9768	2056	0.9714	1114	.8977	1.0118	56.15
1000	7.426	0.9711	2041	0.9644	1113	.8985	1.0148	55.43
1200	7.383	0.9654	2026	0.9574	1112	.8993	1.0178	54.72
1400	7.339	0.9597	2011	0.9504	1112	.8993	1.0208	54.01
1600	7.296	0.9540	1997	0.9435	1111	.9001	1.0238	53.29
1800	7.253	0.9484	1982	0.9366	1110	.9009	1.0268	52.58
2000 2200 2400 2600 2800	7.210 7.167 7.125 7.082 7.040	0.9428 0.9372 0.9316 0.9261 0.9206	1968 1953 1939 1925 1911	0.9298 0.9230 0.9163 0.9095 0.9029	1109 1108 1108 1107 1106	.9017 .9025 .9025 .9033	1.0299 1.0330 1.0361 1.0391 1.0422	51.87 51.15 50.44 49.73 49.02
3000 3200 3400 3600 3800	6.998 6.957 6.915 6.874 6.833	0.9151 0.9097 0.9042 0.8938 0.8934	1897 1883 1869 1855 1841	0.8962 0.8896 0.8831 0.8766 0.8701	1105 1104 1104 1103 1102	.9050 .9058 .9058 .9066	1.0454 1.0485 1.0516 1.0548 1.0580	48.30 47.59 46.88 46.16 45.45
4000 4200 4400 4600 4300	6.792 6.751 6.710 6.670 6.630	0.8881 0.8828 0.8774 0.8722 0.8669	1828 1814 1801 1787 1774	0.8573 0.8573 0.8509 0.8446 0.8383	1101 1101 1100 1099 1098	.9083 .9083 .9091 .9099	1.0611 1.0643 1.0676 1.0708 1.0740	44.74 44.02 43.31 42.60 41.88
5000	6.590	0.8617	1761	0.8320	1098	.9107	1.0773	41.17
5200	6.550	0.8565	1748	0.8258	1097	.9115	1.0806	40.46
5400	6.510	0.8513	1735	0.8197	1096	.9123	1.0838	39.74
5600	6.471	0.8461	1722	0.8135	1095	.9132	1.0872	39.03
5800	6.431	0.8410	1709	0.8074	1094	.9141	1.0905	38.32
6000	6.392	0.8359	1696	0.8014	1094	.9141	1.0938	37.60
6200	6.353	0.9308	1683	0.7954	1093	.9149	1.0971	36.89
6400	6.315	0.8257	1670	0.7894	1092	.9158	1.1005	36.18
6600	6.276	0.8207	1658	0.7834	1091	.9166	1.1039	35.46
6800	6.238	0.8156	1645	0.7775	1090	.9174	1.1073	34.75

TABLE 5. (Cont'd)

lı ft	ρx10 ⁻² 1b/ft ³	ρ ρ.	ps lb/ft ²	Pso	C _s fps	Mach no.	u _t /u _i	T *F
7000	6.199	0.8106	1633	0.7716	1090	.9174	1.1107	34.04
7200	6.161	0.8057	1621	0.7658	1089	.9183	1.1141	33.32
7400	6.124	0.8007	1608	0.7600	1088	.9191	1.1177	32.61
7600	6.086	0.7958	1596	0.7542	1087	.9200	1.1210	31.90
7800	6.048	0.7909	1584	0.7485	1086	.9208	1.1245	31.18
8000	6.011	0.7860	1572	0.7428	1086	.9208	1.1279	30.47
8200	5.974	0.7812	1560	0.7371	1085	.9217	1.1314	29.76
8400	5.937	0.7763	1548	0.7315	1084	.9225	1.1349	29.04
8600	5.900	0.7715	1536	0.7259	1083	.9234	1.1385	28.33
8800	5.864	0.7667	1524	0.7203	1083	.9234	1.1409	27.62
9000	5.827	0.7620	1513	0.7148	1082	.9242	1.1456	26.91
9200	5.791	0.7572	1501	0.7093	1081	.9251	1.1492	26.19
9400	5.755	0.7525	1489	0.7039	1080	.9259	1.1528	25.48
9600	5.719	0.7478	1478	0.6984	1079	.9268	1.1564	24.77
9800	5.683	0.7431	1467	0.6931	1079	.9268	1.1600	24.05
10000	5.648	0.7385	1455	0.6877	1078	.9276	1.1637	23.34
10500	5.559	0.7269	1427	0.6745	1076	.9294	1.1729	21.56
11000	5.472	0.7156	1400	0.6614	1074	.9311	1.1822	19.77
11500	5.386	0.7043	1372	0.6486	1072	.9328	1.1916	17.99
12000	5.301	0.6932	1346	0.6360	1070	.9346	1.2011	16.21
12500	5.217	0.6822	1320	0.6236	1068	.9363	1.2107	14.42
13000	5.134	0.6713	1294	0.6113	1066	.9381	1.2205	12.64
13500	5.052	0.6061	1268	0.5993	1064	.9398	1.2304	10.86
14000	4.971	0.6500	1243	0.5874	1062	.9416	1.2403	9.07
14500	4.891	0.6396	1218	0.5758	1060	.9434	1.2504	7.29
15000	4.812	0.6292	1194	0.5643	1058	.9452	1.2606	5.51
15500	4.734	0.6190	1170	0.5531	1056	.9470	1.2710	3.73
16000	4.657	0.6090	1147	0.5420	1054	.9488	1.2814	1.94
16500	4.581	0.5990	1124	0.5411	1052	.9506	1.2921	.16
17000	4.506	0.5892	1101	0.5203	1050	.9524	1.3028	-1.63
17500	4.432	0.5795	1079	0.5098	1048	.9542	1.3137	-3.48
18000	4.358	0.5699	1057	0.4994	1046	.9560	1.3246	-5.19
18500	4.286	0.5604	1035	0.4892	1043	.9588	1.3358	-6.97
19000	4.215	0.5512	1014	0.4791	1041	.9606	1.3470	-8.76
19500	4.144	0.5419	993	0.4693	1029	.9625	1.3584	-10.54
20000	4.075	0.5328	972	0.4595	1037	.9643	1.3700	-12.32
22000	3.805	0.4976	894	0.4223	1029	.9718	1.4176	-19.46
24000	3.550	0.4642	820	0.3876	1021	.9794	1.4678	-26.59
28000	3.078	0.4025	688	0.3250	1004	.9960	1.5762	-40.85
30000	2.861	0.3741	628	0.2970	995	1.0050	1.6349	-47.99

C. BALLISTIC DRAG COEFFICIENT FUNCTIONS FOR VARIOUS BOMBS

Both numerical data and graphs are given to show the ballistic drag coefficient (K_D) functions for different bombs. By reference to Table 10, it may be noted that in several cases many bombs can be represented by the the same K_D curve; the value of c, the reciprocal ballistic coefficient, may be adjusted to match the various K_D curves if two bombs have the same general shape for their representative curves (see eq. 5).

In Table 6, K_D refers only to the ballistic drag coefficient. For comparison with other tables using the aerodynamic drag coefficient C_D , it should be recalled that:

$$K_{D} = \frac{\pi}{8} C_{D}$$

The various bombs are denoted by numbers; the numbering scheme is as follows:

Bomb No.	Description of Bomb or Type of KD Curve
1	Standard G1 drag function
2	Mk 83/2&3/E
3	Mk 76/062/N
4	Mk 76/4/T/L
5	Mk 76/4/T/N
6	HD-200 (fictitious)
7	Mk 43/0 (Nose Mk 43/1)/large fin
8	AN-M57A1 M126 fin
9	AM-M64A1 M128A1 fin

See paragraph F (page 85) for explanation of homb designation abbreviations.

Figure 19 provides in graphical form the same information as Table 6.

TABLE 6. Ballistic Drag Coefficient Functions

Mach			ninggingsom myssoffigmati kningstratidenstat	Bor	nb no.	vantianių rituralioseidantianių iš		TO SEE AND LONG TO SEE AND LONG TO SEE AND	Au-mania administration
no.	1	2	3	4	5	6	7	۶,	9
.00 .05 .10 .15	.1003 .0975 .0948 .0921	.0428 .0428 .0428 .0428	.0828 .0805 .0783 .0761	.095 .095 .095 .095	.079 .079 .079 .079 .079	.1066 .1066 .1066 .1066	.0647 .0647 .0647 .0647	.077 .077 .077 .077	.067 .067 .067 .067
.25 .30 .35 .40	.0895 .0869 .0846 .0826	.0428 .0428 .0428 .0428 .0428	.0739 .0718 .0699 .0682 .0669	.095 .095 .095 .095 .095	.079 .079 .079 .079 .079	.1066 .1066 .1066 .1066 .1066	.0647 .0647 .0647 .0647	.077 .077 .077 .077	.067 .067 .067 .067
.50 .55 .60 .65	.0799 .0794 .0799 .0816 .0850	.0428 .0428 .0428 .0428 .0428	.0660 .0656 .0660 .0674 .0702	.095 .097 .098 .0995 .1025	.079 .079 .080 .0815 .083	.1066 .1066 .1066 .1066	.0647 .0647 .0647 .0647	.U77 .U77 .U77 .U77	.067 .067 .167 .067
.75 .80 .82 .84 .86	.0908 .1000 .1048 .1106 .1174	.0428 .0428 .0429 .0434 .0451	.0750 .0826 .0866 .0914 .0970	.107 .113 .117 .121 .126	.0845 .087 .089 .091 .095	.1066	.0647 .0647 .0647 .0650 .0653	.077 .080 .081 .085	.067 .069 .072 .074
.88 .90 .91 .92	.1251 .1340 - .1438	.0479 .0527 - .0595	.1033 .1107 - .1188	.132 .140 .145 .151 .157	.100 .106 .110 .114 .119		.0658 .0662 - .0668	.094 .106 .117 .131 .143	.085 .094 .104 .118 .135
.94 .95 .96 .97	.1546 - .1660 - .1774	.0671 - .0756 - .0852	.1277	.165 .174 .183 .194 .205	,124 .130 .137 .144 .153		.0680 .0701 .0755	.162 .176 .193 .205 .220	.157 .175 .193 .211 .227
.99 1.00 1.01 1.02 1.05	.1885	.0958 - .1074 .1238	.1557 - - .1759	.217 .229 .240 .251 .277	.163 .175 .204 .224 .248		.0867 - .0985 .1067	.231 .240 .245 .249 .255	.242 .254 .263 .270 .282
1.10 1.15 1.25 1.50	.2308 .2430 .2559	.1307 .1326 .1387	.1906 .2007 .2114	.299 .313 .333 .356	.270 .285 .308 .332		.1100 .1112 .1112 .1067	.262 .267 .272 .277	.290 .295 .301 .306

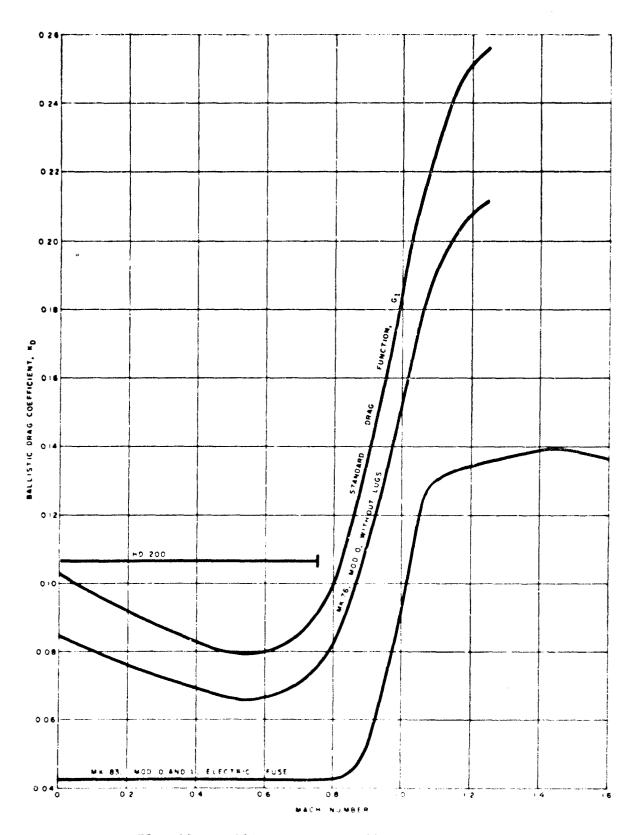


FIG. 19. Ballistic Drag Coefficient Tunctions.

D. BALLISTIC TABLES FOR THE MK 83, MY 76, AND HD-200 BOMBS

On the following pages, numerical data are given for the Mk 83/2&3/E (Table 7), the Mk 76/0&2/N (Table 8), and the fictitious retarded bomb. the HD-200 (Table 9).⁴ The following parameters are computed for femilies of release velocities, angles, and altitudes:

- X Ground range, feet
- R Slant range $(R^2 = X^2 + Z^2)$, feet
- Φ Line of sight or harp angle, degrees
- Y Ballistic lead angle, degrees
- t_f Time of flight, seconds
- Ψ_e Value of Ψ computed by working from computed parameters (the exact value of Ψ)
- 1r.Ψ. Logarithm of Ψ_α
- $\ln \Psi_{\rm C} = 2/3 \ {\rm cK_{\rm D}} \ {\rm K sec} \ \theta$ (to be compared with the exact value of $\ln \Psi_{\rm D}$)
- Impact angle, degrees
- Ui Impact velocity, feet per second
- OX Change in ground range caused by change of one degree in release angle, feet

⁴See page 85 for explanation of bomb designation notation and bomb data.

TABLE 7. Ballistic Data for the Mk 83 Mod 2&3/E

Z ft	X ft	R ft	get ф	γ der	t _f sec	$\Psi_{\mathbf{e}}$	ln∀ _e	ln4′c	'i der	U _i fps	ΔX ft
			U	o = 400	fps (9 = -40	deg				
5000 10000	3468 5529	6084.9 11426.7	55.25 61.06	15.25 21.06	11.447 18.3°5	1.014 1.023	1	.01174 .01604	64.05 70.40		80 115
			U	o = 400	fps $ heta$	= -2 0	deg				
1000 2000 3000 4000 5000 10000	1/66 2879 3761 4516 5184 7826	2029.5 3505.5 4810.9 6032.8 7202.4 12698.3	29.52 34.79 38.58 41.53 43.96 51.95	9.52 14.79 18.58 21.53 23.96 31.95	4.719 7.714 10.104 12.155 13.980 21.255	1.005 1.008 1.012 1.014 1.017 1.025	.00598 .00886 .01262 .01459 .01725	.00549 .00870 .01102 .01285 .01431	37.59 45.83 51.05 54.78 57.63 65.77	531 586 635 681	52 67 78 84 91 100
فقوا البراد والمستقد	<u> </u>		U	o = 400	fps θ	= -10	deg				
1000 2000 3000 4000 5000 10000	2363 3607 4569 5381 6096 8903	2565.9 4124.4 5465.9 6704.9 7884.2 13388.9	22.94 29.01 32.29 36.63 39.36 48.32	12.94 19.01 22.29 26.63 29.36 38.42	6.033 9.236 11.726 13.838 15.706 23.088	1.007 1.011 1.013 1.016 1.018 1.025	.00767 .01124 .01380 .01637 .01872 .02557	.00702 .01039 .01278 .01461 .01605 .02009	33.89 43.14 48.86 52.88 55.92 64.57	469 530 585 634 680 870	70 79 84 87 91 101
			U	o = 400	fps θ	= () de	eg.				
1000 2000 3000 4000 5000 10000	3139 4431 5419 6250 6981 9838	3294.4 4861.5 6194.0 7420.4 8586.9 14028.1	17.67 24.29 28.97 32.62 35.61 45.47	17.67 24.29 28.97 32.62 35.61 45.47	7.905 11.191 13.717 15.852 17.737 25.157	1.009 1.013 1.016 1.018 1.020 1.027	.00936 .01361 .01597 .01833 .02019 .02723	.00918 .01257 .01493 .01671 .01811 .02187	32.63 42.28 48.17 52.30 55.42 64.22	529 584 633 679	86 85 84 84 84 83
			U	o = 400	fps $ heta$	= 20 c	ieg				
1000 2000 3000 4000 5000 10000		5013.7 6335.9 7510.2 8616.7 9685.4 1480).2	11.51 18.40 23.54 27.66 31.08 42.47	31.51 38.40 43.54 47.66 51.08 62.47	13.216 16.213 18.602 20.653 22.482 29.755	1.014 1.017 1.029 1.021 1.023 1.028	.01440 .01755 .01990 .02176 .02333 .02830	.01528 .01816 .02013 .02171 .02290 .02584	37.95 46.20 51.41 55.12 57.95 65.90	527 582 632 678	t .

TABLE 7. (Cont'd)

Z ft	X ft	R ft	Ф deg	γ deg	t _f sec	$\Psi_{\mathbf{e}}$	ln¥ _e	^{lnΨ} c	ri deg	U ₁	ΔX ft
			υ	o = 600	fps θ	= -40	deg				
50 0 0 10000	4274 7152	6577.8 12294.4	49.48 54.43	9.48 14.43	9,418 15,980	1.016 1.026	.01617 .02625	.01447	56.43 63.15	809 969	113 168
			บ	o = 600	fps $ heta$	= -20	deg				
1000 2000 3000 4000 5000 10000	2119 3636 4880 5959 6925 10787	2343.1 4149.8 5728.4 7177.0 8541.4 14709.2	25.26 20.81 31.58 33.87 35.83 42.83	5.26 8.81 11.58 13.87 15.83 22.83	3.778 6.509 8.758 10.723 12.489 19.615	1.006 1.011 1.015 1.018 1.021 1.031	.00668 .01124 .01538 .01882 .02147 .03101	.00659 .01098 .01430 .01695 .01911 .02551	30.14 36.45 41.01 44.56 47.43 56.52	645 688 729 767 804 964	79 111 131 145 157 194
			บ	o = 600	fps $ heta$	= -10	der,				
1000 2000 3000 4000 5000 10000	3114 4921 6333 7532 8590 12753	4370.6 5311.9 7007.6 8528.3 9939.2 16206.1	17.80 22.12 25.35 27.97 30.20 38.10	7.80 12.12 15.35 17.97 20.20 28.10	5.307 8.422 10.874 12.965 14.821 22.178	1.009 1.014 1.019 1.022 1.025 1.034	.00916 .01469 .01892 .02196 .02489 .03382	.00924 .01418 .01771 .02045 .02262 .02878	25.05 32.63 37.85 41.81 44.98 54.80	643 685 726 764 801 962	164
			U	o = 600	fps $ heta$	= 0 de	eg.				
1000 2000 3000 4000 5000 10000	4698 6626 8099 9337 10426 14684	4803.3 6921.3 8636.8 10157.7 11562.9 17765.7	12.02 16.80 20.33 23.19 25.62 34.26	12.02 16.80 20.33 23.19 25.62 34.26	7.913 11.207 13.741 15.881 17.773 25.215	1.013 1.019 1.023 1.026 1.029 1.037	.01380 .01921 .02323 .02645 .02898 .03720	.01373 .01880 .02231 .02496 .02704 .03264	23.21 31.38 36.88 41.00 44.27 54.34	639 682 722 761 798 959	194 192 189 189 188 185
		<u> </u>	U	o = 600	fps θ	= 20 d	leg				
2000 3000 4000 5000 10000	10593 11810 12868 13318	9165.7 10780.2 12185.1 13475.0 14694.8 20272.1	6.26 10.69 14.25 17.27 19.89 29.56	26.26 30.69 34.25 37.27 39.89 49.56	16.492 19.280 21.486 23.453 25.224 32.433	1.027 1.031 1.034 1.036 1.037 1.043	.02713 .03072 .03343 .03566 .03730 .04239	.02835 .03200 .03462 .03661 .03814 .04171	41.80 45.33 48.19	675 717 756	175 154

TABLE 7. (Cont'd)

-				,							
Z ft	X ft	R ft	φ deg	γ deg	t _f sec	$\Psi_{\mathbf{c}}$	ln¥ _e	lnΨ _c	ri deg	U _i fps	ΔX it
			U	o = 800	fps 6	= -40	deg				
5000 10000	4774 8297	6913.1 12993.9	46.32 50.32	6.32 10.32	7.898 13.879	1.018 1.030	.01823 .02985	.01616 .02409	51.55 57.78	957 1079	
			บ	o = 800	pfs 6	= -20	deg				
1000 2000 3000 4000 5000 10000	2323 4138 5677 7035 8263 13241	2529.1 4596.0 6420.9 8092.7 9658.0 16592.9	23.29 25.30 27.85 29.62 31.18 37.06	3.29 5.80 7.85 9.62 11.18 17.06	3.107 5.560 7.654 9.513 11.205 18.161	1.006 1.013 1.017 1.021 1.025 1.038	.00578 .01321 .01764 .02157 .02489 .03739	.00723 .01250 .01664 .02001 .02281 .03132	26.46 31.14 34.84 37.88 40.46 49.38	830 861 891 920 948 1069	150 182 206 225
			U	o = 800	pfs 6	= -10	deg				
1000 2000 3000 4000 5000 10000	3670 5984 7819 9385 10772 16245	(15.24 18.43 20.99 23.08 24.90 31.62	5.24 8.48 10.99 13.08 14.90 21.62	4.697 7.699 10.099 12.161 13.998 21.340	1.010 1.018 1.023 1.027 1.031 1.043	.01084 .01794 .02293 .02693 .03053 .04239	.01089 .01724 .02187 .02548 .02837 .03667	20.29 26.34 30.80 34.35 37.30 47.17	826 855 885 914 942 1064	225 257 272 283
			ט	o = 800	pfs 8	= 0 de	eg				
1000 2000 3000 4000 5000 10000	6250 8808 10759 12399 13841 19473	9032.2 11169.4 13028.2 14716.4	9.90 12.79 15.58 17.88 19.86 27.18	9.90 12.79 15.58 17.88 19.86 27.18	7.923 11.225 13.765 15.913 17.811 25.301	1.018 1.025 1.031 1.035 1.038 1.049	.01833 .02528 .03063 .03450 .03758 .04803	.01827 .02500 .02964 .03315 .03590 .04328	17.90 24.71 29.54 33.32 36.41 46.62	817 846 876 906 934 1059	339 335 332 331
			ប	o = 800	nfs θ	= 20 c	leg				
2000 3000 4000	16312 17796 19113 20312	19527.1 20918.3	3.93 6.99 9.57 11.82 13.83 21.64	23.93 26.99 29.57 31.82 33.83 41.34	20.002 22.476 24.579 26.448 28.150 35.110	1.043 1.047 1.051 1.053 1.055 1.060	.04296 .04679 .05003 .05221 .05373 .05883	.04530 .04927 .05218 .05438 .05607 .05961	27.48 32.32 36.08 39.15 41.73 50.46	794 828 860 892 923 1055	345

TABLE 7. (Cont'd)

Z ft	X ft	R ft	ф deg	γ deg	t _f sec	Ψe	ln¥e	lnΨ _C	r _i deg	U _i fps	ΔX ft
	<u></u>	<i></i>	·	U ₀ = 1	000 fps	θ = -	-40 deg		<u> </u>	<u> </u>	
5000 10000	5089 9070	7134.3 13500.6	44.49 47.79	4.49 7.79	6,794 12,426	1.028 1.060	.02761 .05779	.02259 .03892	48.52 54.22	1099 1164	
				U _o = 1	000 fps	θ = -	-20 deg				
1000 2000 3000 4000 5000 10000	2446 4475 6241 7823 9265 15145	2642.5 4901.6 6924.6 8786.3 10528.1 18148.6	22.24 24.08 25.67 27.08 28.35 33.44	2.24 4.08 5.67 7.08 8.35 3.44	2.622 4.829 6.776 8.543 10.176 17.095	1.007 1.018 1.027 1.034 1.041 1.074	.01745	.00937 .91664 .02338 .02902 .03352 .05298	24.44 28.00 30.99 33.59 35.89 44.59	1017 1034 1050 1066 1081 1143	180 227 261 288
				U _o = 1	000 fps	θ = -	10 deg			<u> </u>	
1000 2000 3000 4900 5000 10000	4081 6834 9046 10941 12620 19196	4201.7 7120.6 9530.5 11649.3 13574.4 21644.5	13.77 16.31 18.35 20.08 21.61 27.52	3.77 6.31 8.35 10.08 11.61 17.52	4.191 7.076 9.431 11.477 13.316 20.797	1.015 1.026 1.035 1.043 1.050 1.082	.01499 .02586 .03450 .04201 .04917 .07909	.01491 .02425 .03234 .03872 .04357 .06408	17.48 22.37 26.23 29.42 32.16 42.07	1009 1023 1038 1054 1069 1132	249 320 357 380 397 443
				U _o ≈ 1	000 fps	0 = C	deg				
1000 2000 3000 4000 5000 10000	7778 10940 13343 15355 17115 23889	7842.0 11121.3 13676.1 15867.5 17830.4 25897.6	7.33 10.36 12.67 14.60 16.29 22.71	7.33 10.36 12.67 14.60 16.29 22.71	7.940 11.256 13.819 15.991 17.918 25.608	1.028 1.039 1.048 1.055 1.061 1,089	.02713 .03807 .04641 .05316 .05931 .08554	.02800 .03823 .04698 .05352 .05819 .07854	14.62 20.45 24.74 28.20 31.13 41.51	992 1007 1023 1040 1056 1125	536 523 515 510 507 503
				U _o = 1	000 fps	θ = 2	0 deg				
1000 2000 3000 4000 5000 10000	23049 24729 26242 27630	21145.7 23135.6 24910.3 26545.1 28078.8 34817.0	2.71 4.96 6.92 8.67 10.26 16.69	22.71 24.96 26.92 28.67 30.26 36.69	23.602 25.840 27.797 29.568 31.202 38.075	1.069 1.073 1.077 1.080 1.083 1.093	.06663 .07083 .07437 .07715 .07937 .08856	.08092 .08573 .09267 .09735 .09998 .11660	25.88 29.63 32.71 35.34 37.63 46.06	f	566 523

TABLE 8. Ballistic Data for the Mk 76 Mod 082/W

Z f t	X ft	R ft	φ deg	γ deg	t _f sec	$\Psi_{ m e}$	lnΨ _e	$1 \text{n} \Psi_{\text{C}}$	7i deg	U _i fps	ΔX ft
				v _o = 40	00 fps	0 = -4(O deg				
5000 10000	1	6048.7 11338.8	55.75 61.88	15.75 21.88	11.303 19.231	1.080 1.127	.07678 .11943	1	65.14 72.00	637 781	78 110
$U_0 = 400 \text{ fps}$ $\theta = -20 \text{ deg}$											
1000 2000 3000 4090 5000 10000	2839 3689 4407 5038	2019.0 3472.7 4754.9 5951.6 7098.0 12492.8	29.69 35.16 39.12 42.23 44.78 53.17	9.69 15.16 19.12 22.23 24.78 33.17	4.780 7.859 10.337 12.480 14.401 22.174	1.032 1.053 1.070 1.084 1.096 1.139	.03169 .05202 .06728 .08020 .09130 .13059		38.07 46.78 52.36 56.36 59.41 68.11	454 505 551 592 629 755	51 66 74 70 85 102
		<u> </u>		v _o = 40	0 fps	θ = -10) deg				
1000 2000 3000 4000 5000 10000	3535	2540,1 4061,6 5366,8 6571,6 7720,0 13099,2	23.18 29.50 33.99 37.49 40.37 49.77	13.18 19.50 23.99 27.49 30.37 39.77	6.110 9.401 11.981 14.186 16.149 24.027	1.041 1.063 1.079 1.093 1.105 1.146	.03989 .06081 .07613 .08902 .09975 .13663	.03839 .05643 .06885 .07818 .08557 .10510	34.64 44.46 50.56 54.85 58.10 67.25	450 500 546 588 625 772	67 74 78 81 83 91
				ບ _ດ = 40	O fps	θ = 0 σ	leg				
1000 2000 3000 4000 5000 10000	3074 4303 5230 6004 6678 9285	3232.6 4745.1 6029.3 7214.4 8342.4 13645.9	18.02 24.93 29.84 33.67 36.82 47.12	18.02 24.93 29.84 33.67 36.82 47.12	7.990 11.365 13.980 16.207 18.187 26.101	1.053 1.074 1.091 1.105 1.115	.05117 .07167 .08691 .09966 .10894 .14297	.04978 .06765 .07969 .08865 .09567	33.76 44.03 50.30 54.67 57.97 67.19	444 495 542 584 622 770	81 78 77 75 75 72
				u _o = 40	O fps	θ = 20	deg				
1000 2000 3000 4000 5000 10000	4683 5704 6506 7189 7793 10173	4788.6 6044.5 7164.4 8226.9 9259.1 14265.0	12.05 19.32 24.76 29.09 32.68 44.51	32.05 39.32 44.76 49.09 52.68 (4.51	13,230 16,319 18,799 20,944 22,868 30,638	1.083 1.100 1.114 1.124 1.133 1.163	.07983 .09558 .10769 .11725 .12513 .15092	.03070 .09543 .10550 .11290 .11880 .13250	40.02 48.77 54.23 58.08 61.00 69.16	434 489 537 580 619 770	68 51 42 35 29 8

TABLE 8. (Cont d)

Z f t	X ft	R ft	φ deg	γ deg	t f sec	$\Psi_{\mathbf{e}}$	lnΨ _e	lnΨ _c	ri deg	Ui fps	ΔX ft
U _o = 600 fps						θ = -	40 deg				
5000 10000	•		49.92 55.31	9.92 15.31	9.788 16.839	1.090 1.149	.08572 .13880	.07439	57.55 65.21	741 842	109 159
				Uo = 6	00 fps	0 = -2	20 deg				
1000 2000 3000 4000 5000 10000	3591 4788 5814 6721	4110.4 5650.2 7057.1 8376.9	25.38 29.12 32.07 34.53 36.65 44.26	5.38 9.12 12.07 14.53 16.65 24.26	3.840 6.668 9.028 11.105 12.988 20.722	1.035 1.062 1.084 1.101 1.117	.03440 .06006 .08047 .09649 .11082 .16152	.03429 .05671 .07328 .08622 .09686 .12690	30.50 37.33 42.38 46.34 49.57 59.83	620 645 671 697 722 826	78 107 124 135 145 173
				v _o = 6	00 fps	$\theta = -1$	gob 0.				
1000 2000 3000 4000 5000 10000	4811 6143 7258	3233.5 5210.2 6836.4 4905.0 9631.5 15610.5	18.01 22.57 26.03 28.86 31.27 39.84	8.01 12.57 16.03 18.86 21.27 29.84	5.401 8.629 11.196 13.402 15.373 23.333	1.051 1.080 1.102 1.121 1.137 1.191	.04955 .07687 .09749 .11395 .12795	.04773 .07250 .08972 .10270 .11320 .14140	25.72 34.02 39.83 44.27 47.32 58.79	711	124 141 150 154 158 169
				U _O = 6	00 fps	0 = 0	deg				
1000 2000 3000 4000 5000 10000	4564 6367 7720 8846 9828 13613	4672.3 6673.7 8282.4 9708.3 11026.8 16891.2	12.36 17.44 21.24 24.33 26.96 36.30	12.36 17.44 21.24 24.33 26.96 36.30	8.028 11.435 14.801 16.334 18.339 26.370	1.104 1.127 1.144 1.158	.07167 .09903 .11912 .13444 .14704 .18863	.06976 .09449 .11100 .12320 .13300 .15820	24.45 33.51 39.65 44.25 47.89 58.94	617 645 673	161 158
				U _o = 60	00 fps	θ = 20	deg				
4000	12530	8413.6 9894.5 11169.4 12358.2 13490.8 18775.6	6.83 11.67 15.58 18.89 21.75 32.18	26.83 31.67 35.58 38.89 41.75 52.18	16.373 19.238 21.613 23.698 25.565 33.311	1.165 1.181 1.193 1.203	.15255 .16602 .17664 .18507	.13590 .15280 .16460 .17340 .18050 .19650	33.89 41.07 46.14 49.99 53.05 62.37	626	166 135 116 103 92 59

TABLE 8. (Cont'd)

Z ft	X	R ft	φ deg	γ deg	t _f sec	Ψe	lny _e	în¥c	ři deg	U _i fps	ΔX ft	
				υ _ο = 8	000 fps	= -4	40 deg					
5000 10000	1		46.75 51.33	6.75 11.33	8.322 15.072	1.111 1.198	.10517 .18057	.09266 .13690	52.73 60.41	852 894	132 199	
U _o = 800 fps = -20 deg												
1000 2000 3000 4000 5000 10000	4088 5564 6845 7986	4551.0 6321.2 7928.1 9422.1	23.39 26.07 28.33 30.30 32.05 38.77	3.39 6.07 8.33 10.30 12.05 18.77	3.174 5.751 7.985 9.995 11.841 19.593	1.042 1.077 1.106 1.131 1.153 1.239	.04085 .07371 .10093 .12319 .14245 .21414	.04121 .07105 .09425 .11230 .12820 .17360	26.76 31.98 36.26 39.86 42.96 53.83	790 791 798 807 818 870	171 190 204	
	U _o = 800 fps = -10 deg											
1000 2000 3000 4000 5000 10000	5827 7533 8961 10207	3755.6 6160.7 8108.4 9813.2 11365.9 18006.1	15.44 18.94 21.71 24.06 26.10 33.74	5.44 8.94 11.71 14.06 16.10 23.74	4.815 7.970 10.525 12.739 14.729 22.833	1.065 1.105 1.137 1.163 1.185 1.267	.06288 .10003 .12813 .15083 .16991 .23626	.06158 .09663 .12170 .14090 .15640	20.93 27.82 33.06 37.30 40.83 52.69	768 766 773 784 796 858	215 229 237 243	
				u _o = 8	00 fps	= 0	deg					
	12749	6080.8 8562.8 10498.7 12173.9 13694.4 20185.2	9.47 13.51 16.60 19.18 21.41 29.70	9.47 13.51 16.60 19.18 21.41 29.70	3.082 11.532 14.215 16.506 18.548 26.750	1.106 1.148 1.179 1.204 1.224 1.294	.10057 .13785 .16475 .18540 .20196 .25774	.10040 .13590 .16010 .17810 .19230 .22980	19.33 27.27 33.00 37.50 41.19 53.14	731 733 744 758 774 849	305 287 276 268 262 249	
		ومناورة والأوارة والأوارة		U _o = 8	00 fps	= 20	deg	والكار المراوا مرور والمراكم وا				
2000 3000 4000 5000	14119 15381 16496 17507	12656.6 14259.9 15670.8 16974.0 18207.0 23846.1	4.53 8.06 11.04 13.63 15.94 24.79	24.53 28.06 31.04 33.63 35.94 44.79	19.558 22.208 24.466 26.486 28.338 36.025	1.234 1.258 1.277 1.292 1.303 1.340	.21034 .22960 .24436 .25580 .26498 .29289		31.73 37.58 42.02 45.57 48.51 58.05	654 678 703 728 751 845	241 214 194 179	

TABLE 8 (Cont'd)

Z ft	X ft	R ft	deg	Y deg	t _f sec	ę	ln∀ _e	ln"c	τ _i deg	U ₁ fps	ΔX ft	
	32			u _o = 10	000 fps	0 = -	40 deg				Caparaments and	
5000 10 000		7069.7 13241.7	45.01 49.04	5.01 9.04	7.365 13.912	1.177	.16322 .27406	.15550 .24610	49.96 57.46	933 936	139 228	
$U_0 = 1000 \text{ fps}$ $\theta = -20 \text{ deg}$												
1000 2000 3000 4000 5000 10000	4405 6076 7537 8843	2629.6 4837.8 6776.3 8532.7 10158.7 17144.5	22.35 24.42 26.28 27.96 29.48 35.68	2.35 4.42 6.28 7.96 9.48 15.68	2.717 5.108 7.262 9.240 11.082 18.950	1.066 1.122 1.172 1.214 1.250 1.396	.06354 .11529 .15905 .19425 .22346 .33347	.06642 .11800 .16030 .19500 .22430 .32190	24.78 29.03 32.80 35.16 39.16 50.44	940 909 892 924 879 891	171 208	
	<u> </u>	<u> </u>	<u></u>	U _o = 10	000 fps	$\theta = -1$	10 deg	L				
1000 2000 3000 4000 5000 10000	6569 8556 10211 11649	4126.0 6866.7 9066.7 10966.5 12676.7 19790.4	14.03 16.93 19.32 21.39 23.23 30.35	4.03 6.93 9.32 11.39 13.23 20.35	4.378 7.499 10.073 12.320 14.354 22.682	1.107 1.176 1.228 1.272 1.309 1.445	.10138 .16212 .20555 .24043 .26911 .36783	.10430 .16800 .21540 .25210 .28200 .37670	18.30 24.36 29.27 33.39 36.34 49.44	851 847 848	232 281 300 311 316 331	
				U _o = 10	00 fps	θ = 0	deg					
1000 2000 3000 4000 5000 10000	13607 15032	7305.8 10152.0 12328.6 14182.8 15841.7 22741.6	7.87 11.36 14.05 16.38 18.40 26.09	7.87 11.36 14.08 16.38 18.40 26.09	8.183 11.695 14.428 16.764 18.350 27.261	1.187 1.255 1.304 1.343 1.376 1.490	.17134 .22714 .26559 .29491 .31882 .39211	.18570 .25060 .29650 .33090 .35840 .44360	16.64 24.00 29.49 33.92 37.65 50.23	811 808 811	434 400 381 367 358 336	
			1	u _o = 10	00 fps	θ = 20	deg					
2000 3000 4000 5000	18082 19433 20639 21735	16549.2 18192.3 19663.2 21023.0 22302.7 28169.7	3.46 6.31 8.78 10.97 12.96 20.79	23.46 26.31 28.78 30.97 32.96 40.79	22.289 24.770 26.937 28.900 30.713 38.375	1.441 1.464 1.483 1.500	.36513 .38124 .39494 .40553	.45110 .48460 .51280 .53410 .55150 .60870	31.67 36.69 40.66 43.94 46.73 56.14	732 752 771 789	385 338 307 284 266 216	

TABLE 9. Ballistic Data for the HD-200

Z ft	X ft	R ft	φ deg	γ deg	t sec	Ψ _e	lnΨ _e	lr.Ψ _c	'i deg	U _i fps	ΔX ft	
	$v_o = 400 \text{ fps}$ $\theta = -20 \text{ deg}$											
100 200 300 400 500 1000	252 461 635 780 904 1315	271.1 502.5 702.3 876.6 1033.1 1652.0	21.64 23.45 25.25 27.15 28.95 37.25	1.64 3.45 5.29 7.15 8.95 17.25	.749 1.511 2.265 2.999 3.711 6.922	1.145 1.331 1.500 1.676 1.837 2.648	.13540 .28601 .40560 .51641 .60835 .97380	.1453 .2650 .3640 .4458 .5152 .7385	27.73 32.25 36.88 41.45	329 282 251 230 216 192	12 19 22 24 24 24	
$U_{o} = 400 \text{ fps}$ $\theta = -10 \text{ deg}$												
100 200 300 400 500 1000	429 698 888 1036 1155 1532	440.5 726.1 937.3 1110.5 1258.6 1829.5	13.12 15.99 18.67 21.11 23.41 33.13	3.12 5.99 8.67 11.11 13.41 23.13	1.309 2.405 3.357 4.215 5.008 8.350	1.277 1.523 1.754 1.953 2.143 3.000	.24412 .42068 .56213 .66947 .76211 1.09851	.2360 .3829 .4857 .5650 .6281 .8209	24.28 31.14 37.44	287 239 214 200 192 185	27 29 29 27 25 20	
				v _o = 40	00 fps	θ = 0	deg					
100 200 300 400 500 1000	787 1024 1183 1303 1400 1715	793.3 1043.4 1220.5 1363.0 1486.6 1985.3	7.24 11.05 14.23 17.07 19.65 30.25	7.24 11.05 14.23 17.07 19.65 30.25	2.706 4.017 5.014 5.882 6.669 9.959	1.606 1.897 2.132 2.343 2.537 3.382	.47362 .64027 .75711 .85152 .93106 1.21835	.5532 .6373 .6998 .7497	36.51 43.30	219 193 182 177 176 182	43 33 28 25 22 15	
				u _o = 40	0 fps	0 = 2 0	deg					
100 200 300 400 500 1000	1436 1525 1599 1661 1715 1910	1439.5 1538.1 1626.9 1708.5 1786.4 2156.0	3.98 7.47 10.63 13.54 16.25 27.63	23.98 27.47 30.63 33.54 36.25 47.63	7.415 8.266 9.032 9.742 10.410 13.402		.97528 1.04781 1.10843 1.16246 1.21102 1.40634		52.00 57.04 61.06	155 159 163 167 171 185	17 14 11 9 7 3	

TABLE 9. (Cont'd)

-		-		-		T		T		***************************************	~	
Z. ft	X ft	R ft	φ deg	y deg	t _f sec	$\Psi_{\mathbf{e}}$	$\ln \Psi_{ m e}$	ln ψ_c	'i deg	U _i fps	ΔX ft	
$v_o = 600 \text{ fps}$ $\theta = -20 \text{ deg}$												
100 200 300 400 500 1000	263 502 713 897 1057 1591	281.4 540.4 773.5 982.1 1169.3 1879.2	20.82 21.72 22.82 24.03 25.32 32.15	.82 1.72 2.82 4.03 5.32 12.15	.525 1.116 1.753 2.417 3.096 6.334	1.222 1.356 1.574 1.806 2.039 3.286	.30417 .45349 .59089 .71246	.2886 .4087 .5127 .6024	21.69 23.99 26.90 30.31 34.17 53.12	398 337 294	14 23 30 33 34 32	
		10,712		= 600	<u> </u>	<u> </u>		.0333	33.12	202		
100 200 300 400 500 1000	487 833 1085 1277 1429 1896	497.2 856.7 1125.7 1338.2 1514.0 2143.6	11.60 13.50 15.46 17.39 19.28 27.80	1.60 3.50 5.46	1.011 2.032 2.984 3.868	1.293 1.662 2.004 2.327 2.636 4.019	.50772 .69500 .84449 .96930	.2679 .4570 .5935 .6965 .7771	13.78 18.94 24.64 30.54 36.37 57.98	404 309 260 231 212 188	38 46 45 43 39 28	
			v _o	- 6 00	fps θ	= 0 de	28					
100 200 300 400 500 1000	1070 1357 1547 1636 1794 2148	1074.7 1371.7 1575.8 1732.8 1862.4 2369.4	5.34 8.38 10.97 13.35 15.57 24.96	5.34 8.38 10.97 13.35 15.57 24.96	2.853 4.158 5.189 6.085 6.894 10.249	1.955 2.431 2.805 3.149 3.477 4.850	.67019 .88810 1.03147 1.14708 1.24605 1.57902	.5798 .7331 .8333 .9056 .9607	14.65 24.41 32.46 39./3 45.51 64.44	256 213 195 186 181 182	71 52 42 37 32 21	
			t'o	= 600	fps $ heta$	= 20 c	leg					
100 200 300 400 500 1000	1963 2040 2107 2164 2215 2404	1965.6 2049.8 2128.3 2200.7 2270.7 2603.7	2.92 5.60 8.10 10.47 12.71 22.59	28.10	8.903 9.674 10.388 11.060 11.702 14.630	4.177 4.475 4.749 5.012 5.261 6.411	1.42952 1.49857 1.55789 1.61172 1.66031 1.8503	1.131 1.172 1.207 1.236 1.262 1.350	50.80 55.93 60.05 63.44 66.28 75.56	161 164 168 171 175 187	18 15 9 10 8 3	

TABLE 9. (Cont'd)

Z ft	X ft	R ft	φ deg	γ deg	t _f sec	$\Psi_{\mathbf{e}}$	lnψ _e	ln ψ_{c}	ri dog	U _i fps	ΔX ft		
	$v_o = 800 \text{ fps}$ $\theta = -20 \text{ deg}$												
100 200 300 400 500 1000	268 520 752 962 1149 1786	286.0 557.1 809.6 1041.9 1253.1 2046.9	20.46 21.04 21.75 22.58 23.52 29.24	.46 1.04 1.75 2.58 3.52 9.24	.401 .875 1.413 2.002 2.631 5.845	1.201 1.395 1.634 1.893 2.177 3.854	.18340 .33268 .49072 .63800 .77776 1.34914	.1545 .2939 .4311 .5498 .6548 1.003	20.98 22.40 24.34 25.84 29.91 48.22	517 427	15 27 35 40 43 40		
$v_o = 600 \text{ fps } \theta = -10 \text{ deg}$													
100 200 300 400 500 1000	515 917 1219 1450 1032 2169	524.6 938.6 1255.4 1504.2 1700.9 2388.4	10.99 12.30 13.83 15.42 17.03 24.75	.99 2.30 3.83 5.42 7.03 14.75	.813 1.741 2.676 3.517 4.413 7.994	1.337 1.758 2.209 2.649 2.075 5.065	.29058 .56406 .79236 .97403 1.12317 1.62230	.2833 .5030 .6668 .7908 .8875	12.32 16.09 20.88 26.28 31.81 54.86	524 380 304 259 231 190	46 60 60 56 49		
				u _o = 8	00 fps	0 = 0	deg						
100 200 300 400 500 1000	1307 1628 1835 1985 2100 2477	1310.8 1640.2 1859.4 2024.9 2158.7 2671.2	4.38 7.00 9.29 11.39 13.39 21.93	4.38 7.00 9.29 11.39 13.39 21.98	2.923 4.263 5.318 6.230 7.053 10.445	2.329 3.002 3.545 4.039 4.511 6.484	.84540 1.09931 1.26540 1.39592 1.50643 1.36937	.7082 .8796 .9885 1.066 1.124 1.307	13.02 22.45 30.46 37.52 43.75 63.40	279 225 202 191 184 183	97 68 54 46 40 25		
				u _o = 8	00 fps	0 = 2 0) deg						
100 200 300 400 500 1000	2355 2425 2485 2538 2586 2768	2357.1 2433.2 2503.0 2569.3 2633.9 2943.1	2.43 4.71 6.83 8.96 10.94 19.86	22.43 24.71 26.88 28.96 30.94 39.86	9.954 10.677 11.358 12.006 12.629 15.509	6.063 6.467 6.852 7.219 7.571 9.204	1.80218 1.86676 1.92454 1.97678 2.02432 2.21968	1.358 1.394 1.424 1.450 1.473 1.554	54.93 59.20 62.71 65.64 68.14 76.50	165 168 171 175 177 188	18 14 12 10 8 2		

E. BALLISTIC CURVES AND SENSITIVITY GRAPHS

In this section are given graphs (Fig. 20 through 44) showing the curves of ground range X, time of flight t_f , impact angle τ_i , impact velocity U_i , and lead angle γ , all plotted against release altitude for a family of release velocities, at three release angles, for the Mk 83, Mk 76, and the fictitious HD-200 bom's.

Also included are a number of sensitivity curves for the same bombs and the same release conditions. These curves show the change in the specified trajectory parameter caused by an incremental change in one of the independent release variables 2, $\rm U_{\rm O},~\theta$, or $\rm cK_{\rm D}.$ They are of value, for example, in quickly estimating the effects on the trajectory of errors in the release conditions and are useful in various other applications. The figures 400, 600, 800, and 1,000 on the curves refer to release velocity in feet per second.

However, in some applications, the curves must be used rather carefully since they were obtained by varying in a small amount each of the independent release variables Z, θ , U_0 , and cK_D , in turn from a given set of "standard" release conditions. Thus, the curves show only the change in the trajectory caused by a slight change in a single release variable. In analyzing many fire control systems, account rust also be taken of the specific system mechanization and of the method of aiming before data points of the curves can be applied correctly.

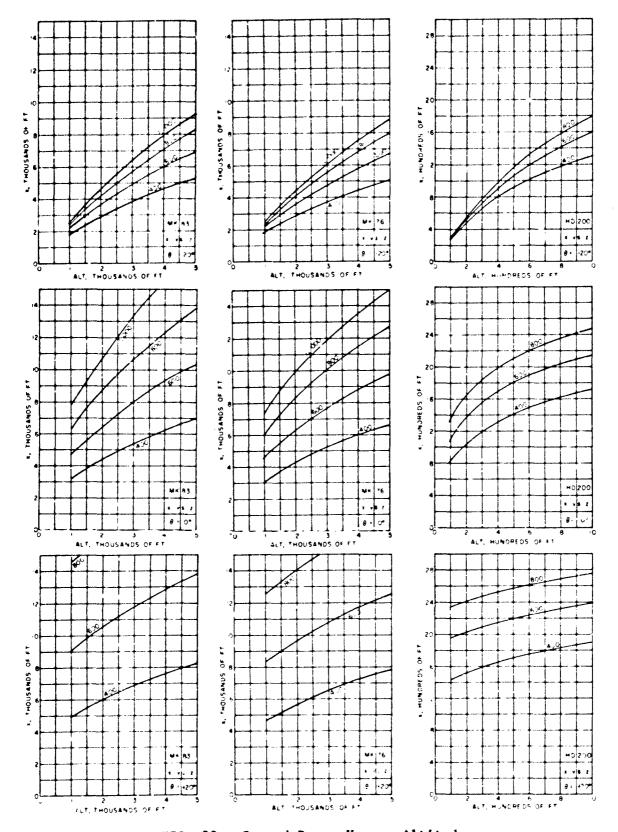


FIG. 20. Ground Range Versus Altitude.

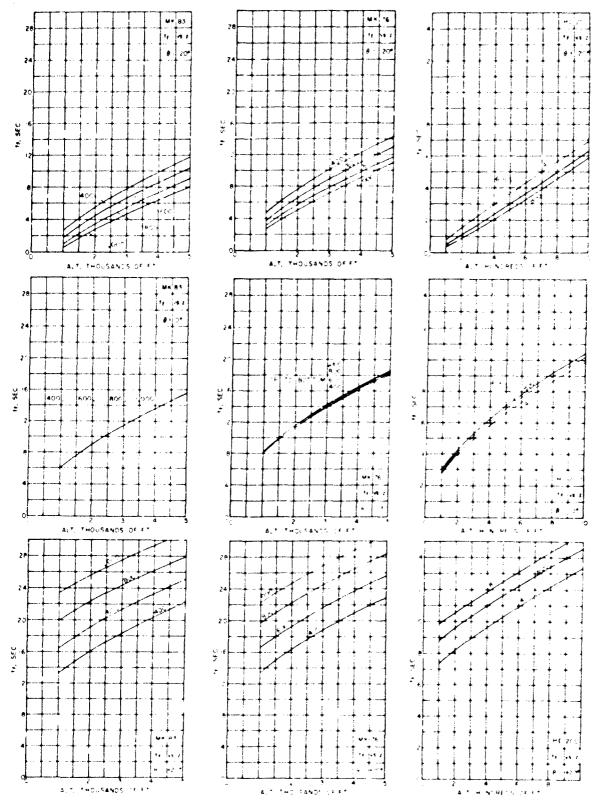


FIG. 21. Time of Flight Versus Altitude.

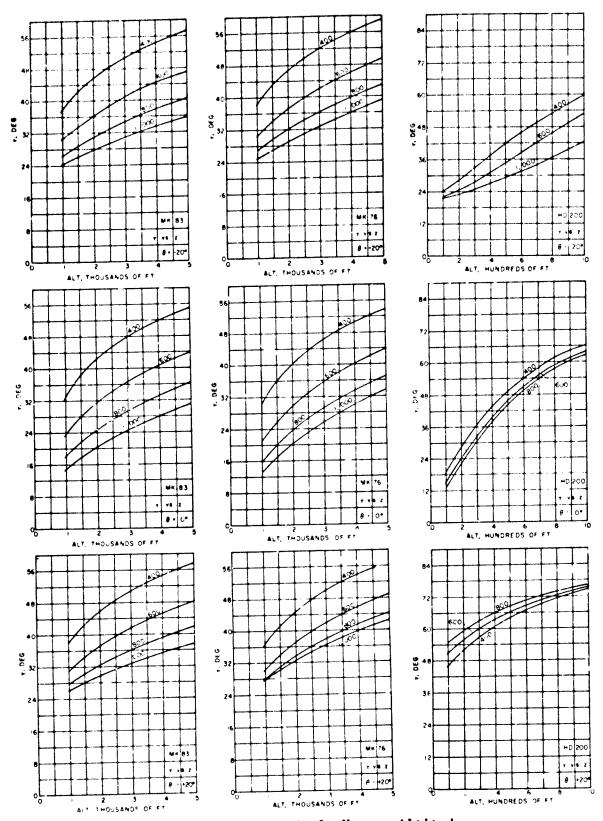


FIG. 22. Impact Angle Versus Altitude.

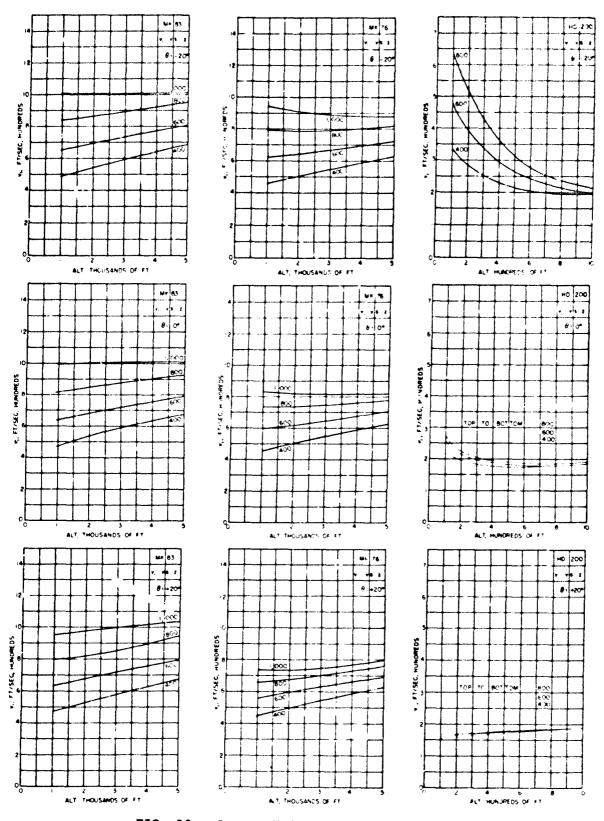


FIG. 23. Impact Velocity Versus Altitude.

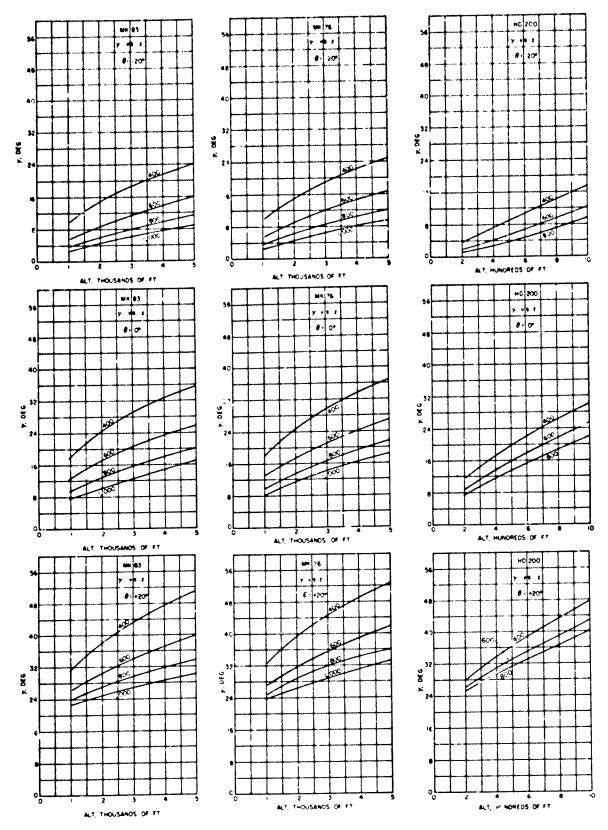


FIG. 24. Lead Angle Versus Altitude.

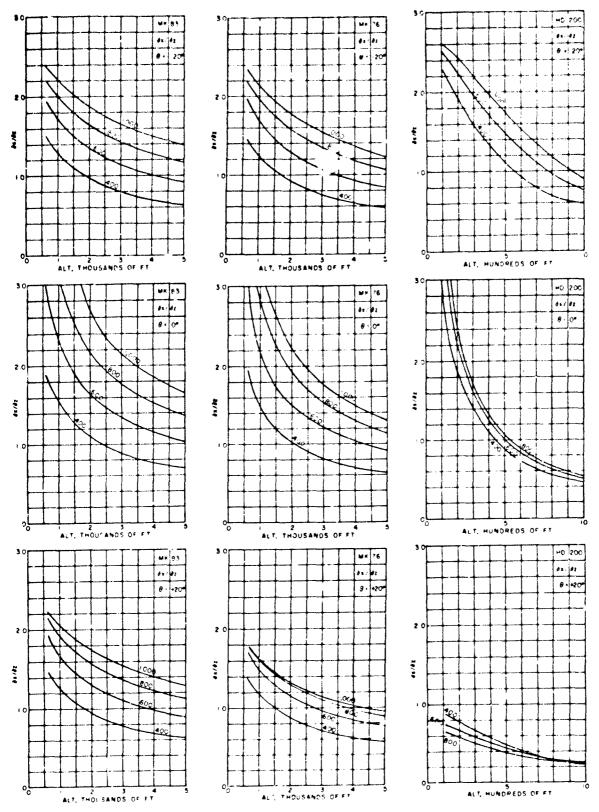


FIG. 25. Ground Range Sensitivity to Altitude Change Versus Altitude.

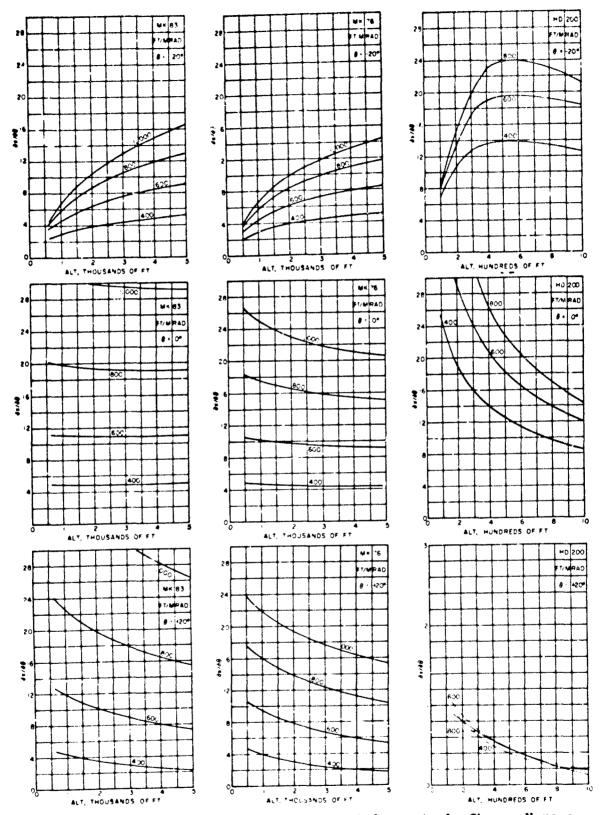
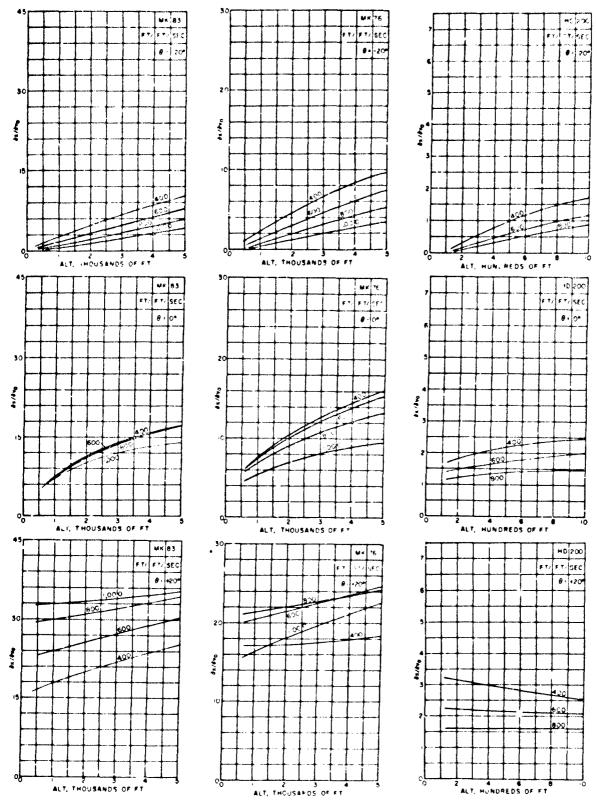


FIG. 26. Ground Range Sensitivity to Release Angle Change Versus Altitude.



FIC. 27. Ground Range Sensitivity to Release Velocity Change Versus Altitude.

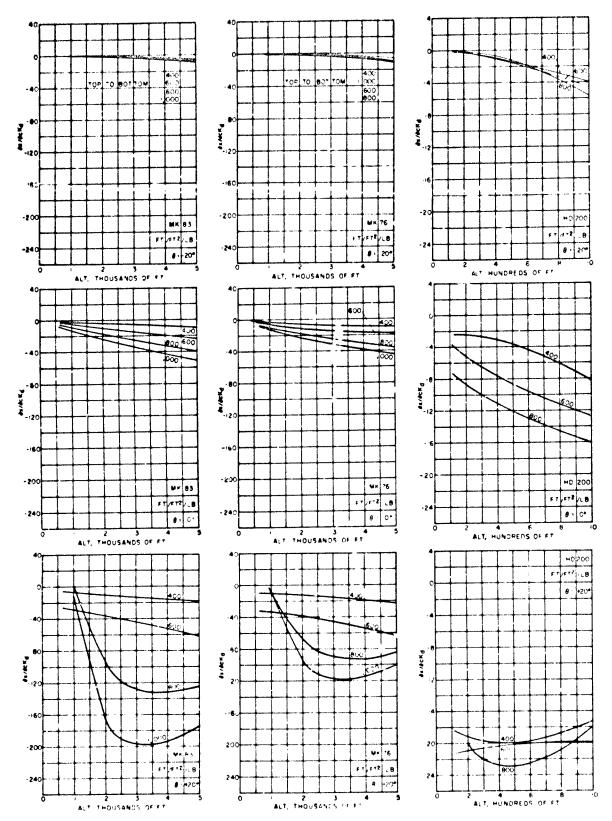


FIG. 28. Ground Range Sensitivity to Drag Function Change Versus Altitude.

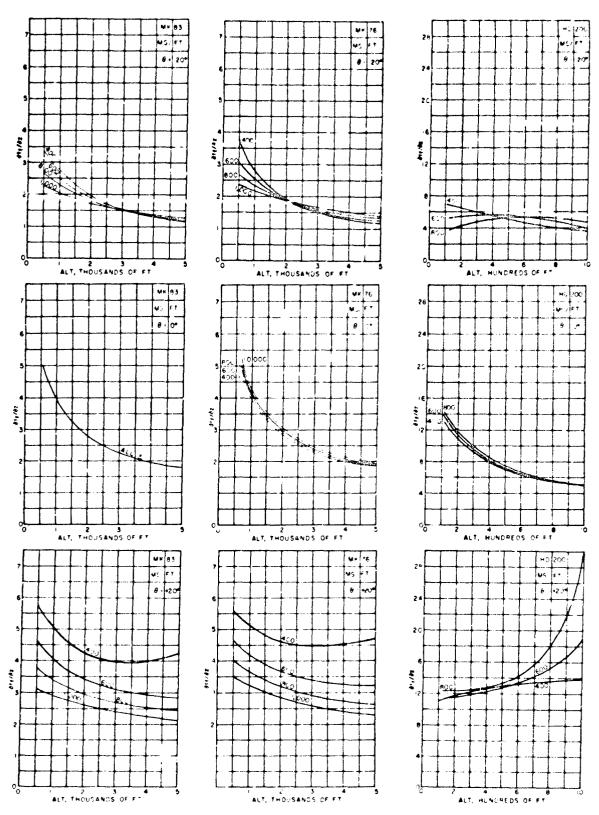


FIG. 29. Time of Flight Sensitivity to Altitude Change Versus Altitude.

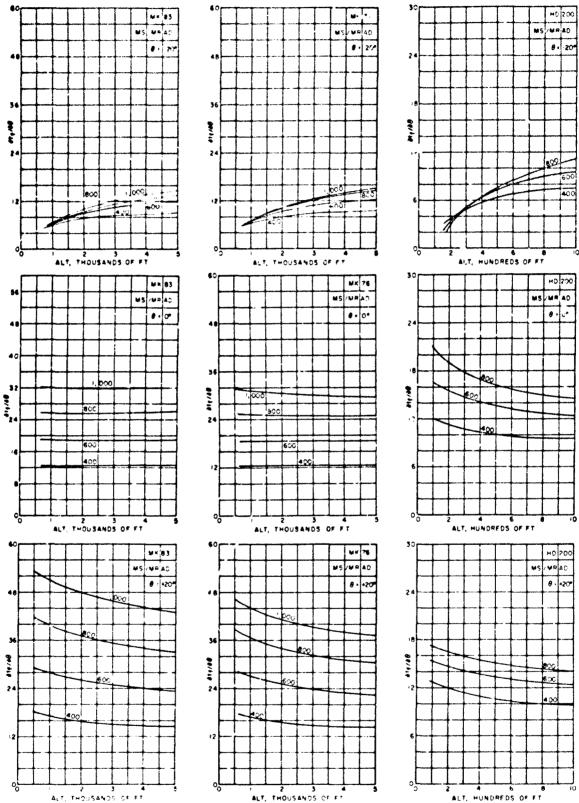


FIG. 30. Time of Flight Sensitivity to Release Angle Change Versus Altitude.

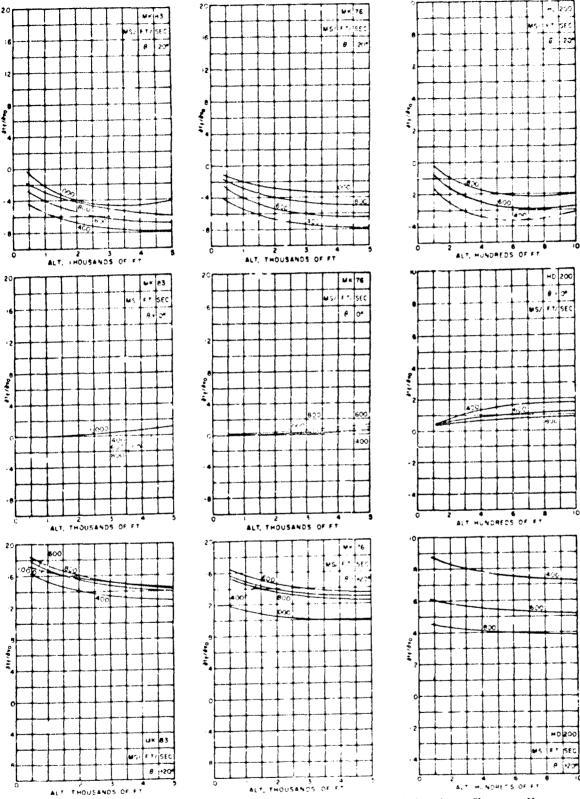


FIG. 31. Time of Flight Sensitivity to Release Velocity Change Versus Altitude.

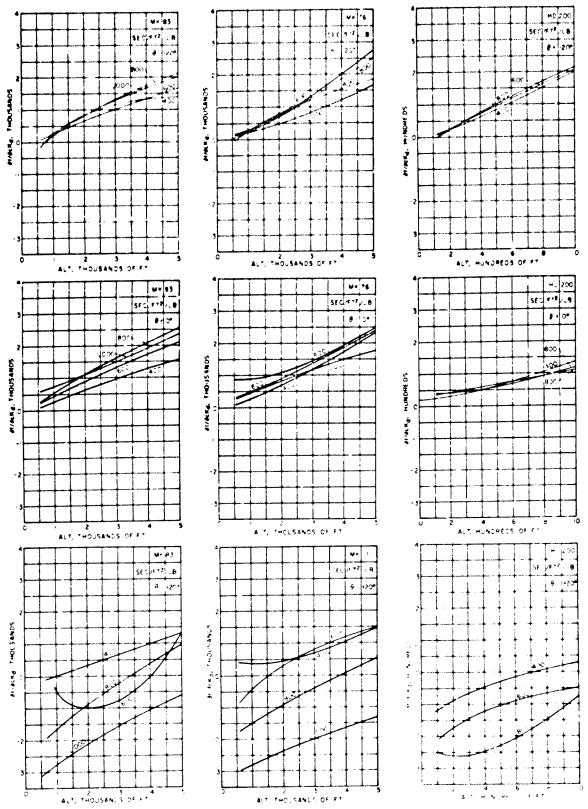


FIG. 32. Time of Flight Sensitivity to Drag Function Change Versus Altitude.

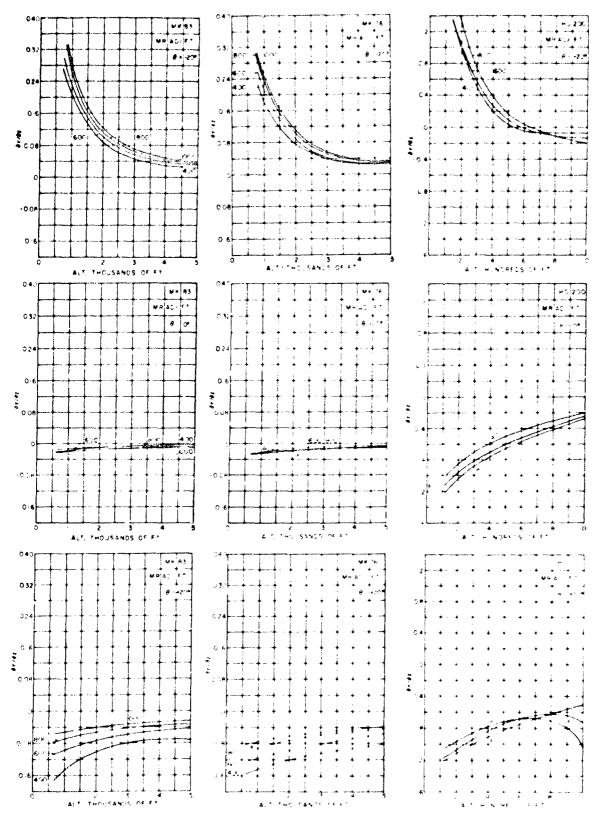


FIG. 33. Impact Angle Sensitivity to Altitude Change Versus Altitude.

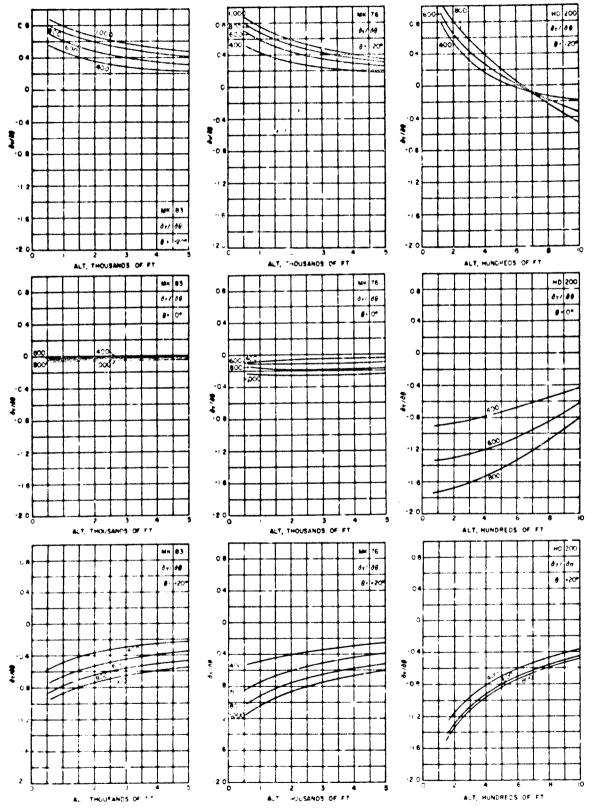


FIG. 34. Impact Angle Sensitivity to Release Angle Change Versus Altitude.

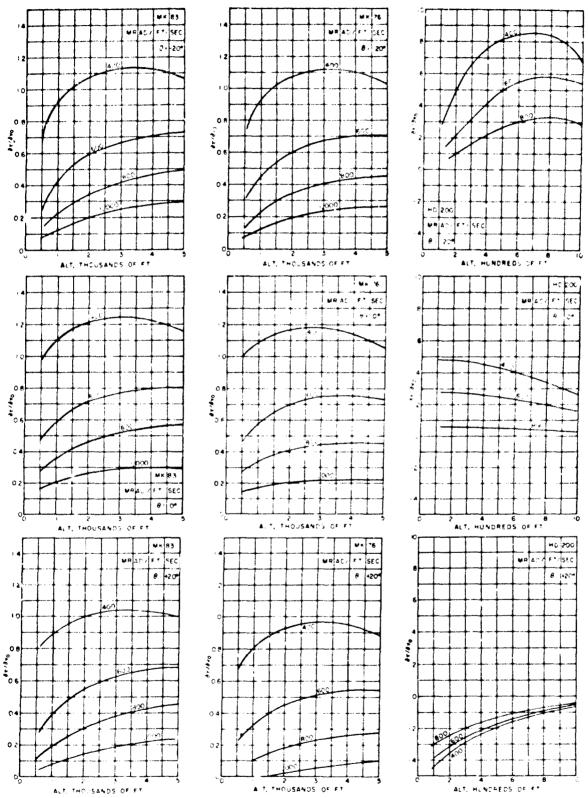


FIG. 35. Impact Angle Sensitivity to Release Velocity Change Versus Altitude.

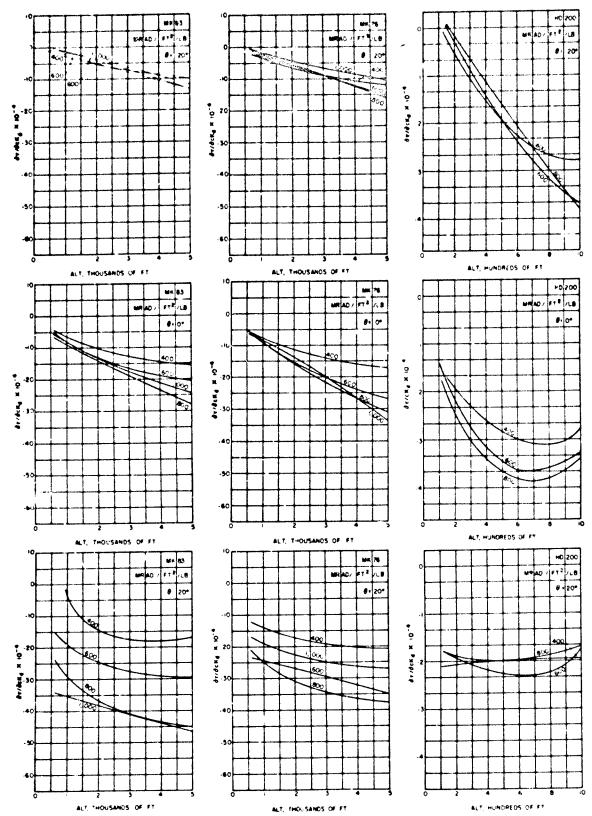


FIG. 36. Impact Angle Sensitivity to Drag Function Change Versus Altitude.

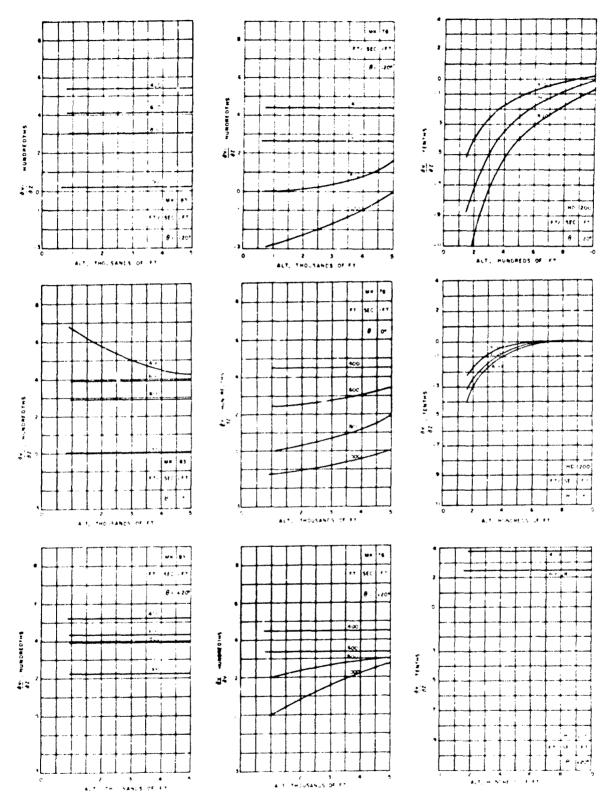


FIG. 37. Impact Velocity Sensitivity to Altitude Change Versus Altitude.

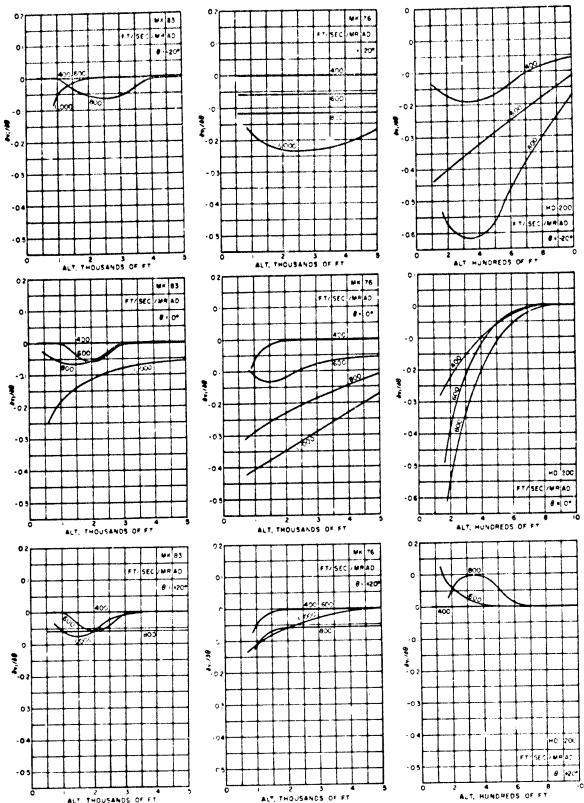


FIG. 38. Impact Velocity Sensitivity to Release Angle Change Versus Altitude.

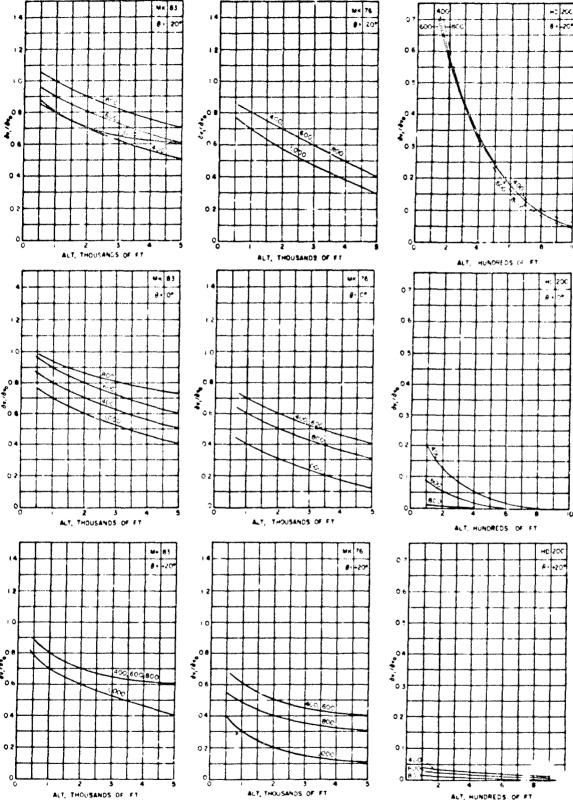


FIG. 39. Impact Velocity Sensitivity to Release Velocity Change Versus Altitude.

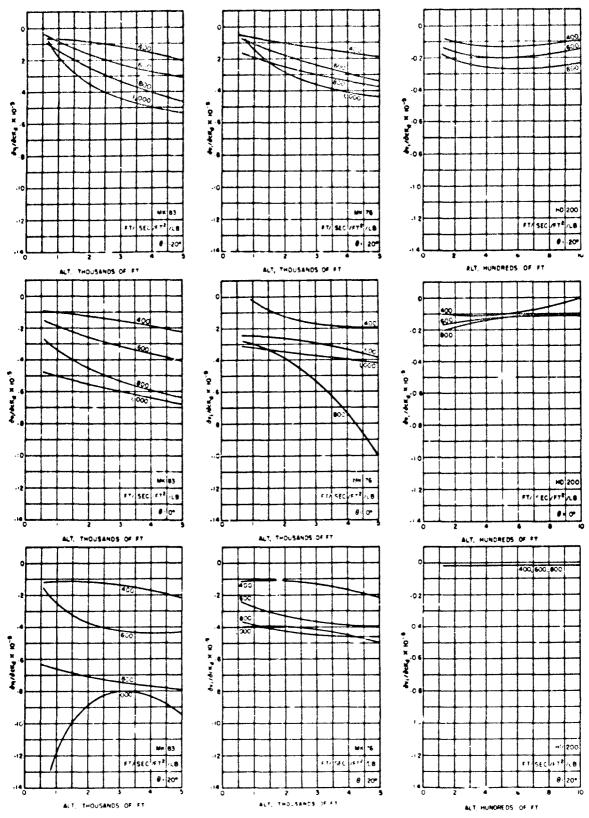


FIG. 40. Impact Velocity Sensitivity to Drag Function Change Versus Altitude.

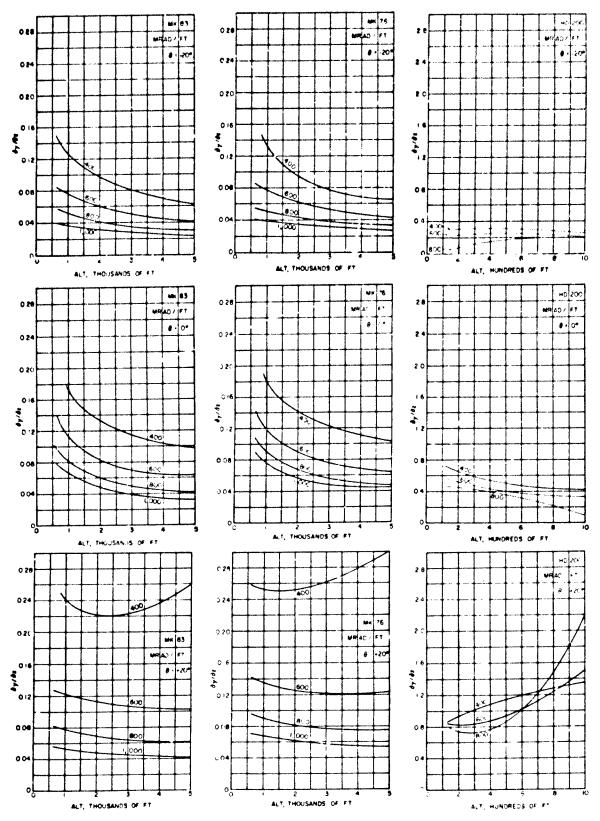


FIG. 41. Lead Angle Sensitivity to Altitude Change Versus Altitude.

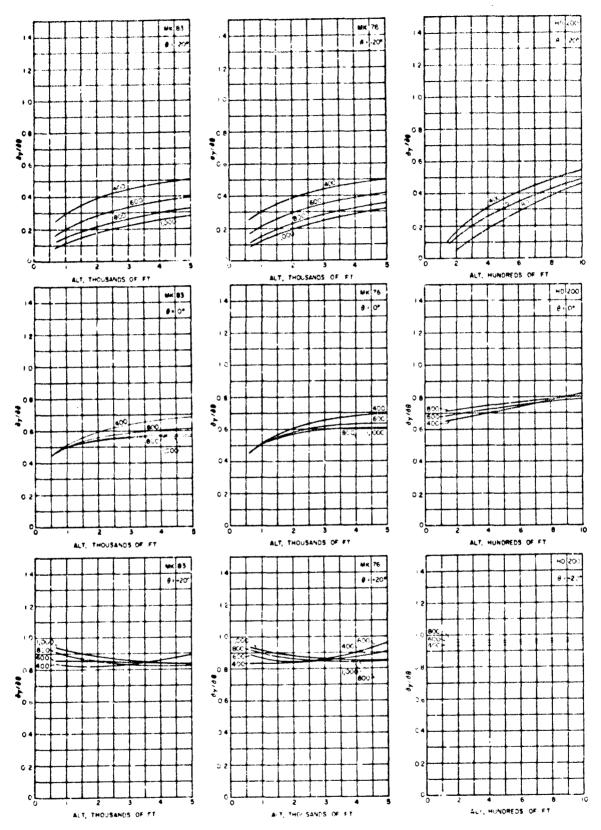


FIG. 42. Lead Angle Sensitivity to Release Angle Change Versus Altitude.

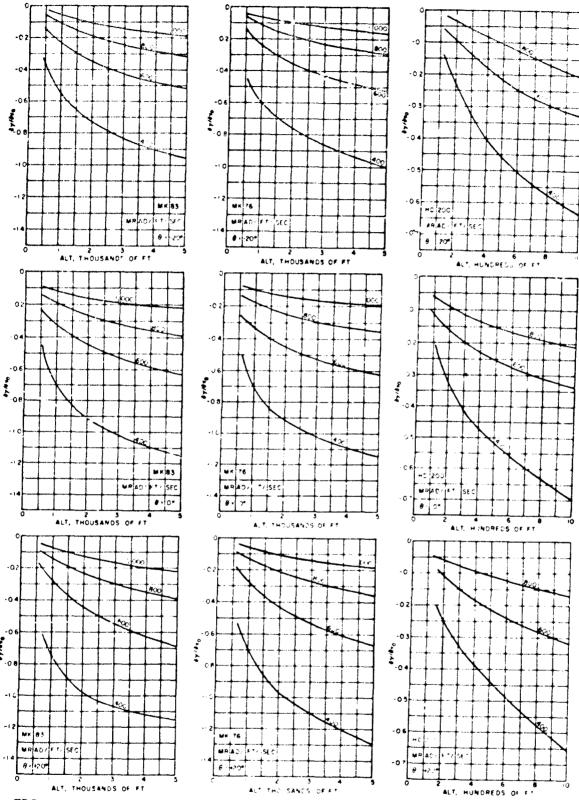


FIG. 43. Lead Angle Sensitivity to Release Velocity Change Versus Altitude.

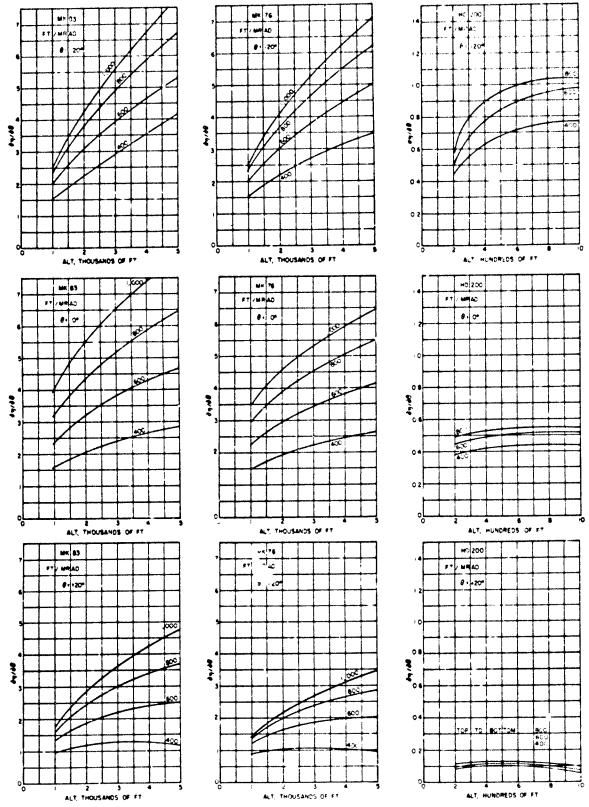


FIG. 44. Sensitivity of Distance Normal to Line-of-Sight to Release Angle Change Versus Altitude.

F. BOMB DATA

Table 10 gives some pertinent unclassified information on various bombs. The correct K_D function is given and the various K_D functions may be found tabulated in Section III.C. In most cases, several bombs can be made to use the same K_D curve by incorporating a correction factor in the value given for the reciprocal ballistic coefficient, c. Thus, c may include a form factor unequal to 1 (see Section II.B.3).

For reference to these bombs, a shortened designation system is used; i.e., the Mk 81 Mod 1 bomb with electric fuze is written Mk 81/1/E. For most bombs the mod number follows the first bar; after the second bar is given other pertinent conditions are given by the following abbreviations:

- T without fuze
- E electric fuze
- M mechanical fuze
- L with lugs
- N without lugs
- WF water filled
- WS wet sand filled

TABLE 10. Bomb Data

Bomb	Mod	Diameter, in.	Weight,	Specifications	c ft ² /lb	K _D table to use
Mk 28	(EX)1	20.00	2040	•	.0008262	19k76/4/T/N
Mk 43	0	18.00	2125	Large fin, nose Mod 1	.0010588	Mk43/0 nose Mod 1
Mk 57	0, 1	14.75	5 00	-	.00244	(with large fin)
Mk 76	0, 2	i	23.6	Without lugs	.004706	Mk76/0&2/N
Mk 76	2	4.00	23.6	With lugs	.006379	Mk76/0&2/N
Mk 76	4	4.00	24.23	With lug, no fuze	.004586	Mk76/4/T/L
Mk 76	4	4.00	24.23	Without lug or fuze	.004586	Mk76/4/T/N
Mk 81	1	9.00	270	Electric fuze	.002937	Mk83/2&3/E
Mk 81	1	9.00	270	Mechanical fuze	.003916	Mk83/2&3/E
Mk 82	0, 1	10.75	500	Electric fuze	.001814	Mk83/2&3/E
Mk 82	0, 1	10.75	5 00	Mechanical fuze	.002721	Mk83/2&3/E
Mk 83	2, 3	14.00	985	Electric fuze	.001382	Mk83/263/E
Mk 83	2, 3	14.00	985	Mechanical fuze	.001759	Mk83/2&3/E
Mk 84	1	18.00	1970	Electric fuze	.001142	Mk83/2&3/E
Mk 84	1	18.00	1970	Mechanical fuze	.001522	Mk83/2&3/E
Mk 86	0, 1	9.00	140	Water filled	.005936	Mk83/2&3/E
Mk 86	0, 1	9.00	200	Wet sand filled	.003994	Mk83/2&3/E
Mk 88	0	14.00	458	Water filled	.002972	Mk83/2&3/E
Mk 88	0	14.00	783	Wet sand filled	.001738	Mk83/2&3/E
Mk 89	0	4.00	56	Without lugs	.002877	Mk83/2&3/E
Mk 89	0	4.00	56	With lugs	.004250	Mk83/2&3/E
Mk 106	0	3.87	4.63	-	.1306	Std G1 drag
Mk 106	2	3.87	4.65	-	.1511	function "
HD-200		-	-	-	.1000	.1066 (constant) M ≤ 0.75
AN-M57A1	-	10.80	284	M126 fin assembly	.002853	AN-M57Λ1 M126 fin
AN-M64A1	-	14.20	587	M128Al fin assembly	.002385	ΔN-M64A1 M128A1 fin

IV. NOMOGRAPHS

The nomographs 5 given herewith allow rapid evaluation of many important parameters. While they cannot give the accuracy of a computed value, they can give an answer that is well within allowable limits of error (usually less than one or two percent) for design and analysis of bombs and types of fire control systems.

Many of the nomographs are versatile; on some of the graphs either of two variables may be given and the remaining one calculated. They are most accurate near the center of their ranges; on some of the graphs the error will increase as velocities tend toward the speed of sound. The emphasis is on subsonic application throughout.

On all nomographs the examples given are drawn as dotted lines on the graphs. In some cases, a small diagram is given and on the most involved nomographs detailed instructions are included.

The nomographs are divided into four sections, which are described below. The first section contains graphs applicable to all bombs; the second contains vacuum solutions of the trajectory which might be useful in allowing for delay times; the third section deals with graphs applicable only to standard drag bombs; and the last section is restricted to retarded bombs.

It should be noted that many of the standard drag bombs require knowledge of the cK_D product. In such cases, a small copy of nomograph 7 is included; Mach numbers may be obtained from nomographs 7 or 16.

⁵Upon request, NOTS, China Lake, will provide specific nomographs on plastic.

DESCRIPTION OF NOMOGRAPHS

- A. GENERAL USACE (p. 88)
 - 1. Altitude, or ground range (three nomographs in one)
 - 2. Altitude, or ground range
 - 3. Slant range
- B. VACUUM SOLUTIONS (p. 94)
 - 4. Ground range
 - 5. Impact angle
 - 6. Altitude
- C. STANDARD DRAG BOMBS (p. 100)
 - 7. Mach number, Kn, cKn product, altitude corrections
 - 8. Impact angle
 - 9. Time of flight, or ground range
 - 10. Altitude
 - 11. Altitude or ground range, level release
 - 12. Ground range, loft bombing from Z = 0 to Z = 0
 - 13. Ballistic lead angle using ground range data
 - 14. Ballistic lead angle using altitude data
 - 15. Change in ground range due to small change in angle of release about level release
- D. RETARDED BOMBS (p. 118)
 - 16. Mach number, $K_{\overline{D}}$, $cK_{\overline{D}}$ product, altitude corrections
 - 17. Impact angle
 - 18. Time of flight, or ground range
 - 19. Altitude
 - 20. Ground lag, ground range, or altitude, level release
 - 21. Ballistic lead angle using ground range data
 - 22. Change in ground range due to small change in angle of release about level release.
 - 23. Time of flight or altitude, level release

A. GENERAL USAGE

Nomograph 1. Altitude, or Ground Range

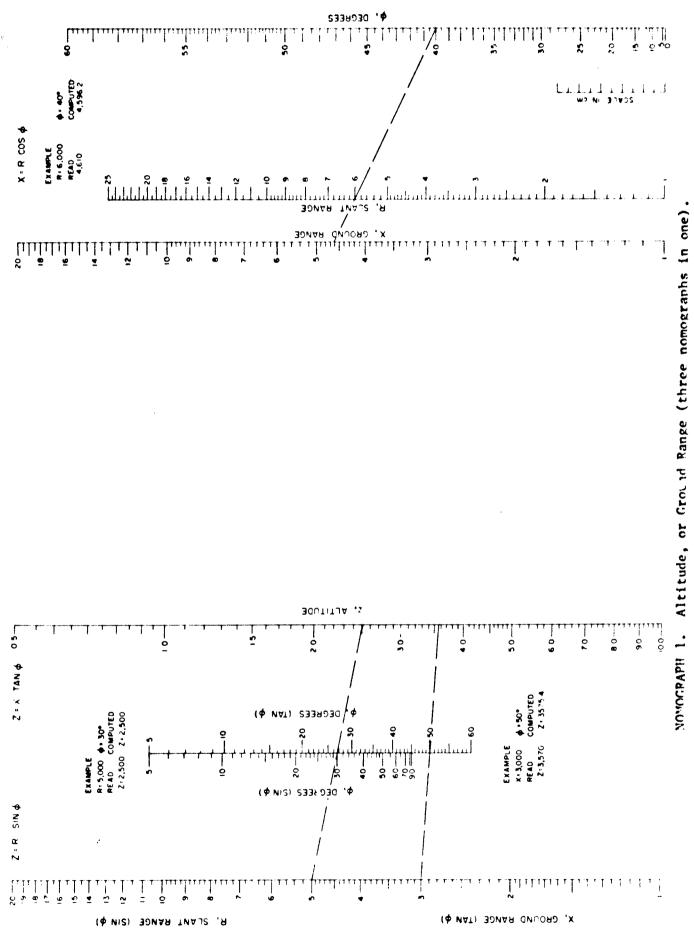
This nomograph solves the relations

 $Z = R \sin \phi$,

 $Z = X \tan \phi$,

 $X = R \cos \phi$.

Given any two of the variables, R, X, Z, or ϕ , the remaining two can be determined.

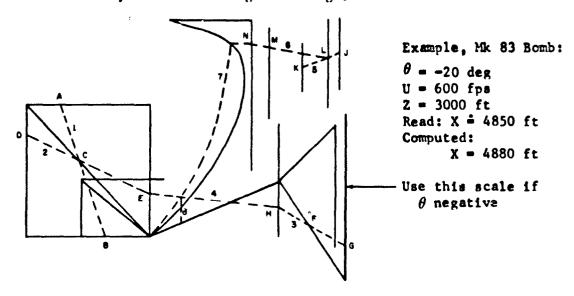


Nomograph 2. Altitude or Ground Ronge (General Usage)

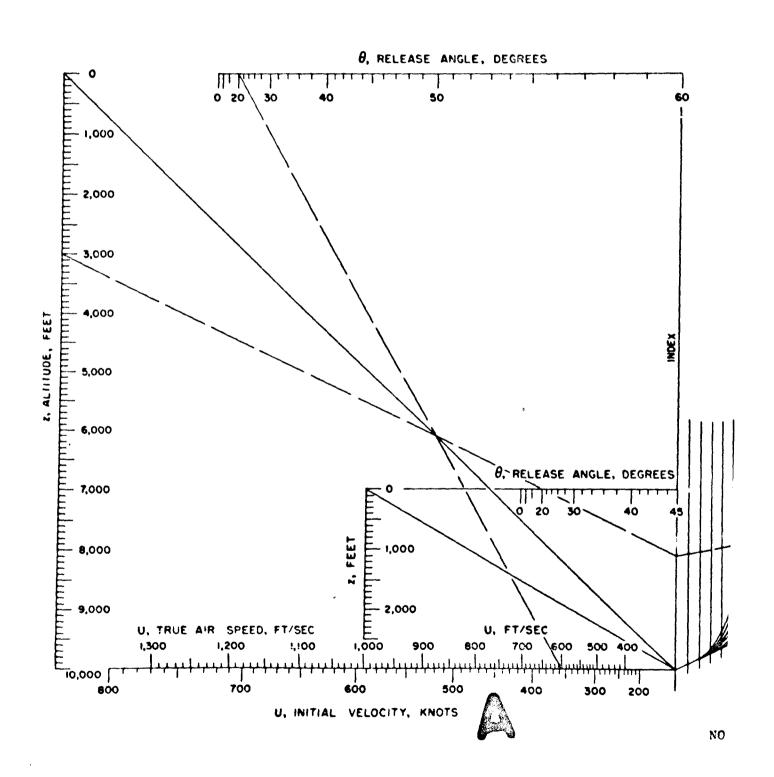
Given Z, X may be solved for using this graph. The process may be reversed to solve for Z although an iteration process may be necessary. This nomograph solves eq. 51a. Either nomograph 7 or 16 may be used to determine the ckp value, depending on the type of bomb being studied.

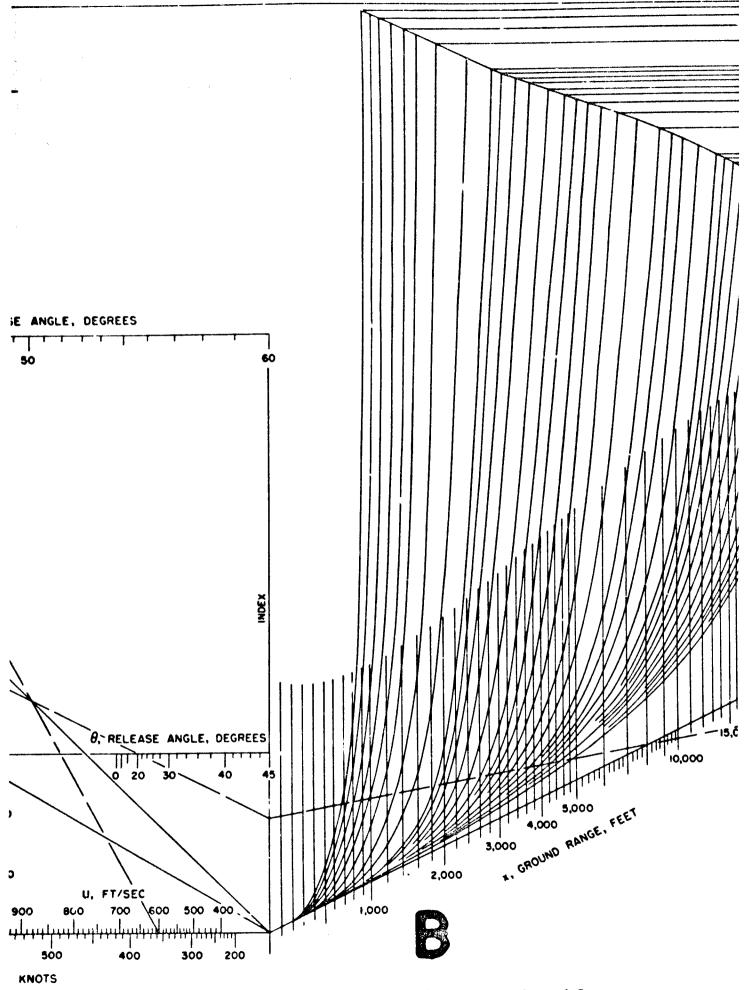
Use of nemograph:

- 1. Locate release angle on upper left scale, label as A.
- 2. Locate velocity on lower left scale, label as B.
- 3. Construct line AB, label as C the point where AB crosses upper oblique index.
- 4. Locate altitude on far left scale, label as D.
- 5. Construct line CD, label as E point where CD cuts center vertical index.
 - Steps 1 through 5 may be carried out on smaller scales at lower right center; this will give the same point E.
- 6. Locate release angle on scales in lower right, label as point F. Note that there are different scales depending on sign of θ .
- 7. Locate velocity on scales in lower right corner. Note that different U-scales are used for different signs of θ .
- 8. Construct line FG, label as H intersection of FG and left vertical index line. Construct line EH.
- 9. Locate θ on upper right scale, label as J.
- 10. Locate Z on upper right scale, label as K.
- 11. Construct line JK, label as L intersection of JK with index line. Locate and label as M the correct cKD value.
- 12. Construct line LM, label as N the intersection of LM and upper left vertical index line.
- 13. From N, trace along curve to the left where curve intersects line EH; note value of ground range.

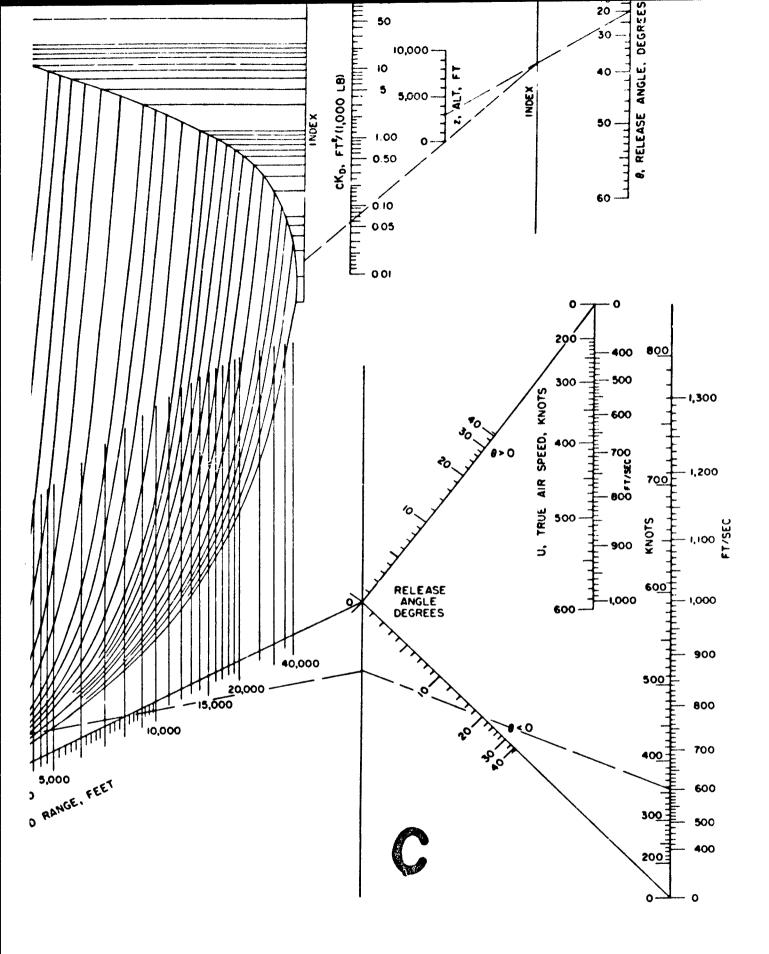


$$z = -x$$
 TAN $\theta + \frac{gx^2 + y}{2u^2 \cos^2 \theta}$
 $\psi = \psi \text{ (kx SEC } \theta \text{)}$
 $k = \frac{2}{3} \rho \text{CK}_D$





NOMOGRAPH 2. Altitude, or Ground Range.

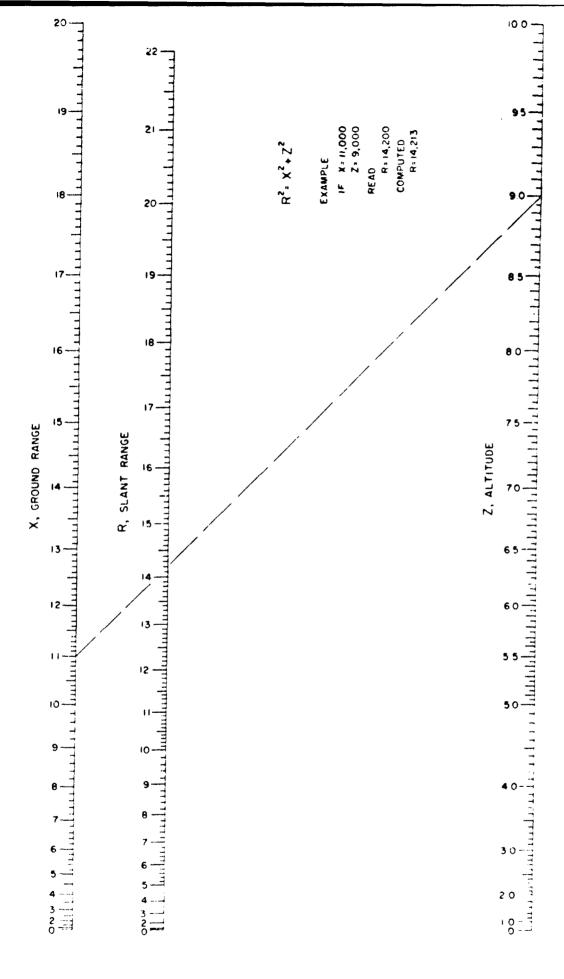


Nomograph 3. Slant Pange (General Usage)

This nomograph solves the relation

$$R^2 = x^2 + z^2$$

for any of the variables R, X, or Z, given the other two.



NOMOGRAPH 3. Slant Range.

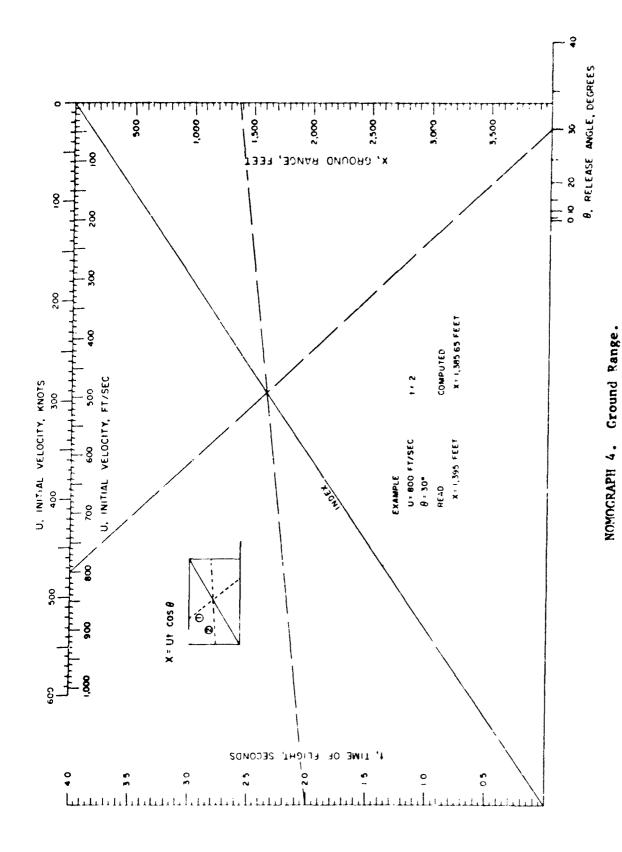
B. VACUUM SOLUTIONS

Nomograph 4. Ground Range

This nomograph solves the relation

 $X = Ut \cos \theta$.

Given any three of the variables X, U, t, or θ , the fourth may be found merely by interchanging, as required, the steps indicated on the nomograph (use diagram).

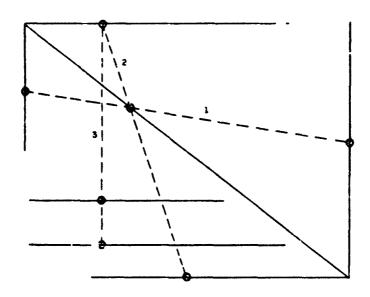


Nomograph 5. Impact Angle (Vacuum Solutions)

Using the equations for the trajectory in a vacuum, this nomograph allows rapid determination of impact angle. The nomograph is based on eq. 26.

For standard drag bombs, this might serve as a very rough approximation of the actual conditions; other nomographs of this section might also be applicable to solution of problems involving delay times of retarded bombs.

Use of Nomograph 5: Given θ , U, and t, enter the nomograph as indicated by the nomograph diagram below to find the impact angle.



Example:

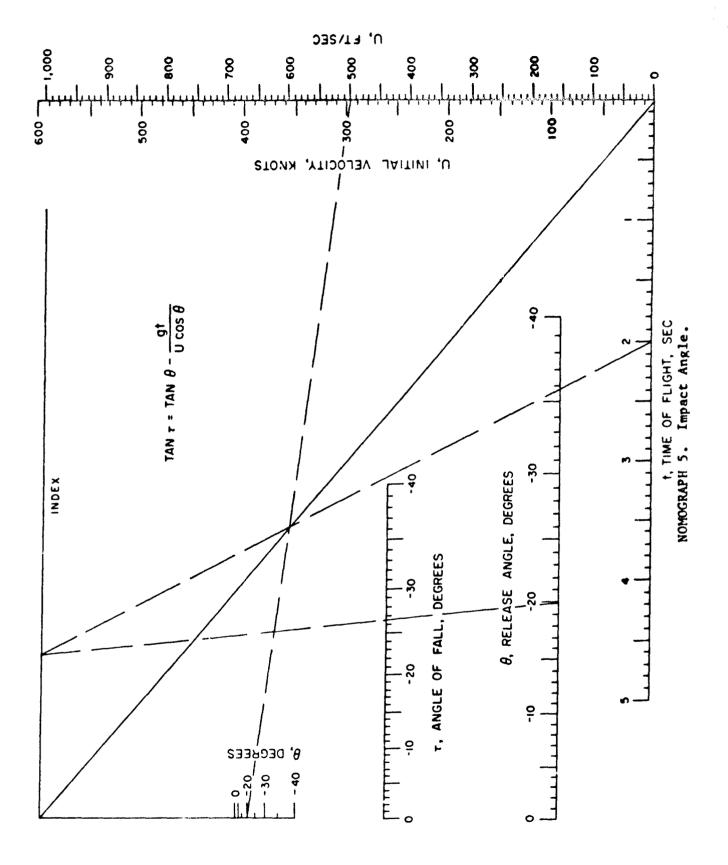
 $\theta = -20 \deg$

U = 500 fps

t = 2 sec (time of flight)

Read: 7 = 26.6 deg

Computed: $\tau = 26.61 \text{ deg}$

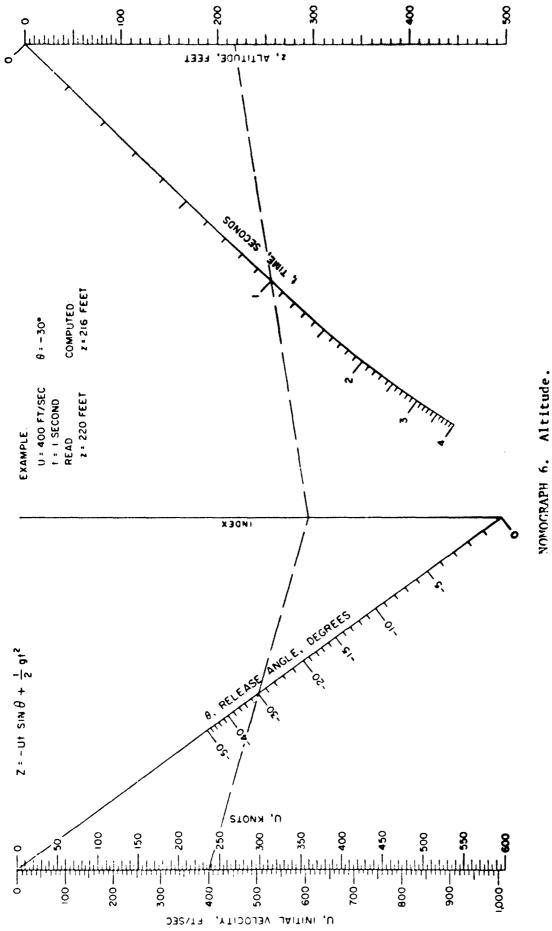


Nomograph 6. Altitude (Vacuum Solutions)

This nomograph solves the relation

$$Z = Ut \sin \theta + \frac{1}{2} gt^2$$
,

Given any three of the four variables Z, U, t, or θ , the fourth may be determined. Use of the nomograph is straightforward.



C. STANDARD DRAG BOMBS

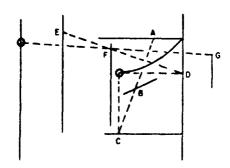
Nomograph 7. Mach Number, Kp, cKp Product, Altitude Corrections

This nomograph uses empirical data to determine several different quantities. Values of c, the reciprocal ballistic coefficient, are indicated for various bembs on one scale. Reference to the bomb data section (III.F.) will show that many bombs follow the $\rm K_D$ curves that are graphed here. If a bomb follows a $\rm K_D$ curve not graphed, its $\rm K_D$ values may be taken from the $\rm K_D$ curve section and this value may then be located on the far right scale.

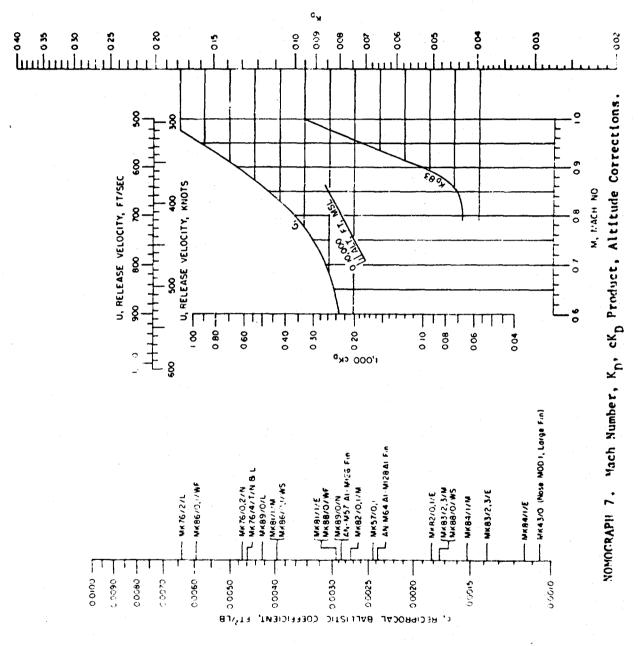
Using the first three steps of the following procedure, the Mach number for a given velocity and altitude may be found. It is also possible to calculate another parameter, 1000 (ρ/ρ_0) cKD, that is used sometimes as a correction rather than merely taking the value of 1000 cKn.

It should be noted that with this nomograph, one need not necessarily start with step one of the procedure. Depending on the amount of information known beforehand, several steps may be eliminated. The complete procedure follows:

- 1. Locate release velocity, label as A.
- 2. Locate altitude on oblique scale, label as B.
- 3. Construct line AB, extend to Mach number scale. This is value of Mach number under given conditions; label as C.
- 4. From point C, go vertically to intersection with appropriate KD curve, then horizontally right to KD scale. This gives the value of the ballistic drag coefficient under the given conditions. If KD is known from some other source, it may be located immediately without going through the preceding steps; label as point D.
- 5. Locate value of c, label as E.
- 6. Construct line DE, determine intersection of DE with 1000 cK_D scale. Note that units here are ft^2/lb ; however, in most of the following work, units will be $ft^2/l000$ lb. Thus, the number read here gives the value of cK_D product in units of $ft^2/l000$ lb; label as F.
- 7. Locate altitude on far right scale, label as G.
- 8. Construct line GF and extend to far left, read off value of 1000 p/p₀ cK_D.







Homograph 8. Impact Angle (Standard Drag Bombs)

This nomograph uses eq. 51b to determine the impact angle.

Use of nomograph:

- 1. Use Nomegraph 7 to determine the cKD value. Locate this value on graph scale, label as A.
- 2. Locate altitude on left scale, label as point B.
- 3. Construct line AB, label intersection with oblique index line as point C.
- 4. Locate ground range on bottom left scale, label as D.
- 5. Construct line CD, label intersection of CD with horizontal index line as E.
- 6. Draw vertical line through E to intersection with appropriate θ curve, then proceed horizontally to right to vertical index line. Label point of intersection with index as F.
- 7. Locate velocity on far right scale, label as G.
- 8. Construct line FG, label intersection of FG with upper oblique index line as H.
- 9. Locate ground range on upper right scale, label as J.
- 10. Construct line HJ, label intersection with horizontal index as K.
- 11. Locate release angle on lower right scale, label as L.
- 12. Construct line KL. Read r where KL crosses scale.

Example:

Mk 83/2&3/E Bomb

Z = 5000 ft

 $\theta = -10 \deg$

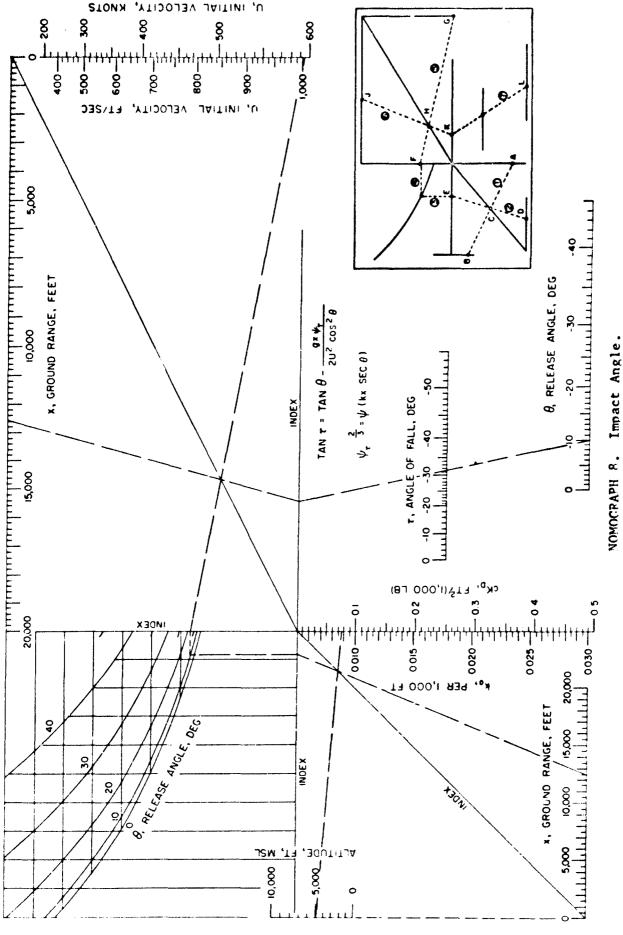
U = 1000 fps

X = 12,620

Read: 7 = 31.5 deg

Computed:

 $\tau = 32.16 \text{ deg.}$

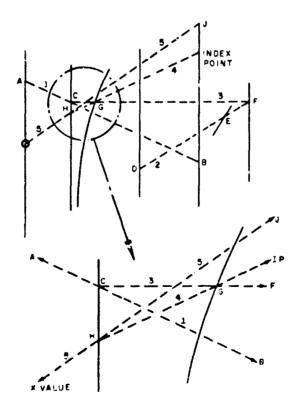


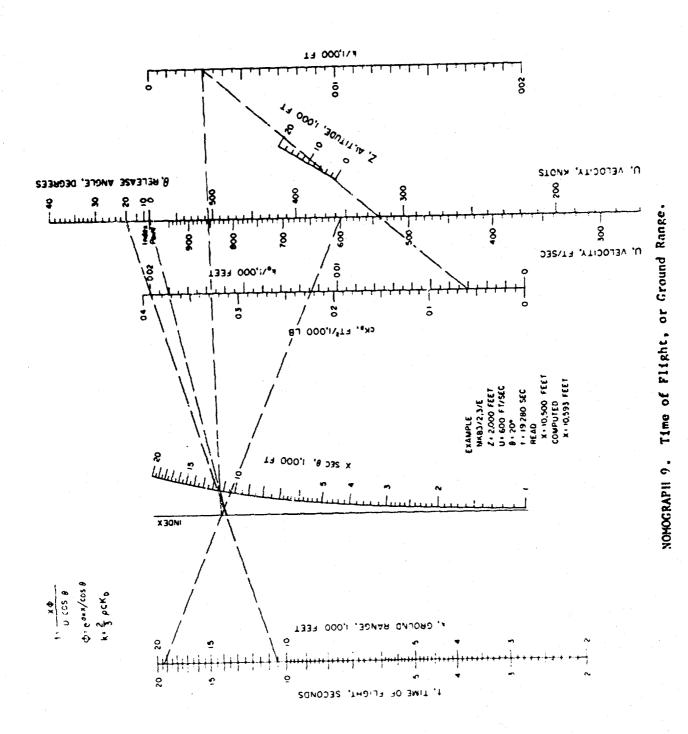
Nomograph 9. Time of Flight or Ground Range (Standard Drag Bombs)

This nomograph uses a slightly modified form of eq. 52; here "a" is chosen for best fit rather than using 3/4.

Given X, t may be determined; and given t, X may be found. Instructions are for getting X, given t. The other method should be obvious once this case is studied.

- 1. Locate time of flight on left scale, label as A.
- 2. Locate velocity U, label as B.
- 3. Construct line AB, label as C intersection of AB and left index line.
- 4. Determine value of cKD from Nomograph 7, locate value and label as D.
- 5. Locate altitude on oblique scale, label as E.
- 6. Construct line DE, label as F intersection of DE with right index.
- 7. Construct line CF, label as G intersection of CF and curved scale.
- 8. Connect G to index point and extend line to left index, label as H.
- 9. Locate angle θ , label as J.
- 10. Construct line HJ, extend HJ to X-scale, read off X.





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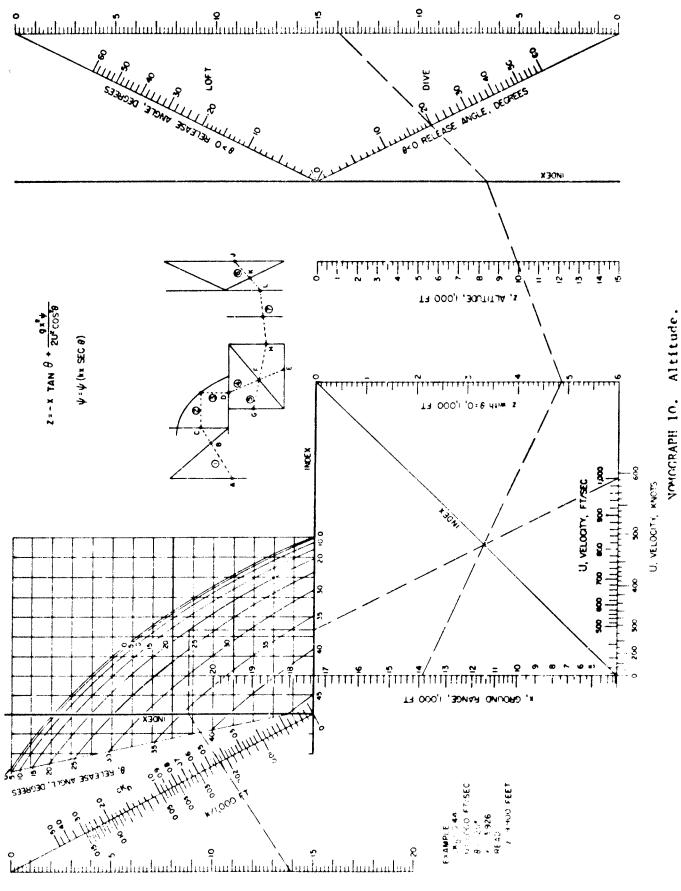
Nomograph 10. Altitude (Standard Drag Bombs)

Using eq. 51a, this nomograph allows calculation of altitude Z for standard drag weapons.

By estimating altitude, cK_D may be determined from Nomograph 7. If original estimate is too inaccurate, the process may be repeated after mawer is read from this nomograph, i.e., use iteration scheme for altitude.

- 1. Locate ground range on upper left scale, label as A.
- 2. Locate value of cKp, label as B on upper oblique scale.
- 3. Construct line AB, label as C intersection of AB and left vertical index.
- 4. From point C, proceed horizontally to appropriate θ curve, then down to horizontal index line. Label point of intersection on horizontal index line as D.
- 5. Locate velocity U on lower scale, label as E.
- 6. Construct line DE, label as F the intersection of DE and oblique index line.
- 7. Locate ground range on lower left vertical scale, label as G.
- 8. Construct line FG, extend line to Z, with $\theta = 0$ scale, label as point H. If $\theta = 0$ deg, point H is the altitude.
- 9. If $\theta \neq 0$ deg, locate X on far right scale. If $\theta > 0$, use upper portion of X-scale. If $\theta < 0$, use lower portion of X-scale. Label as J.
- 10. Locate heta on appropriate oblique scale, label as K.
- 11. Construct line JK, label as L intersection of JK and right vertical index.
- 12. Construct line HL, intersection of HL with Z, altitude scale gives value of Z.





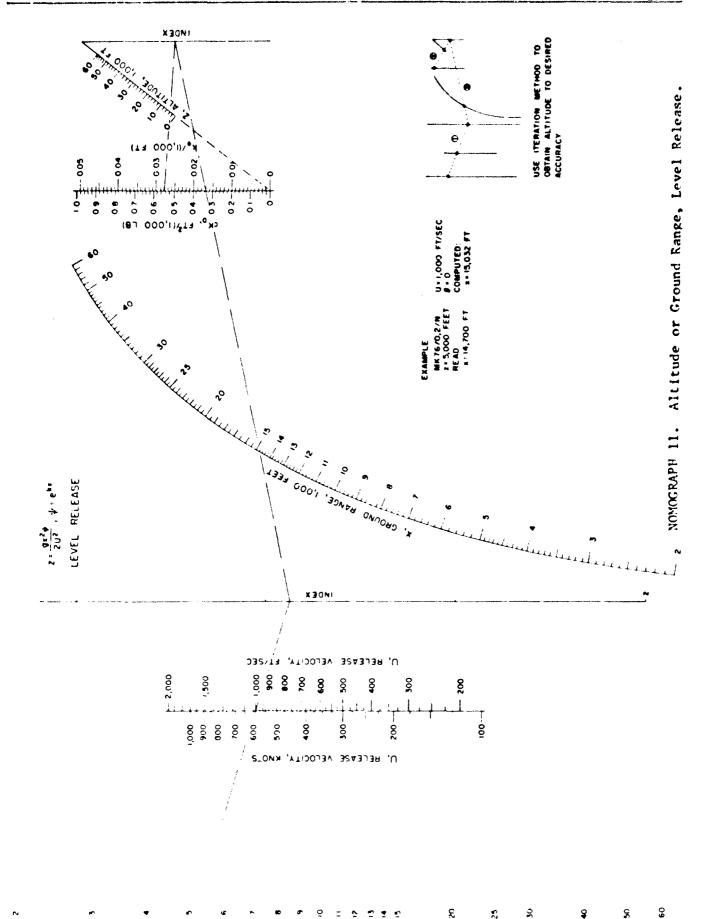
THE GROUND FAMICE, 1,000 FT

Nomograph 11. Altitude or Ground Range, Level Pelease (Standard Drag Bombs)

From this nomograph, pround range may be determined directly given the release altitude, velocity, and $cK_{\overline{p}}$ product of the weapon, or release altitude may be determined by iteration given ground range, velocity and $cK_{\overline{p}}$ product. The equation solved is

$$z = \frac{gX^2}{2v^2} e^{\left(\frac{c}{v_0}\right)k_0X}; \quad k_0 = \left(\frac{2}{3}\right) e_0 cK_D.$$

- Use: 1. Use Nomograph 7 to determine cK_n .
 - 2. To find X, enter nomograph as shown in diagram on nomograph.
 - 3. To find 2, estimate 2 in step 2 of diagram.
 - 4. Proceed in the step sequence 2, 3, 1 to find Z on the lefthand scale. If this Z does not agree with the initial estimate, enter step 2 with Z value just determined and continue as above until Z values agree.



Z, ALTHUDE, HOOG FEET

ε

53

Š

8

Ş

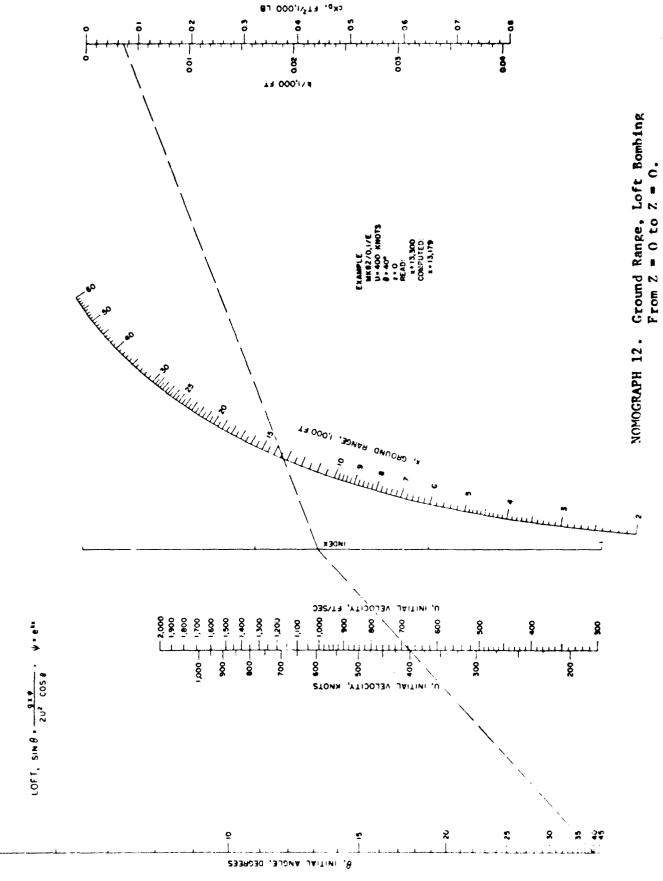
Nomograph 12. Ground Range, Loft Bombing From Z = O to Z = O. (Standard Drag Bombs)

This nomograph solves the equation

$$\sin \theta = \frac{gX\psi}{2v^2\cos \theta}$$
, $\psi = e^{kX}$

for trajectories between Z = U and Z = D.

Given any three of the four variables X, θ , U, or cK_D , the fourth can be found. The nomograph use for any of these cases is straightforward.



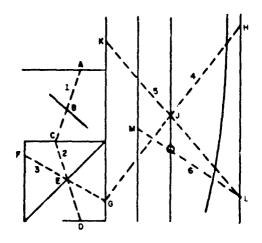
Nomograph 13. Bellistic Lead Angle Using Ground Range Data (Standard Drag Bombs)

This nomograph uses eq. 59 to solve for the ballistic lead angle directly. It can easily be used to solve for ground range or release angle using some iteration.

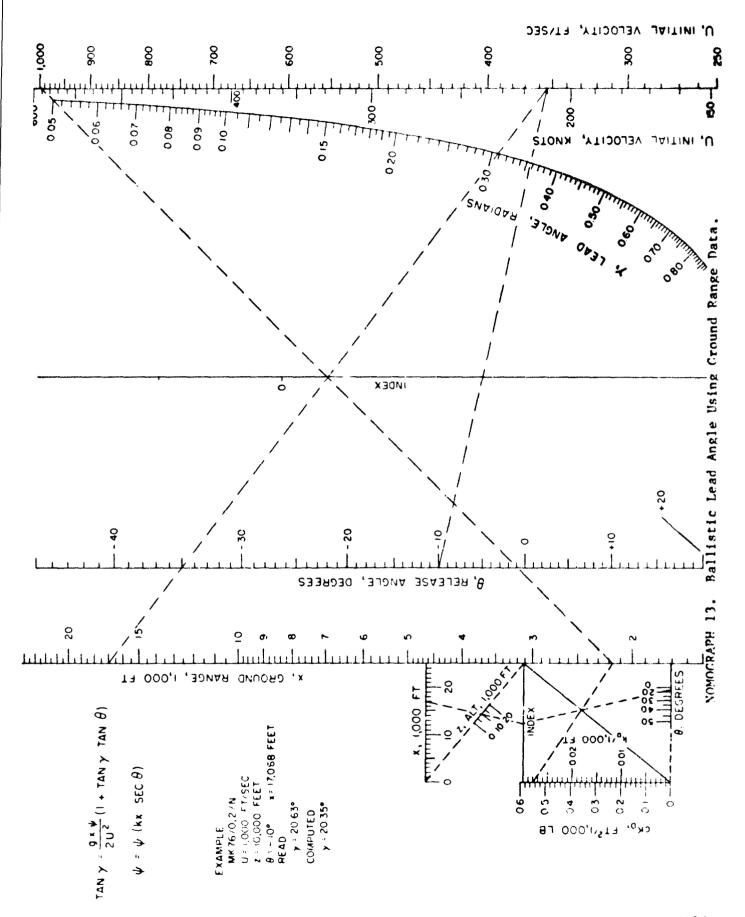
Use of nomograph:

- 1. Locate ground range on small horizontal scale to left, label as point A.
- 2. Locate altitude on scale, label as point B.
- 3. Construct line AB, extend AB to intersection with horizontal index line, label intersection as C.
- 4. Locate θ on scale in lower left corner, label as D.
- 5. Construct line CD, label as E intersection of CD with oblique index line.
- 6. Using Nomograph 7, locate and label as F the value of cKD.
- 7. Construct line EF, label as G intersection of EF with vertical X-scale.
- 8. Locate velocity on right scale, label as H.
- 9. Construct line GH, label as J intersection of GH with center index line.
- 10. Locate X on left vertical scale, label as K.
- 11. Construct line JK, label intersection of JK with U-vertical scale as L.
- 12. Locate θ on vertical scale, label as M.
- 13. Construct line LM, intersection of LM with γ -scale gives the value of γ .

For ckp information, refer to nomograph 7.



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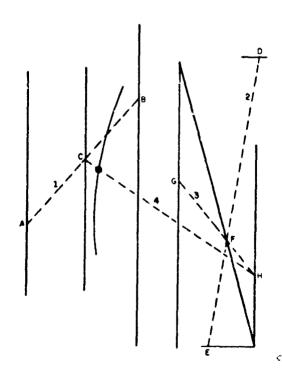


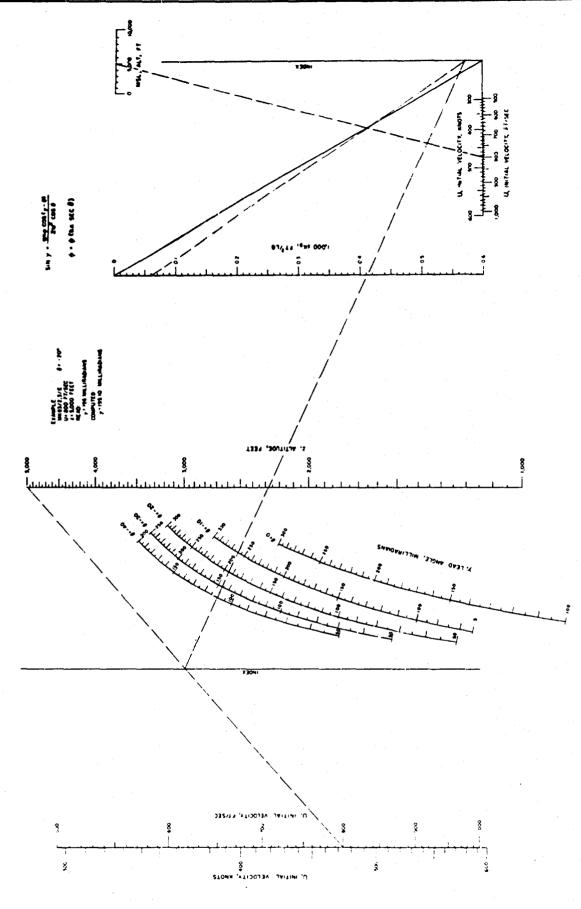
Nomograph 14. Bellistic Lead Angle Using Altitude Data (Standard Drag Bombs)

This nomograph allows calculation of the ballistic lead angle from altitude and airspeed information. The nomograph uses eq. 59.

Nomograph 7 may be used to determine the cK_D value for the various bombs. Necessary bomb data can be obtained from the K_D curve (III.C.) and Bomb Data (III.F.) sections.

- 1. Locate velocity on left scale, label as A.
- 2. Locate altitude on center vertical scale, label as B.
- 3. Construct line AB, label as C intersection of AB and vertical index line.
- 4. Locate altitude on upper right scale, label as D.
- 5. Locate velocity on lower right scale, label as E.
- Construct line DE, label as F the intersection of DE and oblique index line.
- 7. Locate and label as G the value of cKD.
- 8. Construct line FG, label as II the intersection of FG and right index line.
- 9. Construct line CH, intersection of CH with correct release angle curve gives value of Y.





NOMOGRAPH 14. Ballistic Lead Angle Using Altitude Data.

Nomograph 15. Change in Ground Pange Due to Small Change in Angle of Release About Level Release. (Standard Drag Bombs)

This nomograph solves the relation

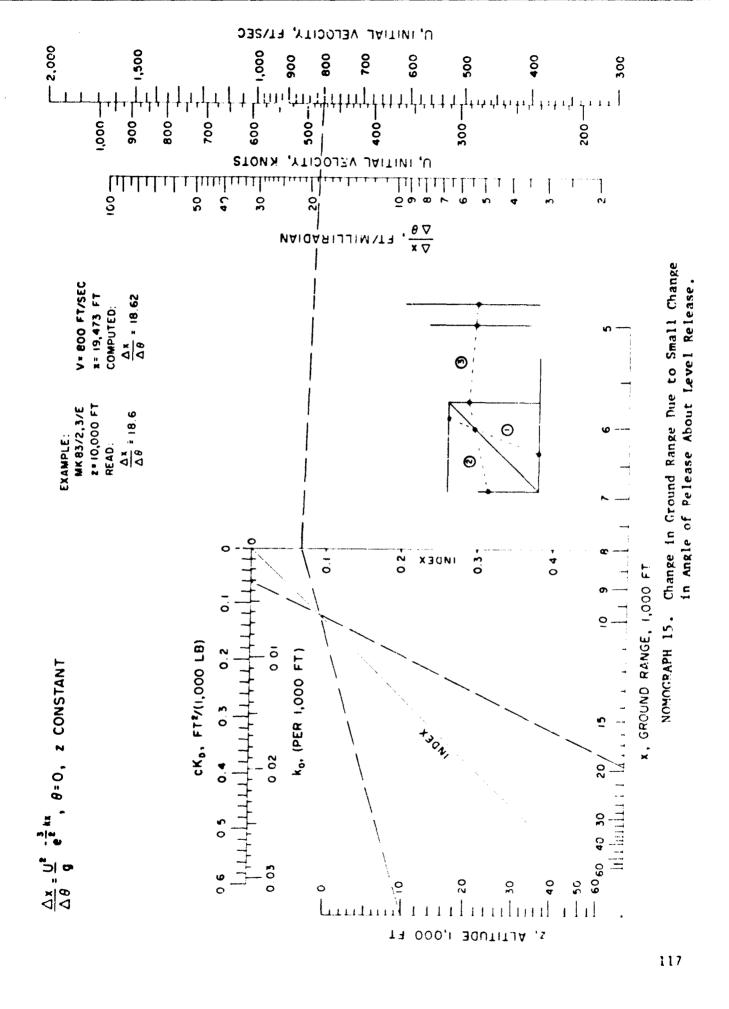
$$\frac{\Delta X}{\Delta \theta} = \frac{U^2}{R} e^{-\frac{3}{2}kX}; \quad \theta = 0, Z = constant,$$

giving the ratio of the change in ground range, ΔX , due to a small deviation of release angle, $\Delta \theta$, about level release.

Use:

- 1. Determine cK_{p} product from Nomograph 7.
- 2. With known X, Z, U, and the $cK_{\overline{D}}$ product, the sequential steps are indicated in the chart diagram.

Note that the ratio $\Delta X/\Delta\theta$ is given in ft/m rad. Multiply by 17.34 to obtain the ratio in ft/degree.



D. RETARDED BOMBS

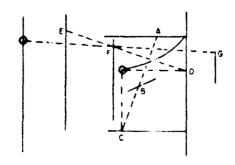
Nomograph 16. Mach Number, KD, cKD Product, Altitude Corrections (Retarded Bombs)

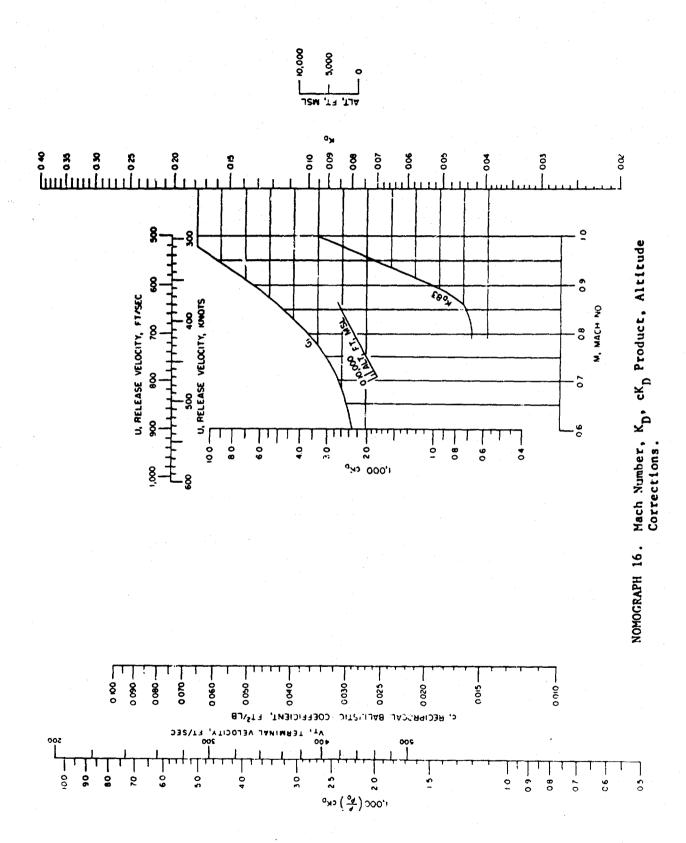
This nomograph uses empirical data to allow the determination of several different quantities. Reference to the Bomb Data (III.F.) section will show that many bombs follow the K_D curves that are graphed here. If a bomb follows a K_D curve not graphed, its K_D values may be taken from the K_D curve section and this value may then be located on the far right scale.

Using the first three steps of the following procedure, the Mach number for a given velocity and altitude may be found. It is possible to calculate another parameter, 1000 (ρ/ρ_0) cK_D, which is used sometimes as a correction rather than merely taking the value of 1000 cK_D.

It should be noted that with this nomograph, one need not necessarily start with step one of the procedure. Depending on the amount of information known beforehand, several steps may be eliminated. Complete procedure follows:

- 1. Locate release velocity, label as A.
- 2. Locate altitude on oblique scale, label as B.
- 3. Construct line AB, extend to Mach number scale. This is value of Mach number under given conditions; label as C.
- 4. From point C, go vertically to intersection with appropriate KD curve, then horizontally to right to KD scale. This gives the value of the ballistic drag coefficient under given conditions. If KD is known from some other source, it may be located immediately without going through the preceding steps; label as D.
- 5. Locate value of c using Bomb Data (III.F.) section, label as E.
- 6. Construct line DE, determine intersection of DE with 1000 cK_D scale. Note that units here are ft^2/lb ; however, in most of following work, units will be $ft^2/1000$ lb. Thus the number read off here gives the value of cK_D product in units of $ft^2/1000$ lb. Label as F.
- 7. Locate altitude on far right scale, label as G.
- Construct line FG and extend to far left, read off value of 1000 p/po cKp.

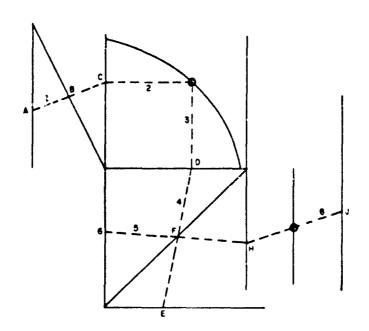


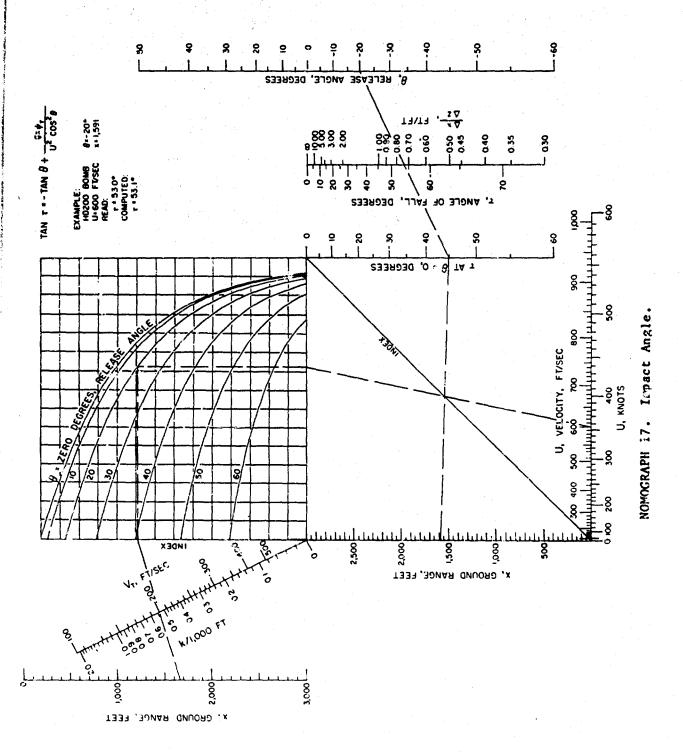


Nomograph 17. Impact Angle (Retarded sombs)

This nomograph uses eq. 51c to allow the determination of impact angles for retarded bombs.

- 1. Locate ground range on upper left scale, label as A.
- 2. Locate terminal velocity of K, label as B.
- 3. Construct line AB, label as C intersection of AB and left vertical index.
- 4. From point C, proceed horizontally toward the right until appropriate θ curve is intersected. Then proceed down to horizontal index, label as D.
- 5. Locate velocity, label as E.
- 6. Construct line DE, label as F intersection of DE and oblique index line.
- 7. Locate ground range on lower left vertical scale, label as G.
- 8. Construct line FG, label as H intersection of "7 at θ = 0 deg" scale. If θ = 0 deg, read impact angle at H.
- 9. If $\theta \neq 0$ deg, locate θ on far right scale, label as J.
- 10. Construct line HJ, read τ where HJ crosses scale.

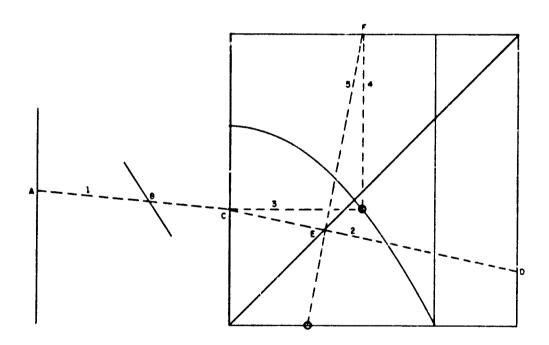


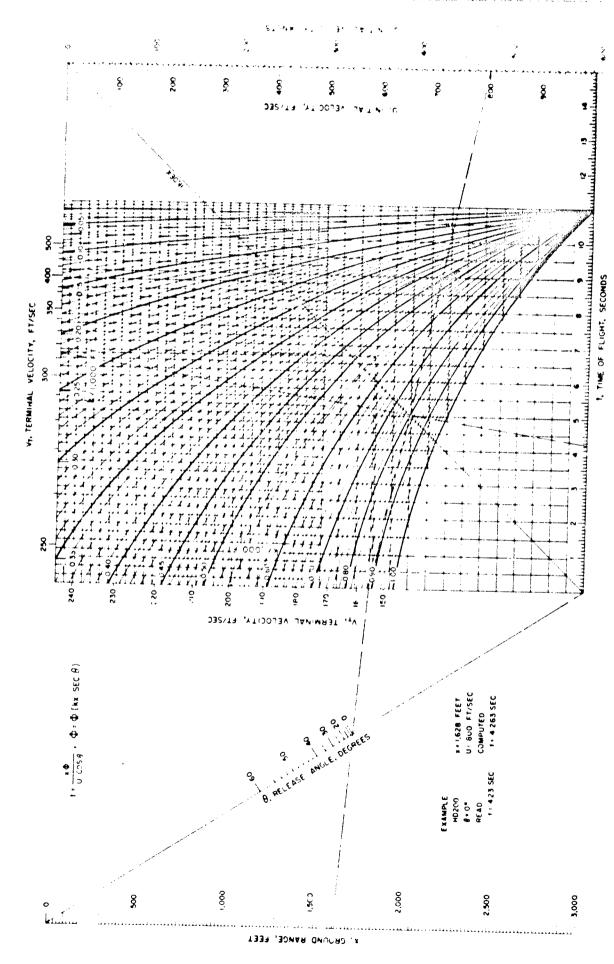


Nomograph 18. Time of Flight or Ground Range (Retarded Bombs)

This nomograph uses eq. 52.

- 1. Locate ground range on left scale, label as A.
- 2. Locate θ on oblique scale, label as B.
- Construct line AB; label as C intersection of AB with vertical "v_t, terminal velocity" scale.
- 4. Locate initial velocity on right scale and label as D.
- 5. Construct line CD; label as E intersection of CD with oblique index line.
- 6. From point C, proceed horizontally until appropriate terminal velocity curve is intersected, then proceed vertically to upper horizontal scale; label point on horizontal scale as F.
- 7. Construct line EF; time of flight given by intersection of EF with lower horizontal scale.



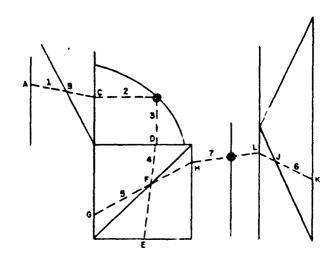


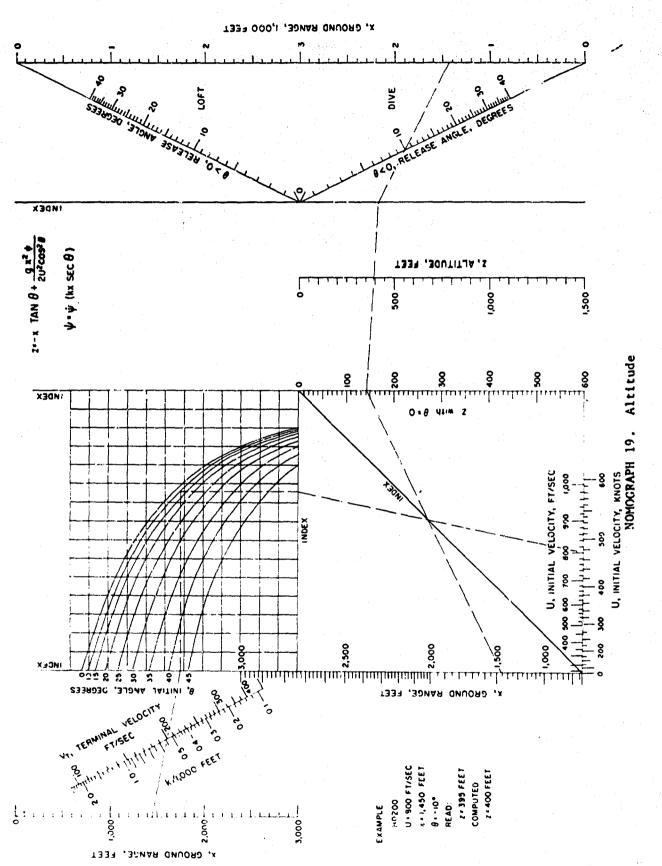
NOWOCRAPH is. Time of Flight of Ground Range.

Nomograph 19. Altitude (Retarded Bombs)

This nomograph uses eq. 51a. It should be noted that a small change in ground range can cause a large change in altitude. This can be verified by reference to the bomb tables, and may be understood by recalling that for the retarded weapons, the X-component of the velocity is damped out rapidly. Thus the velocity vector of the bomb is directed almost perpendicular to the earth after a certain flight time.

- 1. Locate desired ground range on upper left scale, label as A.
- 2. Locate terminal velocity on upper oblique scale, label as B.
- 3. Construct line AB, label as C intersection of AB with left index line.
- 4. From point C, follow horizontal over to appropriate θ curve, then down a vertical line until horizontal index line is intersected. Label intersection as D.
- 5. Locate initial velocity on lower scale, label as E.
- 6. Construct line DE, label as F intersection of DE and oblique index line.
- 7. Locate desired ground range on lower left scale, label as G.
- 8. Construct line FG, label intersection of FG and "Z, with θ = 0 deg" scale as H. If θ = 0 deg, point H gives value of Z.
- 9. If $\theta \neq 0$ deg, locate correct value of θ on two oblique scales to right of graph. Label as point J.
- 10. Locate ground range on appropriate portion of extreme right scale. If $\theta > 0$, use upper portion; if $\theta < 0$, use lower portion. Label as K.
- 11. Construct line JK, label as L intersection of JK and right index line.
- 12. Construct line HL, read altitude where HL crosses scale.

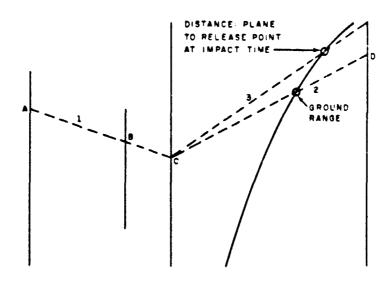


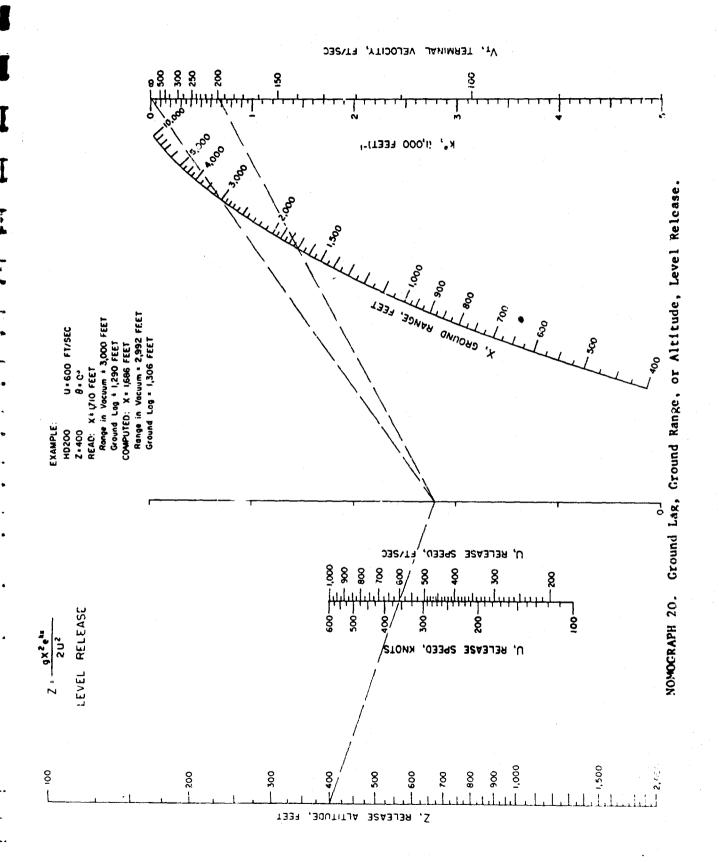


Nomograph 20. Ground Lag, Ground Range, or Altitude, Level Release (Retarded Bombs)

This nomograph uses a variation of eq. 51a for level release conditions. With this nomograph, it is possible to determine the ground lag, ground range, and given altitude. The nomograph may also be used to calculate altitude, given ground range, but this suffers from the instability pointed out in nomograph 19.

- 1. Locate altitude, label as A.
- 2. Locate velocity, label as B.
- 3. Construct line AB, label as C the intersection of AB and index line.
- 4. Locate terminal velocity (or k*), label as D. (k* is chosen to give a best fit in writing $\psi = \exp k*X \sec \theta$).
- 5. Construct line CD; ground range is given by intersection of CD with X-line.
- 6. Construct line from point C to point k* = 0 deg (or infinite terminal velocity). Note intersection of this line with X-line. This number given bomb range in a vacuum.
- 7. Ground lag is given by difference of answers in steps 5 and 6.

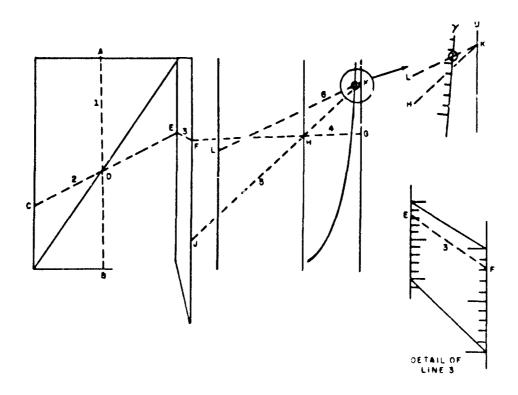


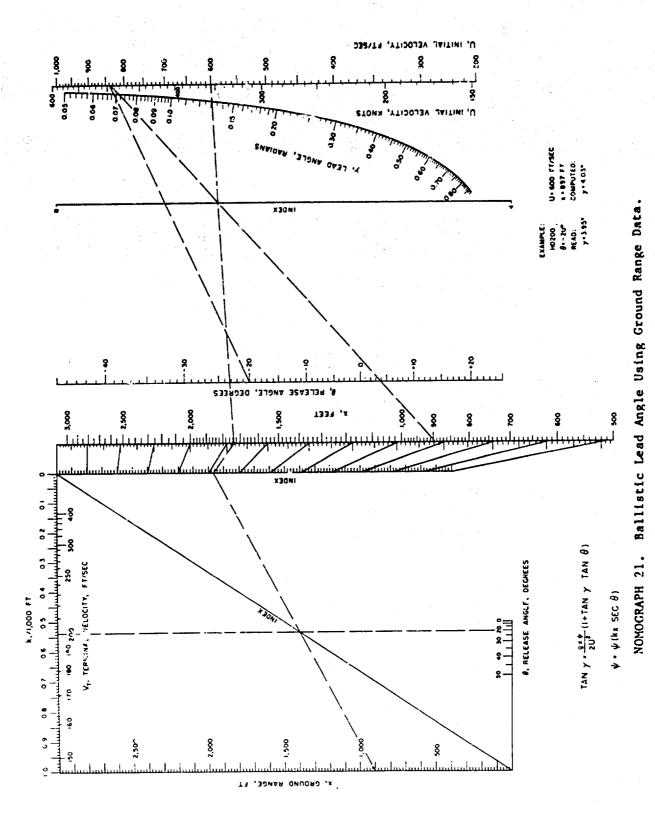


Nomograph 21. Ballistic Lead Angle Using Ground Range Data (Retarded Bombs)

This nomograph uses eq. 54b.

- 1. Locate terminal velocity on upper horizontal scale, label as A.
- 2. Locate θ on lower scale, label as B,
- 3. Locate ground range on left vertical scale, label as C.
- 4. Construct line AB, label as D intersection of AB and index line.
- 5. Construct line CD, label as E intersection of CD with center index line.
- 6. Note that right side of center index line is divided into groups of ten subdivisions, as is left side of center "X-feet" scale. If point E is a certain number of subdivisions below a main dividing line, locate the point on the left side of X-feet scale which is an equal number of subdivisions below the same main dividing line. Label as F.
- 7. Locate U on far right scale, label as G.
- 8. Construct line FG, label as H intersection of FG and right index line.
- 9. Locate ground range on X-feet scale in center, label as J.
- 10. Construct line JH, label as K intersection of JH with U-scale.
- 11. Locate θ on center vertical scale, observe sign of θ , label as L.
- 12. Construct line KL, read γ where KL intersects γ -scale.





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Nomograph 22. Change in Ground Range Due to Small Change in Angle of Release About Level Release. (Retarded Bombs)

This nomograph solves the relation

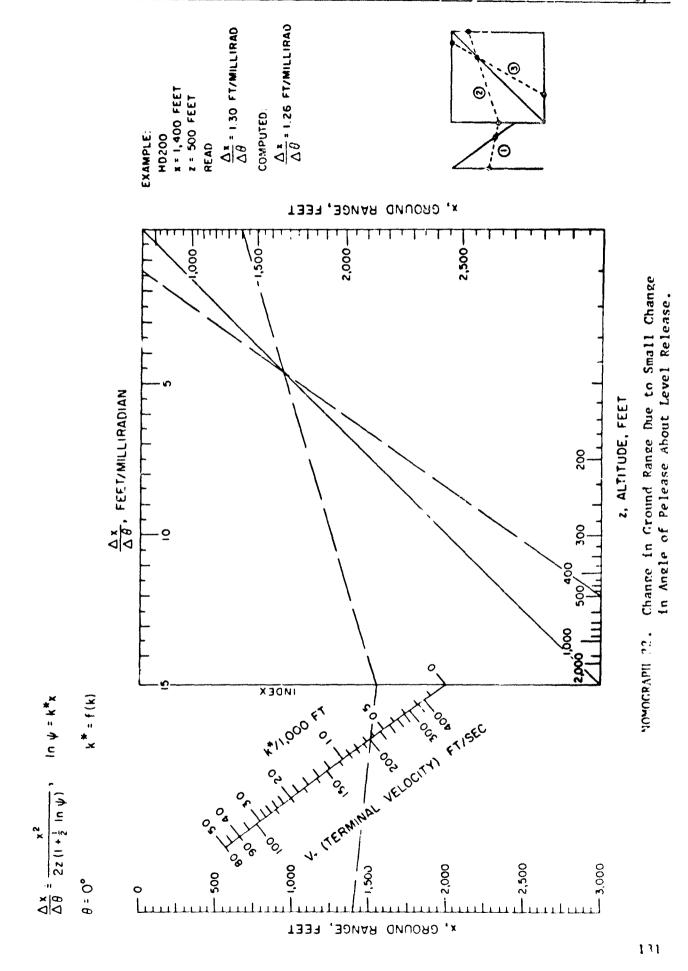
$$\frac{\Delta X}{\Delta \theta} = \frac{\chi^2}{2Z(1 + 1/2 \ln \psi)} , \quad \ell_{n\psi} = k*X , \theta = 0^{\circ}$$

$$k* = f(k) , \quad Z = constant$$

giving the ratio of the change in ground range, ΔX_{\star} due to a small deviation of release angle, $\Delta \theta_{\star}$ about level release.

Use:

- 1. The value of terminal velocity $\mathbf{V}_{\mathbf{T}}$, if not known, can be obtained from Nomograph 16.
- 2. With $V_{\underline{\tau}}$ or k^* , X, and Z known, the solution steps are as indicated by the diagram in the nomograph.



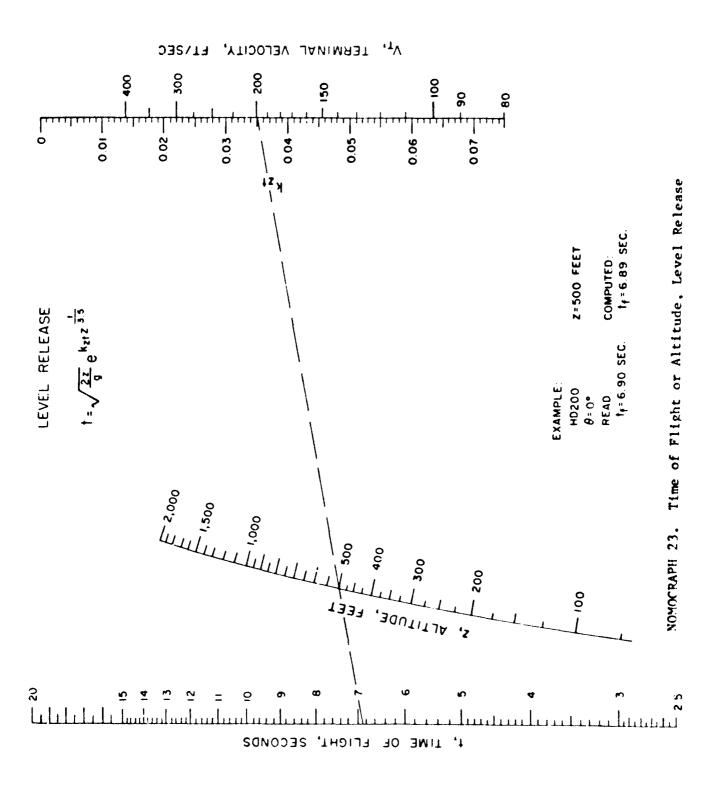
Nomograph 23. Time of Flight or Altitude, Level Release. (Retarded Bombs)

This nomograph solves the relation

elves the relation
$$k_{Zt}^{21/3.5}$$

$$t = \sqrt{\frac{27}{8}} \quad e$$

Given $V_{\overline{T}}$ and Z, t may be found, or, given $V_{\overline{T}}$ and t, Z may be found. $V_{\overline{T}}$ may be obtained from Nomograph 16.



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From: Commander, U. S. Naval Ordnance Test Station
To: Distribution of NOTS Technical Publication 3902

Subj: NOTS TP 3902, Ballistic Handbook, dated July 1965; transmittal of errata sheet for

Encl: (1) Errata sheet dated 17 November 1965 for subject report

1. It is requested that the corrections described on the enclosed errata sheet be incorporated in NOTS TP 3902.

C. E. VAN HAGAN By Direction

NOTS TP 3902

ERRATA

Title page:

Change the publishing date of August 1965 to read July

1965

Abstract cards:

Change the publishing date of August 1965 (3rd line)

to read, July 1965.